A STOCHASTIC MANAGEMENT MODEL FOR THE OPERATION OF A STREAM-AQUIFER SYSTEM

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I dedicate this work to my parents, Lic. Luciano Z. Flores and Manuela W. de Z. Flores, to my wife, Olga L. de Z. Flores and daughter Lucia Z. Flores L. as well as to the other members of my family.

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ABSTRACT

The objective of this study is to develop and evaluate a simple management technique through which the cost of conjunctive operation of surface water and groundwater resources can be minimized under the effect of uncertainty.

A lumped parameter model represents the physics of the system and a linear outflow equation simulates the stream-aquifer flow. A subsurface outflow constant related to the response time of the aquifer proves to be an important concept in the simulation process. Furthermore, a drawdown correction is developed to compute the drawdown at wells.

In the developing of the management model, dynamics in the operation of the system is obtained by using linear decision rules. The nonlinear optimization problem (pumping cost dependent on the drawdown and the pumping volume) is solved by an iterative procedure which uses a standard linear programming package.

To study the effect of randomness in the system, uncertainties in the water demand, natural inputs and the physical properties of the system are considered. A stochastic differential equation governs the system and some of the statistics are obtained via spectral analysis. In addition, a conditional probability approach is followed to account for a random subsurface outflow constant. Chance constraints are introduced to include probabilities of satisfaction of constraints.

comparative test with a previous study using a distributed parameter model is carried out; good agreement is obtained. An application to a basin in northwestern Mexico shows the capability of the proposed model in regional management problems involving hundreds of wells and large surface water facilities. A sensitivity analysis in the latter application shows a larger increase in the operational cost due to uncertainty in the water demand than to uncertainty in the aquifer parameters.

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LIST OF SYMBOLS

```
subsurface outflow constant (1/T)
a
           thickness of a restrictive layer (L)
đ
          75 percentile of the water demand (L^3)
a(0.75)
          mean water table in the aquifer (L)
h
          mean water level at the wells (L)
h
           initial water level
h
           design period (T)
n
           dimensionless pressure
p_{D}
           stream-aquifer discharge per unit aquifer area
q
           (L/T)
           nominal interest rate
r
           average well radius (L)
r_w
           75 percentile of the streamflow (L^3)
r(0.75)
ន
           average drawdown (L)
           drawdown at the wells (L)
s<sub>w</sub>
           āimensionless time
           response time of the system (L)
t_h
           frequency (radians/T)
W
           minimum dam storage fraction
\mathbf{w}_{\mathbf{m}}
           initial dam storage fraction
Wo
           fictitious net input to the system (L/T)
У
           net inflow to the system (L/T)
y_{R}
           aquifer area (L2)
A
           sine Fourier coefficient
\mathbf{A}_{\mathbf{m}}
           average influence area of a well (L2)
```

```
leakage factor (L)
В
        unit cost of pumping ($/L4)
\mathbf{c}_{\mathbf{p}}
        unit cost of spreading ($/L3)
C_{\mathrm{R}}
        unit cost of surface water (\$/L^{5})
CS
        unit cost of water returned to the stream (\$/L^3)
C,,
        consumptive use (L^3)
CU
         coefficient of variation
C
        demand of water (L^2)
D
         drawdown correction (L)
DC
         evapotranspiration (L3)
ET
         gamma cumulative distribution
F(x)
         dam freeboard (L3)
F1
         mean stream stage (L)
H
         average initial lift (L)
HL
        hydraulic conductivity (L/T)
K
         downstream flow (L^3/T)
K1
         hydraulic conductivity of a restrictive layer (L/T)
K
         autocovariance of
K_{\mathbf{v}}
         characteristic length (L)
L
         design period (T)
N
         recharge from precipitation (L3)
N_{r}
^{\mathrm{N}}s
         seasons per year
         objective function ($)
OF
         precipitation (L3)
P
P'
         percent error in the discounted expected cost in
         relation to the deterministic case
         average instantaneous pumping (L^3/T)
Q
```

```
Q<sup>¹</sup>
          capacity of water facilities (L3)
          conveyance loss (L3)
Q_{C}
          subsurface inflow (L3)
Qį
          water release from the dam (L^3)
Qou
          quantity of water pumped from the aquifer (L3)
Q_{\mathbf{p}}
          amount of water recharged to the aquifer (L<sup>3</sup>)
\mathtt{Q}_{\mathrm{R}}
          irrigation return flow (L3)
Q_{ret}
          surface drainage (L)
Q_{RS}
          stream-aquifer discharge (L^3/T)
Q_{S}
          quantity of water diverted from the stream (L3)
Q_{\mathrm{SD}}
          streamflow (L^3/T)
\mathbf{Q}_{\mathbf{ST}}
          amount of water returned to the stream (L^3)
Q_{11}
          radial dimension (L)
Ro,Ro
S
          storage coefficient
S
          dam storage (L3)
          spectral density function of
S_{\mathbf{ff}}
          transmissivity (L^2/T)
\mathbf{T}
          volume (L<sup>3</sup>)
V
          number of wells
MM
          ground surface level (L)
\mathbf{Z}
Z(w)
          random process with orthogonal increments
Z*(w)
          complex conjugate of Z(w)
\alpha_{s}
          hydraulic diffusivity (L^2/T)
\alpha_1
          fraction of precipitation that actually recharges
          the aquifer
\alpha_1
          fraction of developed water for return to the stream
\alpha_2
          fraction of water applied that infiltrates
```

```
fraction of developed water for spreading
\alpha_2
          fraction of water infiltrated that actually
04
          recharges the aquifer
          dimensionless constant, shape of the gamma distribution
          fraction of precipitation that helps to satisfy
          the demand
          dam operation decision variable (L3)
\mathcal{J}_{P}
          pumping decision variable
          artificial recharge decision variable
          size of the dam (L^3)
\mathfrak{J}_{s}
          surface water decision variable
          R_0 / R_2
8 (u)
          Dirac delta function
 \epsilon
          natural recharge (L/T)
 θ
          angle (radians)
λ
          probability level
\mu
          expected value
          autocorrelation function
          cross correlation function of head and pumping
          standard deviation
          variance
T
          lag time (T)
χ
          chi-square distribution
Δh
          aquifer head difference (L)
Δt
```

time increment (T)

CHAPTER 1 INTRODUCTION

1.1 Background

There is urgent need in many areas of the world to develop or allocate water resources in an optimal manner.

Aquifers important reservoirs provided by nature and able to store and convey water, and to improve its quality often are not used properly by planners; instead, emphasis is given to the development of surface water resources by constructing large reservoirs and ignoring the dynamic connection between stream and aquifer. Management of the conjunctive use of groundwater and surface water is an amenable solution to the problem.

In recent years, the use of distributed models in groundwater hydrology has been widespread. The trend has been favored by the development of numerical techniques and electronic computers. Regardless of field information available, the trend has been biased toward more elegant and detailed techniques.

With the previous ideas in mind the present study was oriented toward developing simple models capable of simulating the behavior of an interconnected stream-aquifer system and managing it in an economically optimal way. There was also interest in the study of the effects of uncertainties induced by nature and man on the operation of the system.

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1.2 Previous Work

Optimal management of the conjunctive use of surface water and groundwater is a complex problem widely discussed in the literature but not yet exhausted.

Table 1.1 presents a review of the literature on optimal management of the conjunctive use of surface water (SW) and groundwater (GW); it also lists papers related to the research subject in terms of concepts and techniques.

Dynamic Programming is a widely used optimization technique (see Table 1.1). It is favored mainly because of the dynamic characteristics of the management problem. Therefore, it is extensively used for scheduling purposes. Frobabilities of events can easily be included in its recursive equation (Buras, 1963; Saleem and Jacob, 1971) which is based on the optimality principle (Bellman, 1957, p.83). In general, a computer program has to be written for solving a specific problem. See Aron (1969) for advantages and disadvantages of the technique.

Linear Programming has fewer advantages than dynamic programming mainly because of nonlinear pumping costs and the dynamics of the system; see Table 1.1.

A significant contributor to a better understanding of the economics of groundwater resources has been O. Burt. A sequence of his papers (Table 1.1) discusses intensively the problem of optimal water allocation where random streamflows and conditional probabilities for storages have been included. Simple decision rules were developed and Burt (1970) worked

TABLE 1.1 Review of Literature Relating to Management of Conjunctive Use of Groundwater and Surface Water

Renark	variable pumping costs	a functional equation is obtained to derive approx-	variable pumping cost; detail field data computations	the variance of the net output is considered	an application is given; constant pumping cost	a linear decision rule is obtained	a linear decision rule is given	the aquifer outflow is linear; variable pumping	an optical mining yield volume is found; variable pumping cost
Randomness	random streamflow	deterministic	random streamflow and conditional probabil-ity for storages	random recharge	deterministic	random recharge	random recharge	random recharge	deterministic
Physical Model	continuity equation	continulty equation	continuity equation	continuity equation	continuity equation	continuity equation	continulty equation	lumped line- ar outflow model	continuity equation
Type of	*D- *N	Mo	MO-MS	GW.	No-MS	פא	MO	МĐ	פא
Optimization Technique	dynamic programming	dynamic programming	dynamic programming	dynamic programming	parametric linear programming	marginal analysis	marginal analysis	dynamic programming	marginal analysis
Objective	optimal planning, design and operation of the sys-	optinal allocation of a single resource	optimal management of groundwater and surface water	develop a sequential decision model	optimum use of ground- water and surface water	a simple dynamic model for allocation of ground- water	tenporal allocation of groundwater under quad- ratic criterion functions	optimal operation of a groundwater system	optimal ground-water mining
Reference	Buras (1963)	Burt (1964a)	Burt (1964b)	Burt (1966)	Dracup (1966)	Burt (1967a)	Burt (1967b)	Bear and Levin (1967)	Domenico etsals (1962)

TABLE 1.1 (Continued)

Renark	discussion of other optimization techniques; variable punging cost	use of a linear decision rule; use of chance constraints	constant pumping cost; the physical model is tied to the management model, through the	the stream depletion is optimized; only 3 cells	constant pumping cost for a head range	part of the problem is solved by linear programming	the decision rules are in- terpreted but application is not given; the aquifer is considered to be closed to outside recharge	optimiz, for in time and space is performed
Randomness	random atreamilow	random streamflow	deterministic	deterministic	random streamilow and natural recharge	deterministic	random streamflow	random streamllow and natural recharge
Physical Model	continuity equation	continulty equation	distributed model	distributed model	continuity equation	distributed model	continuity equation	continuity equation
Type of System	SW-GW	N.S.	SW-GW	NO-NS	M9-AS	M.S	NS-GW	NO-MS
Optimization Technique	dynamic programming	linear programming	linear programming	linear programming	linear programming	simmulation	marginal analysis and lagrangian multiplier	dynamic programming
Objective	optimization of a complex eystem with subsystem preoptimization	optimal design and operation of a dam	optimal operation for conjunctive use of ground- water and surface water	optimal conjunctive use of water	optinal conjunctive use of water	optimization of temporal allocation of groundwater	water resource management in arid regions	optimal utilization of several leaky aquifers and surface water
Reference	Aron (1969) and Aron and Scott (1971)	Rovelle et.al.	Longenbaugh (1970)	Taylor (1970)	M111fgan (1970)	Eredenoeft and Young (1970)	Cunifuga and Wincellan (1970)	Saleem and Jacob (1971)

TABLE 1.1 (Continued)

Renark	lag 3 linear regression models of streamflow were used; use of chance constraints and a zero order decision rule	no natural recharde; a sequential linear pro- gramming approach is followed to solve the problem; constant pumping cost	emphasis on economic aspects	the effect of each well is considered in the pumping cost; variable pumping cost	separable programming techniques are used in nonlinear functions	a separable procraming procedure was used to manage a quadratic pumping cost; a sensitivity analysis was performed to study the system performance to chinges in economical and hydrological factors
Randomness	random streamflow	deterministic	deterministic	deterministic	deterministic	deterministic
Physical Model	continuity equation	distributed model	continuity equation	distributed model	ı	distributed model
Type of	no-ns	NO-NS	æ	A	ŧ	M
Optimization Technique	linear programming	simulation	lagrango multiplier and marginal analysis	quadratic programming	mixed-integer programaing	mixed-integer programming
Objective	optimal planning of con- junctive use of surface water and groundwater	optimal conjunctive use of groundwater and surface water	optimal economic use of an aquifer under several conditions	coupling of a distributed physical model to a management model	developing of a water resources planning model to design a data collection network	planning and operation of a groundwater bystem
Reference	Nieswand and Granstrom (1571)	Young and Erecenceft (1972)	Brown and Deacon (1972)	Radcock III (1972a)	Roody and Raddock III (1972)	Maddock III (1972b)

TABLE 1.1 (Continued)

				_
Renark	there is not natural re- charge; the effect of eco- nomics, hydrologic, and physical factors on the management is studied	the demand persistence is included in the problem	the overall regional prob- lem is decomposed to two levels; variable pumping cost; an example is given; a penalty function method is used to solve the first level	three examples are given; an analytical procedure to compute Well drawdown for a regular boundary geometry is given
Randonness	distributed deterministic model	distributed random streamflow and model	distributed deterministic model	distributed deterministic model
Physical Model	distributed model	distributed model	distributed model	distributed model
Type of System	M 0	No-NS	NONS	SW-CW.
Optimization Technique	quadratic progremming	quadratic programming	conjugate gradient method	linear programming
Objective	planning and operation of a Eround-water system	optinal operation of a stream-aquifer system under random demands	multilevel optimization for conjunctive use of groundwater and Burface Water	conjunctive surface ground-water management
Reference	Keddock III (1973)	Maddock III (1974)	In and Haimes (1974)	Morey-Seytoux (1975)

out a situation in which institutional constraints were important.

Few cases with variable pumping cost, dependent on the well drawdown, are found in the literature (Buras, 1963; Aron, 1969; Maddock, 1972a; Yu and Haimes, 1974).

A linear decision rule in connection with chance constraints was used by Revelle et.al. (1969) in the optimal design and operation of a surface reservoir. Much controversy arose concerning the use of the linear decision rule (see e.g., Lockus, 1970; Eisel, 1970; Kirby et.a., 1970; Nayak and Arora, 1970). A zero decision rule was used by Nieswand and Granston (1971) to find the deterministic equivalent of the chance constraint in the management of the conjunctive use of surface water and groundwater.

Maddock (1974) emphasizes the stochastic nature of the problem and deals with a stochastic process represented by its mean, variance and autocovariance (persistence). Bear and Levin (1967) deal explicitly with a lumped model which includes a linear outflow, though the system consists of only a groundwater reservoir.

The optimal management of the conjunctive use of groundwater and surface water is a problem to which much attention has been given in the literature. However, there are only a few cases which have dealt with stochastic models, and none of these have included uncertainty in the properties of the stream-aquifer system.

The representation of physical systems by distributed

models in the management model is a recent advance. Three different couplings between the physical and management model have been noted. One includes the distributed aquifer model in the objective function and/or in the constraints of the management model (Taylor, 1970; Longenbaugh, 1970). Another considers only the distributed effect at the wells, with part of the drawdown computation done outside of the management model (Maddock, 1972; Morel Seytoux, 1975). Thirdly, the drawdown may be computed entirely outside of the management model. Young and Bredehoeft (1972) followed the latter approach; however instead of a mathematical programming technique a simulation technique was used to approach and optimum.

Despite the common use of linear reservoirs or lumped parameter models to describe surface runoff phenomena (Chow 1964, Section 14), little importance has been given to this type of model in groundwater hydrology. Kraijenhoff Van de Leur (1958), Dooge (1960), Eriksson (1970), Eliasson (1971), Dowming et.a.(1974), Klemes (1974) and Gelhar and Wilson (1974) deal with lumped model applications to groundwater hydrology.

1.3 Purpose and Scope of this Study

The main purpose of this research is to develop simple and reliable models which can be used to manage a regional system. The physical prototype under consideration is composed of a stream which is hydraulically connected to an aquifer; uncertainties exist in its properties and inputs.

The principal objectives of the study are:

- 1. Development of a simple model capable of representing the physics of a stream-aquifer system, simulating the head in the aquifer and at the wells, and being naturally connected to a management model.
- 2. Inclusion of uncertainties into the operation of the system.
- 3. Testing of the developed models against suitable work obtained from the literature and application to a real example.

Scope of the Study

A lumped model formed by an aquifer water balance and a linear outflow term represents the stream-aquifer system. The subsurface outflow constant and the response time are important concepts in the understanding and modeling of the system. The mean water levels of the aquifer are computed by a convolution integral. To obtain an average head at pumping wells, a drawdown correction is included in the physical model. A link between the physical and the management models was obtained through the mean head of the aquifer. Because of the nature of this connection it is possible to solve a nonlinear optimization problem with an iterative procedure that uses a linear programming package.

When randomness is included in the system, a stochastic differential equation represents the physical model, and the principal statistics of the head are obtained. The uncer-

tainty in the head is described by its standard deviation. By analysis of conditional probability, the uncertainty in the outflow constant is included in the problem. The cross correlation function between head and pumping, was found via spectral analysis. In the stochastic representation of the management model, the expected value of the objective function was used as an economic indicator; uncertainties in the demand of water and future availability of water facilities were included through chance constraints.

To examine the reliability of the proposed models, the results are compared with results obtained from a management model connected to a distributed type of model (Maddock, 1974). The sensitivity of the system to uncertainties is illustrated by an application of the models to a real basin in northwestern Mexico.

CHAPTER 2 DEVELOPMENT OF THE PHYSICAL MODEL

2.1 Introduction

In recent years many authors have used distributed models with the purpose of reproducing natural systems. Some of this work can be misleading in that very detailed models are not consistent with the field information available. In groundwater hydrology limited attention has been given to lumped parameter models (Kraijenhoff Van de Leur, 1958; Dooge, 1960; Van Schilfgaarde, 1965; Eriksson, 1970; Eliasson, 1971; Gelhar and Wilson, 1974) but none used this type of model in stochastic management of groundwater systems.

A lumped parameter model consisting of an aquifer water balance and a linear stream-aquifer flow will be developed in this work. This model is defined as the physical model, since it will deal with the physics of the groundwater flow system. The stream-aquifer interaction and the mean head in the aquifer are governed by this model. The output of the physical model will serve as a link to a management model.

In general, a system can be defined as a set of interrelated objects which can respond to one or several inputs producing one or a series of outputs. Many definitions of a system exist in several disciplines. Two interesting discussions in the hydrological literature can be found in Dooge (1973, p.3) and Chow (1975, p.17). A simplified representation of nature which tries to clarify its behavior by simulation is called a model. Chorafa (1965) defines

simulation simply as a working analogy. A common practice is to use a mathematical model to simulate a complex system. A mathematical model is a set of mathematical equations used to describe a model. A proposed classification of hydrological models with reference to applications is given by Clarke (1973a, p.10; 1973b).

Two main types of models can be used to represent a hydrological system. The distributed model describes the spatial structure of a system and considers the inputs of the system as distributed in time and space. In general, a partial differential equation governs its behavior. The lumped parameter model groups inputs, and deals with a system in which temporal variation of the parameters is treated by an ordinary differential equation while spatial variation of the parameters is not considered. Black box is another name for a lumped model, because inputs and outputs can be measured, although the process which governs the system is masked, distorted or averaged. In other words no detailed description of interrelated processes is observed (Domenico, 1972, p.8).

2.2 Mathematical Representation of the Lumped Model Description of the System

The system studied in this work is formed by two interconnected subsystems, an aquifer and a stream (Figure 2.1). An aquifer is defined as a saturated and permeable bed, formation or group of formations able to yield a

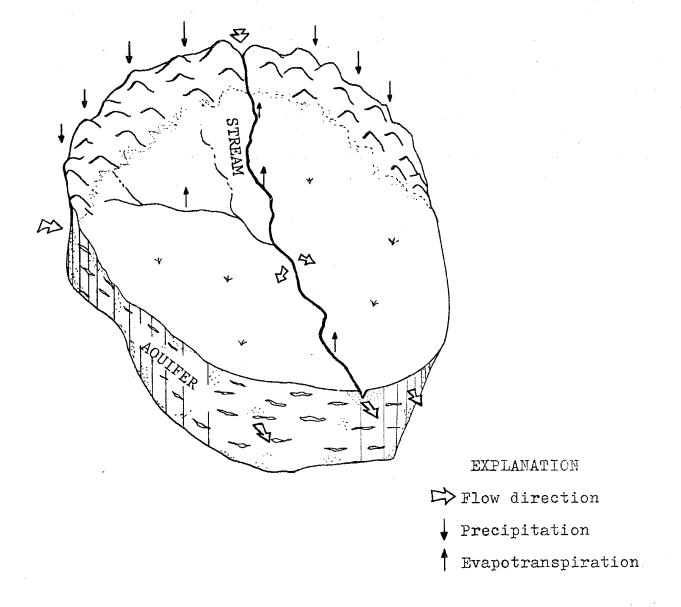


Fig. 2.1 Schematic representation of a natural stream-aquifer system.

substantial amount of water. The aquifer is unconfined or tends to be so at a regional scale. The stream can have one or several branches, is connected to the aquifer, and can be uncontrolled or controlled by a reservoir.

The system may or may not be connected to other systems. The inputs to the system are natural and artificial recharge, irrigation return flow, subsurface inflow and streamflow; the outputs from the system are pumping, subsurface outflow evapotranspiration and any downstream streamflow losses or water rights.

Development of the Lumped Model

The process that describes the behavior of the system is mass transport, governed by the law of conservation of water. The mathematical model which defines the system is an ordinary differential equation developed from the above principle and represents a water balance of the aquifer.

Amount of water that Amount of water that goes into the system - comes out of the system in the interval Δt in the interval Δt

Change of amount of
= water stored in the
aquifer in the interval Δt

$$(v_{in} - v_{out})/\Delta t = S\Delta V/\Delta t \qquad (2.1)$$

where, S is the storage coefficient (or specific yield).

A continuous representation can be found taking limits of both sides of equation 2.1

$$Q_{in} - Q_{out} = S dV/dt$$
 (2.2)

Now let

dV = Adh

and

$$y_R = (Q_{in} - Q_{out})/A$$

where y_R is the net inflow to the system, \underline{A} is the area of the aquifer, and \underline{h} is the mean water level in the aquifer. Substituting into equation 2.2 we obtain

$$S dh/dt = y_{R}$$
 (2.3)

The stream-aquifer flow may be approximated by a linear term

$$q = a (H - h)$$

where, \underline{H} is the mean water level of the stream and \underline{a} is called the subsurface outflow constant.

Introducing the above equation into (2.3) produces

$$S dh/dt + ah = y (2.4)$$

where, \underline{y} is a fictitious net input of the system with units of L/T and based on the aquifer area \underline{A} , defined by

$$y = y_R + aH$$

Equation 2.4 is an ordinary differential equation which describes the aquifer and its connection to a stream in a lumped manner.

The physical model exactly represents the natural system except for the assumption of linearity in the stream-aquifer flow.

2.3 Subsurface Outflow Constant

Stream-Aquifer Interaction

The use of linear models to represent outflows is a common practice in surface hydrology (Chow, 1964, p.14.27). However, few investigators have tried to apply these simple

models to depict subsurface flows.

In this section we make use of several elementary solutions for groundwater flow to determine the structure and magnitude of the subsurface outflow constant. Background information on the development of these elementary solutions can be found in texts on subsurface hydrology (see e.g., Bear, 1972). Though an actual system is nonlinear, the simplest most practical flow relationship between a stream and an aquifer, within the degree of accuracy required, is the linear one,

$$q = a(H - h) \tag{2.5}$$

where

- q stream-aquifer flow, L/T;
- a subsurface outflow constant, 1/T;
- H mean stream stage, L;
- h mean water table in the aquifer, L.

Development of the Subsurface Outflow Constant

The subsurface outflow constant <u>a</u> is a very useful system parameter. It accounts for stream channel characteristics such as, stream bed properties; type of flow; it also

subsurface outflow constant shows its relationship to the properties of the aquifer and the validity of the linear assumption in the stream-aquifer flow.

Effect of Linearity Assumption on the

Stream-Aquifer Flow Computation

Let us consider a stream connected to an aquifer with natural recharge \leq , and under steady flow conditions, as shown in Figure 2.2

Using the Dupuit approximation, the one dimensional flow equation is (Bear, 1972, p.376).

$$d/dx (Kh dh/dx) + \epsilon = 0$$
 (2.8)

where \underline{K} is the hydraulic conductivity of the aquifer (L/T). Integrating equation 2.8 and using the boundary condition

$$x = L$$
, $dh/dx = 0$

includes the aquifer geometry, transmissivity of the aquifer, and recharge and withdrawal distribution. This constant is related to the time that the aquifer takes to respond to an input and allows the computation of the stream-aquifer flow in a simple way.

The subsurface outflow constant, a, is defined as the stream-aquifer flow per unit aquifer area under a unit difference of mean head between the aquifer and a stream, which may be either influent or effluent.

Multiplying (2.5) by the horizontal area of the aquifer, A gives

$$Q_{s} = qA = aA(H - h)$$
 (2.6)

which may be rewritten to give

$$a = (Q_s/A)/(H - h)$$
 (2.7)

where the variables are

Q stream-aquifer discharge, L3/T;

A aquifer area, L2.

The following mathematical procedure to find the

we obtain

$$Kh \quad (dh/dx) = \varepsilon (L - x) \tag{2.9}$$

Integrating (2.9) with

$$x = 0$$
, $h = H$

we obtain

$$h^2 - H^2 = \epsilon x(2L - x)/K$$
 (2.10)

Solving for h

$$h = H(1 + \epsilon x(2L - x)/KH^2)^{\frac{1}{2}}$$

A second order approximation of the term in parentheses is given by expanding the radical

$$h - H = \epsilon x(2L-x)/2KH - \epsilon^2 x^2(2L-x)^2/8K^2H^3$$
 (2.11)

In addition,

$$\bar{h} - H = 1/L \int_0^L (h - H) dx$$
 (2.12)

where \overline{h} is the mean water table in the aquifer. Substitute (2.11) into (2.12)

$$\overline{h} - H = \epsilon L^2 (1 - \epsilon L^2 / 5TH) / 3T$$
 (2.13)

where the transmissivity of the aquifer is T = KH.

From equation 2.11, we note that the difference between the maximum water level and the stream level, Δh , is

$$\Delta h = \epsilon L^2/2T - \epsilon^2 L^4/8T^2H$$

or

$$\Delta h/H = (1 - \epsilon L^2/4TH) \epsilon L^2/2TH \qquad (2.14)$$

When the change in saturated thickness is small relative to the aquifer depth, H,(Δ h/H<<1) the term ϵ L²/2TH is also small relative to unity; under these conditions it is reasonable to neglect ϵ L²/5TH in (2.13).

Then since the flow is steady (q = ϵ),

$$q = 3T (\overline{h} - H)/L^2$$

where

$$\mathbf{a} = 3T/L^2 = \beta T/L^2 \tag{2.15}$$

Therefore, the subsurface outflow constant \underline{a} , depends on the transmissivity of the aquifer, \underline{T} , a characteristic length \underline{L} , and a dimensionless constant $\underline{\beta}$ which will be discussed subsequently.

The linear assumption in the stream-aquifer flow implies that (2.14) must be satisfied. Under steady conditions if the stream is influent or if the aquifer is subject to withdrawals as in Figure 2.3, the same analysis applies with $\epsilon < 0$ and the same subsurface outflow constant results.

Effect of Unsteady Flow on the Subsurface Outflow Constant

To examine the effect of unsteady flow on \underline{a} , the Dupuit approximation given in linearized form (T = constant)

$$\partial (T \partial h/\partial x)/\partial x + \epsilon = S \partial h/\partial t$$
 (2.16)

is used with the initial condition

$$h - H = \epsilon_0 x(2L - x)/2T$$
 if $t < 0$

$$\epsilon = 0$$
 if $t \ge 0$

and boundary conditions similar to the steady state case. The solution to (2.16) is

$$h - H = \sum_{m=1,3,5,...}^{\infty} A_m \exp(-m \pi \alpha / 2L)^2 t$$
 Sin $(m\pi x/2L)$ (2.17)

where A_{m} is the sine Fourier coefficient of h - H,

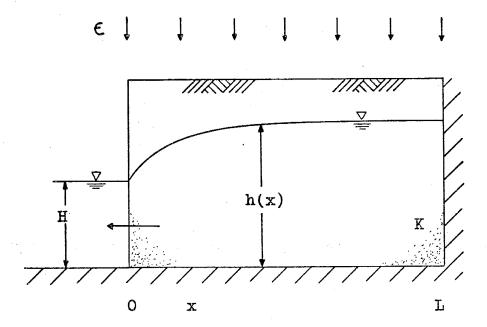


Fig. 2.2 Stream-aquifer interaction in an unconfined aquifer under stream effluent conditions

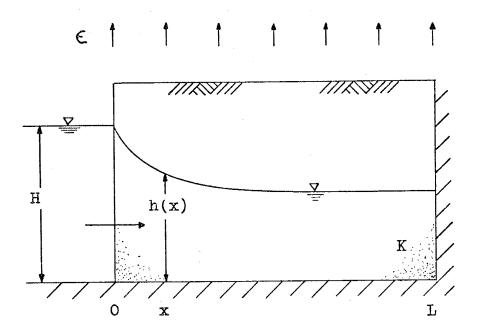


Fig. 2.3 Stream-aquifer interaction in an unconfined aquifer under stream influent conditions.

$$A_{m} = 8 \epsilon_{o} L(1 - \cos m\pi) / Tm^{3} \pi^{3}$$

Using (2.17) and following a procedure similar to the steady case, an average head of the aquifer, \underline{h} , and the unit stream-aquifer discharge, \underline{q} , can be computed. Appendix A details the development of the solution of equation 2.16 and the computation of \underline{a} . Using (2.5) a value of the subsurface outflow constant was found for unsteady flow conditions.

$$a = T/4 (\pi^2/L^2) = \beta T/L^2$$

where

$$\beta = \pi^2/4$$

The above examples of unsteady and steady flow conditions have shown us that the structure of the subsurface outflow constant remains the same except for the numerical value of the dimensionless constant, . Eraijenhoff Van de Leur (1958, p. B92) states that a constant ratio between the storage in the aquifer and outflow rate can be approximated in a period of depletion. His conclusion is similar to our introduction of the subsurface outflow constant.

If the water table decline is large the linearity of equation 2.5, may produce excessively large flows from stream to aquifer. In actuality, the flow approaches an asymptotic

limit (see, Figure 2.4) due to two restrictions: (1) the rate of infiltration into the stream bed is limited as the water table is lowered below the stream bed and unsaturated flow conditions develop and (2) the outflow relation (equation 2.13) becomes nonlinear when the change in water level across the aquifer is of the same order as the aquifer thickness.

Therefore, the stream-aquifer flow is not only controlled by differences in head and aquifer properties but also by the streamflow and the physical characteristics of the stream bed.

Effect of Stream Clogging on the Subsurface Outflow Constant

Several situations affecting the stream-aquifer flow will be presented to give an idea of the range and type of variables that affect the dimensionless constant.

The effect of stream bed clogging on the stream-aquifer flow is shown first.

Applying Darcy's law to the aquifer flow (Figure 2.5), the head difference across the semipermeable layer, Δ h, is approximated by

$$\Delta h = h_o - H \cong \epsilon Ld/HK_s \qquad (2.18)$$

where, \underline{d} is the thickness of the restrictive layer and K_s its hydraulic conductivity (see Figure 2.5).

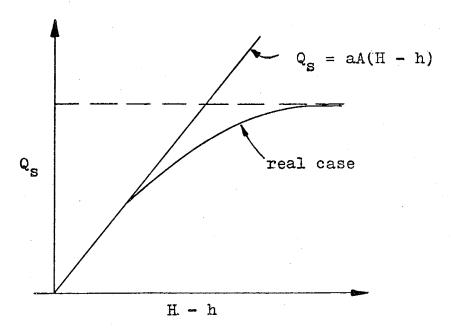


Fig. 2.4 Stream-aquifer flow as a function of the stream-aquifer head difference.

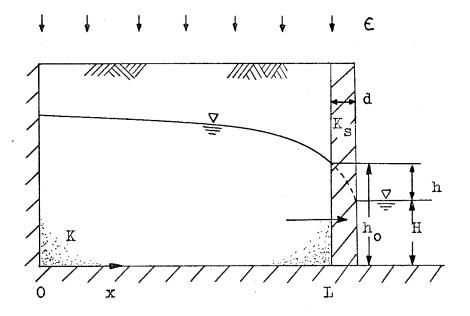


Fig. 2.5 Stream-aquifer flow, with the stream clogged by a semipermeable layer of thickness \underline{d} and hydraulic conductivity K_s .

If steady state is considered or $q = \epsilon$, we have

$$q = a_c (h - H)$$
 (2.19)

where a_c is the subsurface outflow constant corrected for the clogging layer. Also

$$q = a(h - h_0) \tag{2.20}$$

In Appendix B we show that

$$a_c = a/(1 + 3B^2/HL)$$
 (2.21)

where \underline{a} , is the subsurface outflow constant for steady state conditions, and \underline{B} is defined as the leakage factor (Davis and De Wiest, 1967, p.225).

$$B = (T/(K_s/d))^{\frac{1}{2}}$$

As expected, a_c is smaller than \underline{a} by a factor which depends on the square of the leakage factor. A larger \underline{B} means smaller leakage, therefore a smaller a_c , and vice versa. Thus the stream channel characteristics can have a significant effect on the subsurface outflow constant.

Effect of Converging Aquifer Flow on the Subsurface Outflow Constant

Two extreme cases will be considered: converging and

diverging flow under steady state. The flow is radial and converges toward the system outlet, the stream, as shown in Figure 2.6.

Equation 2.16 for steady state in cylindrical coordinates is

$$1/r (d (Tr dh/dr)/dr) = -\epsilon$$
 (2.22)

where <u>T</u> is again taken as a constant.

The boundary conditions are

$$r = R_2$$
, $dh/dr = 0$.

and

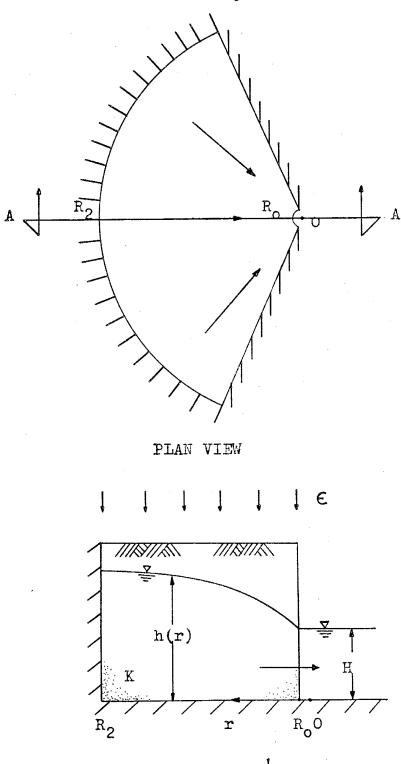
$$r = R_0$$
, $h = H$

The solution of (2.22) is

T
$$(h - H) = (R_0^2 - r^2) \epsilon / 4 + (\ln(r/R_0)) \epsilon R_2^2 / 2$$
 (2.23)

The mean water level in the aquifer is

$$\overline{h} - H = 1/(R_2^2 - R_0^2) \pi \int_{R_0}^{R_2} (h - H) 2 \pi r dr$$
 (2.24)



CROSS SECTION A-A

Fig. 2.6 Converging aquifer-stream type of flow.

$$\bar{h} - H = ((1 + 2 \delta) \ln \delta^{-1}/2 - 3(1 + 2 \delta)/8) \epsilon L^2/T$$
(2.25)

Using (2.5) and (2.25), we have

$$a = (1/(1 + 2 \delta) \cdot (\ln \delta^{-1}/2 - 3/8))T/L^2$$
 (2.26)

Additional information concerning the development of the above equations is available in Appendix ${\tt C}$.

To give an idea of the magnitude of $oldsymbol{eta}$ for this type of flow, assume that

$$\delta = R_0/R_2 = 0.1$$

and substitute into equation 2.26 to obtain

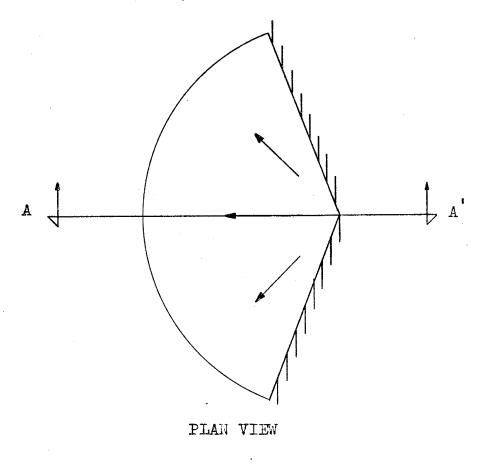
$$a = 1.07 \text{ T/L}^2$$

and hence

$$\beta = 1.07$$

Effect of Diverging Aquifer Flow on the Subsurface Outflow Constant

To simulate the other extreme flow case, diverging flow in an unconfined aquifer is considered. Due to the aquifer shape, the flow is forced radially to a constant head boundary as shown in Figure 2.7.



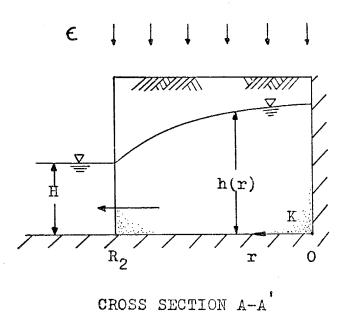


Fig. 2.7 Diverging aquifer-stream type of flow.

Using equation 2.22 plus the two boundary conditions

$$r = 0$$
 , $dh/dr = 0$

$$r = R_2$$
 , $h = H$

we obtain the solution

$$T(h - H) = \epsilon (R_2^2 - r^2)/4$$
 (2.27)

Computing the average water level as

$$\bar{h} - H = \int_{0}^{R_2} 2\pi h r dr / \pi R_2^2$$
 (2.28)

and substituting equation 2.27 into (2.28), we have

$$\overline{h} - H = \epsilon R_2^2 / 8T$$

Making use of equation 2.5

$$a = 8T/L^2 \tag{2.29}$$

The constant \underline{a} is identical for a semicircular or a wedge shaped aquifer with the same natural recharge $\underline{\epsilon}$.

Therefore, a reasonable range for β as a function of aquifer geometry (converging and diverging flow) is 1 to 8. This range of variation on β demonstrates the impor-

tance of a three dimensional flow on the computation of a.

Effect of Recharge Distribution on the Subsurface Outflow Constant

Consider steady flow in a homogeneous aquifer in which the recharge occurs at the upper reaches of a basin (see Figure 2.8). For the computation, the aquifer is divided into two regions. Mathematically, this problem can be posed as

$$\epsilon_1 \propto L = \epsilon L$$

where ϵ_1 is the actual rate of recharge and $\underline{\epsilon}$ is the rate of recharge applied over the entire aquifer.

The differential equation applicable to region 1 is

$$d/dx (T dh_1/dx) = -\epsilon_1$$
 (2.30)

where \underline{T} is a constant. The boundary conditions are

$$dh_1/dx = 0$$
 , $x = 0$

$$h = h_1$$
 , $x = \alpha_L$

For region 2, the differential equation is

$$d/dx (T dh2/dx) = 0 (2.31)$$

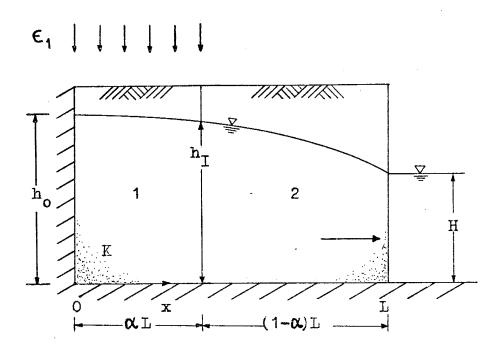


Fig. 2.8 Stream-aquifer interaction with recharge applied on a portion of the basin.

and the boundary conditions are

$$T dh_2/dx = T dh_1/dx$$
 , $x = x L$

$$h = H$$
, $x = L$

The solutions of (2.30) and (2.31) are

$$h_1 = H + (2\alpha L^2 (1 - \alpha) + \alpha^2 L^2 - x^2) \epsilon_1/2T$$
(2.32)

and

$$h_2 = H + \alpha \epsilon_1 L(L - x)/T \qquad (2.33)$$

The mean water level is computed by

$$\bar{h} = 1/L \left(\int_{0}^{\alpha_L} h_1 \, dx + \int_{\alpha_L}^{L} h_2 \, dx \right)$$
 (2.34)

Therefore,

$$\bar{h} - H = (3 \alpha/2 - \alpha^3/2) \epsilon_1 L^2/3T$$
 (2.35)

and, since
$$\epsilon_1 = \epsilon/\alpha = q/\alpha$$
,

(2.35) becomes

$$\overline{h} - H = (3/2 - \alpha^2/2) qL^2/3T$$
 (2.36)

Using (2.5), we find the subsurface outflow constant

$$a = 6T/(3 - \alpha^2)L^2$$
 (2.37)

With equation 2.37, we compute values for the two possible extremes which might occur in nature, and hence the range of the recharge distribution effect on the subsurface outflow constant.

If $\alpha = 1$, recharge occurs over the entire aquifer and

$$a = 3T/L^2 \tag{2.38}$$

If $\alpha = 0$, recharge is concentrated on the impermeable boundary, and

$$a = 2T/L^2 \tag{2.39}$$

Equation 2.38 represents, of course, the value of <u>a</u> already computed for the steady-state case, and equation 2.39 can easily be verified by using Darcy's law, as follows:

$$\epsilon L = T(h_o - H)/L$$
; $h_o - H = \epsilon L^2/T$

Since the head distribution is linear, we may write

$$\overline{h} - H = \epsilon L^2/2T$$

and with equation 2.5, we obtain

$$a = 2T/L^2$$

which verifies (2.39).

The obvious conclusion from the above analysis is that the effect of the distribution of recharge or withdrawal is not very significant, since β ranges only from 2 to 3.

The effects of different aquifer properties in individual segments of a stream-aquifer are discussed in Appendix D. It is shown there that the system can be represented by a single linear reservoir only when \underline{a} and \underline{S} are the same in each segment.

A summary of the range of \underline{a} , for all studied possibilities is shown in Table 2.1. The $\underline{\beta}$ ranges from 1.07 to 8.

Gelhar et.al. (1974, p.94) applied spectral analysis to a Dupuit aquifer with recharge over the entire basin, and obtained values of β within the above range. Appendix E gives a mathematical justification for the use of average aquifer and stream water levels in equation 2.5.

In regions with limited field information Table 2.1 can be a helpful tool. If piezometric data exist, a more reliable selection of <u>a</u> can be made by the following procedure:

a) From a piezometric map, compute the mean water level.

TABLE 2.1 Typ	Type of Effects	ts on the Subsurface	Outflow Constant a , and	the Respective	Values of a , and β	
of Flow	Effect	t on a	Schematic Flow Picture	rd	Parameters Used to Compute a	6
	Clogging		X X X X X X X X X X X X X X X X X X X	91/1]/(1+3B/HL)	B =1.4x10 m ² H =350 m L =1.6x10 m K =10 ⁻³ K	
+ 0 0 70	Recharge Distribution	on	1 1 1 6 1 =	ģT/Lj/(3/2-0c ² /2)	0 II II II B B	3.0
	Aquifer Geometry	Converging	r Plane View	3(1–2&\n&\2–3/8)	$S = R_0 / R = C \cdot 1$	1.07
	AND THE PROPERTY OF THE PROPER	. Diverging	r Thirthe O	81/Te	and algorithms or all delications are also also as a second of the secon	8.0
Unsteady	Type of Flow	Falling Sinusoidal Water Table	T X 0	75/14L°		2.47
	,	A CAMPANIAN PROPERTY OF THE PR	\$			-

- b) Apply Darcy's law to the flow passing through the stream tubes close to the stream and calculate a mean stream-aquifer flow or estimate the stream-aquifer flow from an aquifer water balance.
- c) Calculate a mean stream bed elevation from a topographic map and use it to compute a mean stream elevation.
- d) Apply equation 2.6 and obtain the subsurface outflow constant. Note that if the wells close to the stream are shallow an error in the streamaquifer discharge can be introduced in the flow computation (b), due to the fact that the hydraulic gradients at the water table are greater than the gradients deeper in the aquifer.

The previous analysis investigates the validity of the linear outflow assumption in representing the stream-aquifer interaction. It gives a rather narrow range of variation of the subsurface outflow constant and presents a simple field procedure to obtain the latter. The subsurface outflow constant groups most of the system properties and helps to define the stream-aquifer flow in a simple way. Therefore the subsurface outflow constant is a very important parameter for defining or condensing important properties of the system. Its limitations include the effect of a deep water table in the stream-aquifer flow.

2.4 Techniques Used to Solve the Lumped Model

Analytical Solution

The first technique presented for solving the lumped model is an analytical one. The solution of equation 2.4 is

$$h(t) = h_0 \exp(-at/S) + 1/S \int_0^t y(\tau) \exp(-a(t-\tau)/S) d\tau$$
(2.40)

where h_0 is the initial condition at t = 0.

The first term on the right hand side represents the initial condition effect and the second term includes the effect of all past inputs y(7), on the system. The integral is usually called the superposition or convolution integral (Miller, 1963, p.273). The mathematical development of equation 2.40 is given in Appendix F.

Finite Difference Approach

A finite difference representation of equation 2.40 can be written as

$$(h_{i+1} - h_i) S/\Delta t + (h_{i+1} + h_i) a/2 = y_i$$
 (2.41)

Solving equation 2.41 for h_{i+1} will give

$$h_{i+1} = (y_i \Delta t/S + (1 - a \Delta t/2S) h_i)/(1 + a \Delta t/2S)$$
(2.42)

Equation 2.42 is easily programmed for an electronic computer; however, significant errors may be introduced by an improper choice of the time interval Δ t, as illustrated by the following analysis.

Define the response time $t_h = S/a$ and assume, for simplicity, that y_i is zero. The exact solution of the lumped model (see, App. F) is

$$h_{i+1} = h_i (exp(-\Delta t/t_h))$$

Using a Taylor series expansion, we obtain

$$h_{i+1} \cong h_i (1 - (\Delta t/t_h) + (\Delta t/t_h)^2/2 - (\Delta t/t_h)^3/6$$
+) (2.43)

Expanding the denominator of equation 2.42 and assuming that y_i is zero, we obtain

$$h_{i+1} \cong h_i (1 - \Delta t/2t_h) (1 - (\Delta t/2t_h) + (\Delta t/2t_h)^2$$
 $- (\Delta t/2t_h)^3 + \dots)$

or

$$h_{i+1} \cong h_i (1 - (\Delta t/t_h) + (\Delta t/t_h)^2/2 - (\Delta t/t_h)^3/4$$
+) (2.44)

The difference between equations 2.43 and 2.44 is on the order of

$$h_{exact} - h_{finite differences} = (\Delta t/t_h)^3/12$$
 (2.45)

considering the first four terms of the expansions.

Therefore, a finite difference representation of the head \underline{h} , can introduce a significant error that depends on the Δ t/(S/a) ratio. Thus it is seen that the increment time of a specific problem must be selected carefully.

For instance, a ratio $\Delta t/t_h$ of approximately 0.5 produces an error of about 1%. Since the error depends on the third power (equation 2.45), $\Delta t/t_h$ ratios greater than 1 are not recommended.

Discrete Representation

A discrete representation of the exact solution of the lumped model was preferred over the finite difference approach. Equation 2.4 is rewritten

$$S dh/dt + a (h - y_i/a) = 0$$

If y_i is constant during the time interval (i, i+1) this can be written

$$S(d/dt)(h - y_i/a) + a(h - y_i/a) = 0$$

It has the solution

$$h - y_i/a = C \exp(-at/S)$$

where \underline{C} is a constant of integration. The initial conditions are

at
$$t = 0$$
 , $h = h_i$

at
$$t = t$$
 , $h = h_{i+1}$

Therefore,

$$C = h_i - y_i/a$$

which yields

$$h_{i+1} = h_i \exp(-a\Delta t/S) + (1 - \exp(-a\Delta t/S))y_i/a$$
(2.46)

This is equivalent to (2.40) with the input $\,y_{i}\,$ a constant in a time interval $\,\Delta\,t_{i}\,$.

2.5 Response Time

The response time, t_h , of the stream-aquifer system is the time required for the water level excess over that in the stream to drop to 1/e times the original level when there is no net inflow to the aquifer (see Figure 2.9).

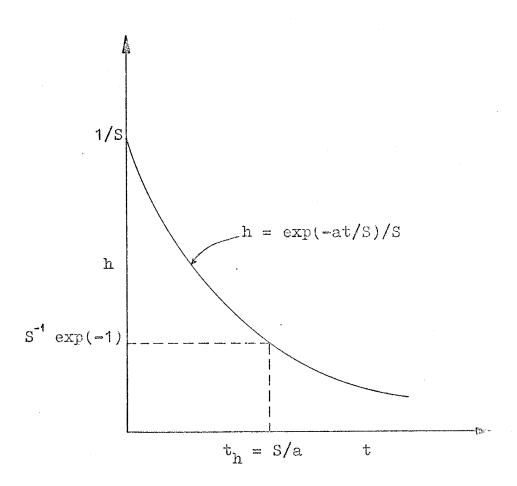


Fig. 2.9 Response time $t_{\rm h}$, as a function of the stream-aquifer unit response.

The unit response of the system (Appendix F) is

$$h = \exp(-at/S)/S$$

and

$$h_{t_h} = 1/Se$$

Therefore,

$$t_h = S/a \tag{2.47}$$

where \underline{S} is the storage coefficient and \underline{a} is the subsurface outflow constant.

The ratio of an active volume above the aquifer storage with zero outflow, Δ V , to the stream-aquifer discharge, ${\bf Q}_{\rm s}$, is another definition of response time.

$$t_h = \Delta V/Q_s$$

or

$$t_h = AS(H - h)/Q_S$$

where $Q_s = Aa(H - h)$ is the stream-aquifer discharge. Therefore,

$$t_h = S/a$$

Note that this same definition would apply when the river is influent, but in this case the volume increment is the active aquifer deficit.

Chapman (1964) mentioned the importance of the ratio of storage to flow. He gives a table of typical values and also mentions that in arid regions a value of at least fifty years, safely let us use a steady state formula to compute the flow. In an actual situation the steady state approximation is adequate if the long-term average of groundwater flow is more important than oscillations caused by non-steady fluctuations, as noted by Kraijenhoff (1954). Hence, as the response time increases it will be more appropriate to use the steady state value of the dimensionless constant Δ .

2.6 Well Drawdown Correction

As noted earlier the output of the lumped model is a mean water level in the aquifer; its use is limited to specific types of problems. Costs of pumping determined by a model of this sort would be underestimated. Therefore, in order to make our physical model capable of accounting not only for average drawdowns but for local drawdowns at the wells, a correction was developed and added to the model.

Several papers exist in the field of petroleum engineering concerning the relationship of average pressures and specific pressures in a bounded reservoir. Matthews et. al. (1954), presented a procedure using the superposition principle for finding the difference between a so-called extrapolated pressure and an average pressure for different shapes of reservoirs. Earlougher et.al. (1968) developed a simplified procedure to find the pressure distribution in a bounded square, which was used as a building block to generate flow behavior in any rectangular region. Ramey et.al. (1973) checked the results obtained by earlier authors and presented programs to solve rectangular shapes with different types of boundaries.

To develop an average drawdown correction the following assumptions are made: the flow in the aquifer is unsteady; the aquifer area influenced by a given pumping well is a square of impermeable boundaries; the aquifer is confined. Inasmuch as our model is lumped, a mean area of influence for a well was obtained by dividing the entire area of study by the number of wells. The work by Earlougher et.al. (1968) is followed closely.

First some of the variables entering in the problem are presented. A water balance of a closed square is used as the basic tool. Let

 $\bar{s} = Qt/AS$

where \overline{s} is an average drawdown, and \underline{A} is the area of the square. Rearranging and multiplying the above equation by $2\,\pi\,\text{T}$, we find

 $2\pi T \overline{s} / Q = 2\pi T t / AS$

Noting that the left hand side of this equation is an average dimensionless pressure, \overline{p}_D , and the right hand side of the equation can represent a dimensionless time based on \underline{A} , t_{DA} ; we have

$$\overline{p}_{D} = 2\pi t_{DA}$$

where

$$\overline{p}_{T} = 2\pi T \overline{s}/Q$$

and

$$t_{DA} = Tt/AS$$

A table showing the dimensionless pressure, p_D , against t_{DA} for $\sqrt{A}/r_W = 2000$ is given by Earlougher et.al. (1968). If different ratios of \sqrt{A}/r_W are found a correction must be added to the p_D values given in the table; it is

$$\ln ((\sqrt{\Lambda}/r)/2000)$$
 (2.48)

For $t_{DA} \ge 0.2$ was found that the difference in pressure $p_D - \overline{p}_D$ was almost constant and equal to 6.29, as

shown in Figure 2.10. Therefore, a simple formula is developed to represent the average drawdown at the wells and it is

$$s_w - \bar{s} = (6.29 + \ln ((\sqrt{A}/r_w)/2000))Q/2\pi T$$
 (2.49)

where Q is an average instantaneous pumping.

The average drawdown of the aquifer \overline{s} is obtained from the lumped model.

Conclusion

The use of the physical model presented in this chapter is straightforward. It was prepared with the purpose of linking it to a management model. It takes into account the stream-aquifer connection and models the aquifer under any type of input. It represents a water balance of the aquifer and the only assumption made throughout its development is a linear outflow which in most cases is satisfactory. Two useful concepts were developed: the subsurface outflow constant and the aquifer response time. The subsurface outflow constant a, condenses several properties of the system and allows for a simple stream-aquifer interaction. The aquifer response time is a ratio of an active volume above or below a basic aquifer storage with zero outflow, to the stream-aquifer flow. The analysis shows that the range of a is not large and a simple field procedure can be used to determine this parameter. Since our model is

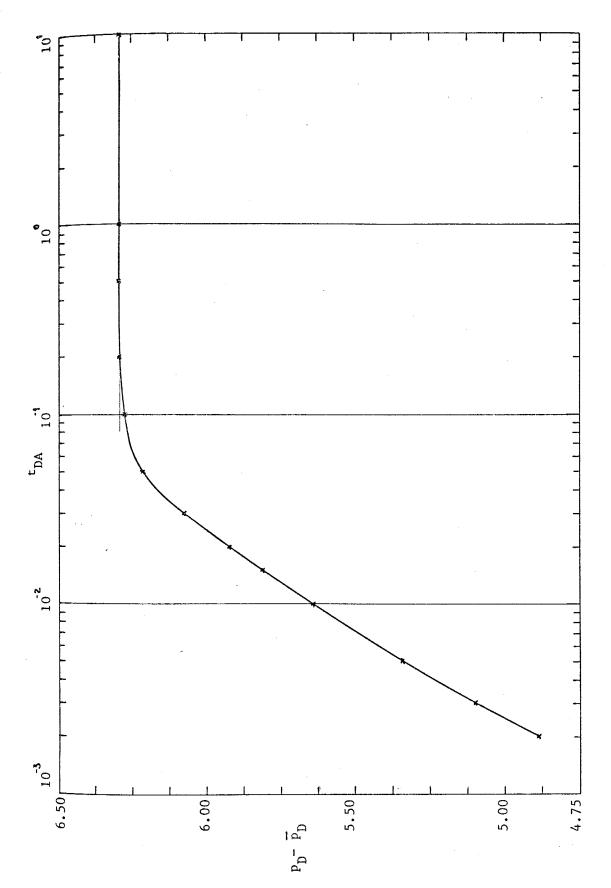


Fig. 2.10 Graph of the dimensional pressure difference $p_D^ \overline{p}_D^-$ against the dimensionless time t_{DA} .

lumped, all the variables are worked out in terms of space averages. A drawdown correction is successfully added to the average aquifer water level, to represent the drawdown in the wells.

CHAPTER 3 MANAGEMENT MODEL DEVELOPMENT

3.4 Introduction

One objective of this study is to present a simple and logical procedure for operating a system formed by a stream connected to an aquifer under optimal economic conditions. The interaction between the economics and the physics of the system is represented by the management model, which yields the optimal policy of operation. The model may also be used for design of surface and groundwater facilities (e.g. size of a dam, well fields and main canals).

The pumping cost will be considered as variable and dependent, on the pumping volume and the total lift. Linear decision rules will be used to define the decision variables. These linear decision rules allow for more dynamics in the system operation and for a deterministic analogy of chance constraints. A suitable link will be developed between the physical and management models. This link simplifies the objective function by computing the physical model outside of the management model. As a consequence of this link, it is possible to use an iterative procedure and a standard linear programming technique to solve a nonlinear optimization problem.

3.2 Systems Analysis Approach

Terminology

Systems Analysis or Operations Research is defined as a scientific approach to problem solving for executive management (Wagner 1969, p.4). However one of the main problems encountered in the use of water resources is the difference that exists in space, time and quality between the natural water supply and the water demand. Therefore, a more specific definition of operations research is; the art or science of choosing from a number of feasible alternatives whether it be in relation to planning, design, construction or operating a water resources system. An interesting discussion on the subject is found in Hall and Dracup (1970, p.39). The analysis of the set of alternatives is carried out in an organized common-sense strategy of techniques; ranking them according to a desired criterion e.g. an optimality criterion. The set of techniques available to solve the problem of development, allocation and use of limited resources to the best advantage is called Mathematical Programming. Optimization should be understood as the problem of finding the best type of action from a set of alternatives. An optimization procedure selects an optimal policy. A set of decision variables that maximizes or minimizes a performance function subject to the system constraints is called an optimal policy. An objective function, return function, value function or criterion

function is a function that establishes the criterion by which the best solution is selected.

Objectives and Limitations

The main objective of the management model is to reproduce the economics and physics of the problem and generate an optimal policy for the operation of the stream-aquifer system.

pifferent types of objectives of a water resource system can be thought of; social, economic and political or a combination of them. To simplify and to obtain a better understanding of the stream-aquifer management problem, the optimality criterion used in this study is based only on economic terms. This study is based on the following assumptions: (i) the management model is independent of changes in economic activities generated by decisions taken during the operation of the system, (ii) a central agency is responsible for the management of the system under non-competitive conditions, (iii) the water is used for agriculture only and (iv) no penalties are applied if the demand is not satisfied.

3.3 Mathematical Programming

Before going to the technique used to obtain the optimal policy, the main components of the optimization procedure will be discussed.

Objective Function

The main guiding principle used to select the objective function was the allocation of scarce water resources at the minimum possible cost. Inasmuch as operational costs need to be computed, a comparison of costs occuring at different points of time in the future was necessary. The present worth was, therefore, the economic concept used to bring out all costs to the same reference level and in order to perform this operation a nominal interest rate was used; to review these concepts in more detail an engineering economics book such as De Garno (1960) is recommended.

The objective function selected considering conjunctive use of surface and groundwater was the discounted cost, that is

$$W = \sum_{i=1}^{n} (C_{S_i} Q_{SD_i} / (1 + r/N_S)^i + C_{P_i} Q_{P_i} (Z-h_i) / (1+r/N_S)^i)$$
(3.1)

where the parameters are

```
c_s unit cost of surface water, $\(\frac{1}{2}\);
```

 c_p unit cost of pumpage, $$/L^4$;

 Q_{SD} quantity of water diverted from the stream, L^3 ;

 Q_p quantity of water pumped from the aquifer, L^3 ;

Z ground surface level, L;

h' mean water level at the wells, L;

r nominal interes rate;

n design period, T;

 N_S number of seasons per year.

The first term of the right hand side of equation 3.1 represents the discounted cost of diverting water from the stream and is linear with respect to the amount of flow Qsp. The second term is the discounted cost of pumping water out of the aquifer and is quadratic with respect to $Q_{\rm p}$, since h' depends on all past inflows of the system including pumping. In other words the groundwater pumping cost is a function of the total lift and the volume pumped. Hence our problem can be classified as a nonlinear programming type, for which standard solution packages exist (Kuester, 1973, p. 105). They have certain limitations in terms of initial assumptions, preparation of data and computer storage. Dynamic Programming Techniques could also be used but they require special computer programs for each specific problem. Aron (1969, p.40) gives advantages and disadvantages of the technique.

The purpose of this study was not to test different mathematical programming procedures but to develop a simple technique able to solve nonlinear optimization problems of the type described. This is done by taking advantage of the coupling between the physical and management model.

Constraints

Three types of constraints were used for an uncontrolled stream connected to an aquifer. The first deals with the demand of water to be satisfied; the second with the surface

water diversion and pumping facilities; and the last with the water requirements to be met by the stream.

The demand of water constraint is represented by

$$Q_{SD_{i}} + Q_{P_{i}} \geq D_{i}$$
 (3.2)

and says that the sum of surface water diverted from the stream $Q_{\mathrm{SD}_{\mathbf{i}}}$, plus the amount of water pumped out of the aquifer $Q_{\mathbf{p}_{\mathbf{i}}}$, should satisfy the water demand for a given period of time.

The pumping facilities constraint is

$$Q_{P_{i}} \leq Q_{P_{i}} \tag{3.3}$$

where Q_{P_i} is the maximum pumped volume allowable, at time \underline{i} . This constraint establishes a limit, equal to the maximum capacity of pumping, for the amount of water pumped out of the aquifer at time \underline{i} .

The surface water diversion constraint is defined as

$$Q_{SD_{i}} \leq Q_{SD_{i}} \tag{3.4}$$

where $Q_{\mathrm{SD}_{\underline{\mathbf{i}}}}$ is the maximum allowable diverted volume from the stream at time $\underline{\mathbf{i}}$. The constraint says that the amount of water diverted from the stream must be less or equal to the surface facilities vailable at time $\underline{\mathbf{i}}$.

The last constraint, called the stream requirements

constraint, consists of the conservation of matter principle applied to the stream. Recall that this principle was already considered in the aquifer, and the mean water level \mathbf{h}_i , is a result of its application. Stream and aquifer are coupled through this constraint which is very dynamic and restrictive with respect to the system operation.

Applying the conservation of matter principle to the stream under steady state conditions.

$$Q_{ST_{i}} - Q_{SD_{i}} - Q_{S_{i}} \ge K1_{i}$$
 (3.5)

the parameters are defined as:

 Q_{ST} . streamflow at time \underline{i} ;

 Q_{SD_2} water diverted from the stream at time \underline{i} ;

 Q_{S} . stream-aquifer flow at time \underline{i} ;

 $K1_{i}$ downstream flow required at time \underline{i} .

Substituting equation 2.10 into 3.5, we obtain

$$Q_{ST_{i}} - Q_{SD_{i}} - Aa (H_{i} - h_{i}) \ge K1_{i}$$
 (3.6)

which requires that the net sum of flows through the stream must be greater than or equal to any senior right existing downstream of the study area, at the time \underline{i} .

Decision Variables

The linear decision rule used to define the decision variables was introduced by Charnes et.al. (1958) for an

optimization problem and then applied by Revelle et.al. (1969) to a surface water management problem. Two important features of the linear decision rule are: (1) In a stochastic management problem, chance constraints can be changed to their deterministic equivalent; (2) It is highly desirable to base present decisions on a previous state of the process. A linear decision rule can be defined as $R_2 = \beta_{21} S_1 + \sqrt[8]{2}$ (Charnes et.al. 1958) where β_{21} , $\sqrt[8]{2}$ are the decision variables, R_2 is the unknown variable at time 2, and S_1 defines the state of the process at time 1. Several variants of this decision rule can be obtained (Charnes and Cooper 1963). Two types of decision rules are used in this study to define three decision variables. The first two decision variables use a linear decision rule such as

$$R_2 = \beta_{21} S_1$$

in which Charnes's notation is followed. The last decision variable makes use of a linear decision rule equal to that applied by Revelle et.al. (1969).

$$R_2 = S_1 + \gamma_2$$

The decision variables used in this study are:

(1) The diversion of surface water decision variable

$$\gamma_{S_i} = Q_{SD_i} / D_{i-1}$$
 (3.7)

(2) The groundwater decision variable

$$\gamma_{p_i} = Q_{p_i} / AS_{h_{i-1}}$$
 (3.8)

(3) If a dam controls the stream, a decision variable related to the dam operation is given by

$$\mathcal{J}_{B_{i}} = S_{i-1}' - Q_{ou_{i}}$$
 (3.9)

The decision variables are defined as follows:

- $\chi_{S_{\underline{i}}}$ ratio of the water diverted from the stream at time \underline{i} to the demand at time i-1;
- ratio of the water pumped from the aquifer at time \underline{i} to the amount of water stored in the aquifer at time i-1;
- difference between the storage of the surface reservoir \underline{S} at time i-1 and the volume of water released from the dam \mathbb{Q}_{01} at time \underline{i} .

Coupling of the Physical and Management Models

An important part in the development of the management model is its coupling to the physical model of the streamaquifer system. The physical model output is in our case the mean head at the wells, $\underline{\mathbf{h}}$. A pumping lift can easily be found by subtracting $\underline{\mathbf{h}}$ from the ground surface level $\underline{\mathbf{z}}$.

Three alternative links can be established between the two models: (1) The physical model is located within the management model (Longenbaugh, 1970), (2) Part of the drawdown is computed outside of the management model (Maddock, 1972), and (3) The physical model is computed outside of the management model and the head is used as a link between the models. The later method was followed in the present study. Two connections are obtained: One is performed through the objective function by means of the drawdown ($Z - h_i^{i}$), which brings to the management model all the properties and past information recorded in the aquifer by the physical model output, h; . The other connection is through the stream requirements constraint (equation 3.6) by means of the stream-aquifer interaction $Aa(H_i - h_i)$, where <u>h</u> is the mean water table in the aquifer.

Two main advantages were gained because of the use of this coupling. First, an iterative procedure using a standard linear programming package was used to solve an optimization problem having a quadratic objective function. Second, the objective function was simplified by computing the head outside of the management model since the head computation implicitly considers all past inputs of the system.

Iterative Procedure

There are procedures to linearize equations, such as

(3.1), by approximating the objective function by straight lines (separable function) and then solving the optimization problem using a linear programming package (Maass, 1966, p.501). The problem then becomes extremely cumbersome and depending on the case, sometimes it is almost impossible to solve it with the available generation of computers.

Due to the coupling between the physical and management model an iterative procedure, using a standard linear programming program, was developed to solve a nonlinear programming problem.

As noted above, equation 3.1 is quadratic in \mathbb{Q}_p when \underline{h} is unknown and includes all past stimuli of the system. However, the same equation should be linear in \mathbb{Q}_p if \underline{h} somehow was known. Therefore, the substitution of assumed values of \underline{h} in equation 3.1 makes the iterative procedure logical. In an initial step, the physical model computes the mean heads with assumed inputs to the system. The computed heads are then substituted into the management model; the answers are fed back into the physical model and the procedure is repeated as many times as necessary to satisfy a convergence criterion. The number of iterations required to reach an optimal solution depends on the initial estimates. Figure 3.1 shows a flow chart depicting the technique.

The iterative procedure behaved satisfactorily when the cost of water diverted from the stream and the cost of water pumped out of the aguifer were not equal. If both

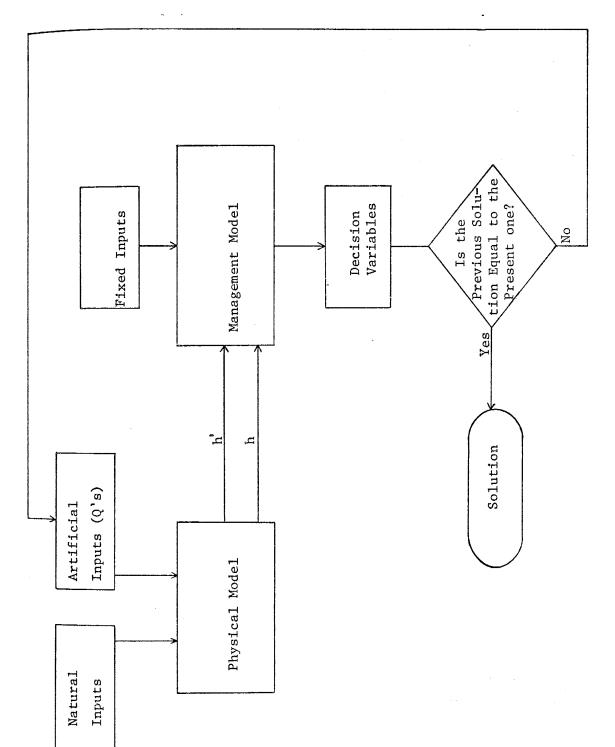


Fig. 3.1 Flow chart depicting the iterative procedure.

costs were similar, convergence problems appeared and no convergence was reached. However, this result appears reasonable since close to an optimum the model was indifferent to pumping or to use of surface water when both costs were almost the same. Furthermore, the values of the objective function for two different policies were practically same.

CHAPTER 4 STOCHASTIC REPRESENTATION OF THE PHYSICAL MODEL

4.1 Introduction

Large controversies have been raised in hydrology about the conceptual advantage of randomness over determinism (Kisiel 1969, p.23 and Yevjevich 1974). The use of stochastic approaches in groundwater hydrology has been slow in coming. In this work, a deterministic process will be presented as a special case of a stochastic or random process. The former is only concerned with the central tendency of a phenomenom and the latter also includes any unexplained variability of the studied variable. Therefore, both processes may be considered from a combined deterministic-stochastic point of view or as complements (Yevjevich, 1974, p.238).

Uncertainties or randomness in the inputs and properties of the physical model will be considered and studied. The statistics needed to represent a random stream-aquifer system are developed in this chapter. A stochastic differential equation governs the stream-aquifer system when the lumped model becomes subject to random inputs. Its solution is given in terms of ensemble averages of the aquifer head. The autocovariance function of the head as a measure of persistence, the cross correlation function as a measure of correlation between head and pumping, and the head variance as a measure of uncertainty are obtained. The subsurface outflow constant is considered to be a random variable and

through a conditional probability approach an expression for the variance of the head as a function of the variance of the subsurface outflow constant is obtained.

4.2 Stochastic Differential Equation

Three different types of randomness can be related to a system; randomness in the forcing function or inputs, randomness in the coefficients or properties of the system, and a random initial condition.

The deterministic representation of the physical model was given by equation 2.4. In this section, the initial condition h_0 , the storage coefficient \underline{S} , and the subsurface outflow constant \underline{a} will be assumed to be deterministic quantities represented by their mean values. However, the total input to the system y(t) will be a random variable. Equation 2.4 under these circumstances becomes a so called stochastic differential equation with a random forcing function (Syski, 1967, p.378).

$$S dh/dt + ah = y(t)$$
 (4.1)

Due to the random behavior of the input y(t) the filter or equation 4.1 produces a random h(t). The solutions of (4.1) are of the form of equation 2.47, that is

$$h(t) = h_0 \exp(-at/S) + 1/S \int_0^t y(\tau) \exp(-a(t-\tau)/S) d\tau$$

A simple way to represent the output process of the system is to take an ensemble average of all possible solutions of (4.1). Since integration and expectation commute, the solution of the stochastic differential equation 4.1 is represented by

$$E (h(t)) = h_o \exp(-at/S)$$
+ 1/S
$$\int_0^t E (y(\tau)) \exp(-a(t-\tau)/S) d\tau \qquad (4.2)$$

An ensemble average is defined as an average over all possible realizations at a given time. A realization is the deterministic representation obtained from measuring a stochastic process.

Equation 4.2 is valid for a stationary or non-stationary input y(t). Although the system filter is time invariant, the output of the system E(h(t)) is a non-stationary process in the mean (see e.g., Kisiel, 1969, p.20 for definitions of stationarity).

Inputs of the System

In general, the input of the physical model y(t) can be formed by the contributions of two kinds of inputs: natural inputs and man-controlled inputs. Natural inputs such as subsurface inflow, precipitation, evapotranspiration, etc. are random processes to a greater or lesser degree and with a natural persistence which can be computed from past

measurements. Some random processes depend on natural phenomena, but can be controlled by man. Such processes are pumpage, water diverted from the stream, etc. Their persistence depends on the persistence of the natural inputs and of the filter characteristics.

4.3 Statistics of the Processes

Three of the most important characteristics that define a stochastic process are: its expected value or ensemble average, the autocovariance and the variance.

The Autocovariance Function of The Head

The autocovariance function of the head represents the interdependence of the stochastic process h(t), at different times \underline{r} , \underline{t} and it is the second moment about the mean values of the function h(t).

Cov
$$(h(r) h(t)) = K_h (r, t) = E((h(r) - \mu_h(r))(h(t) - \mu_h(t)))$$

or

$$K_h(r, t) = E(h(r) h(t)) - \mu_h(r) \mu_h(t)$$
 (4.3)

Combining equation 2.47 with (4.3), we obtain

$$K_h(r,t) = 1/S^2 \int_0^r K_y(u,v) \exp(-a(r-u)/S) \exp(-a(t-v)/S) dudv$$
(4.4)

where $K_{\mathbf{y}}(\mathbf{u},\mathbf{v})$, the autocovariance of the input $\mathbf{y}(\mathbf{t})$, is defined by

$$\mathbb{K}_{y}(u, v) = \mathbb{E}(y(u) y(v)) - \mu_{y}(u) \mu_{y}(v)$$

If the process y(t) is a stationary process in the autocovariance, i.e., K_y is dependent on u-v only, then

$$K_{h}(\tau) = 1/S^{2} \int_{0}^{r} \int_{0}^{t} K_{y}(u - v) \exp(-a(r+t-u-v)/S) dudv$$
(4.5)

where T = r - t

The Variance of the Head

If r = t in equation 4.4, we obtain the variance of, \underline{h}

$$\sigma_{h}^{z}(t) = K_{h}(t, t)$$

or

$$\sigma_{h}^{2}(t) = 1/S^{2} \int_{0}^{t} K_{y}(u,v) \exp(-a(t-u)/S)\exp(-a(t-v)/S)dudv$$
(4.6)

In a real case the autocovariance of the input, ${\tt K}_{{\tt y}}({\tt u},\,{\tt v}) \text{ should be computed from raw data. However, if white }$

noise is assumed feeding a system like ours, the output \underline{h} is called a first order autoregressive process and has a standard autocorrelation function (Jenkins and Watts, 1968, p.162). White noise is a process which consists of uncorrelated contiguous impulses, with an autocovariance function $K_z(u) = \sigma_z^2 \delta(u)$, where $\delta(u)$ is the Dirac delta function (Jenkins and Watts, 1968, p.157).

In this study the random component y'(t) of the input y(t) was removed from its mean $\mu_y(t)$. The random component was assumed stationary and belonging to a first-order autoregressive process. Therefore, its autocovariance function is

$$K_{y}(\tau) = \exp(-|\tau|/J) \sigma_{y}^{2}$$
 (4.7)

where, $J = -1/\ln f_1$ and f_1 is the autocorrelation function of the input for t = 1.

Stationary Head Variance Computed Via Spectral Analysis

Next, a procedure making use of spectral analysis (see Gelhar, 1974) will be used to obtain an asymptotic or stationary expression of the variance of the head h(t).

Substituting $t_h = S/a$ into equation 4.1, we obtain

$$t_h dh/dt + h = y(t)/a$$
 (4.8)

If

$$h(t) = \mu_h(t) + f$$
 and $y(t) = \mu_y(t) + r$

where, \underline{f} and \underline{r} are stationary random components about the means, then equation 4.8 can be transformed into

$$t_h d \mu_h/dt + \mu_h + t_h df/dt + f = (\mu_y + r)/a$$
 (4.9)

taking ensemble averages

$$t_h E(d \mu_h/dt) + E(\mu_h) + t_h E(df/dt) + E(f)$$

=
$$(\mathbb{E}(\mu_y) + \mathbb{E}(r))/a$$

and since E(df/dt), E(f) and E(r) are zero.

$$t_h d \mu_h/dt + \mu_h = \mu_y/a$$
 (4.10)

by linearity, we can subtract equation 4.10 from 4.9 and get

$$t_h df/dt + f = r/a$$
 (4.11)

which is a stochastic differential equation for the random fluctuations about the mean.

Since f and r are stationary random processes,

they can be represented by a Fourier-Stieljes integral in the form (Lumley and Panofsky, 1964, p.16)

$$f(t) = \int_{-\infty}^{\infty} \exp(iwt) dZ_f(w)$$
 (4.12)

and

$$\mathbf{r}(t) = \int_{-\infty}^{\infty} \exp(i\mathbf{w}t) \, d\mathbf{z}_{\mathbf{r}}(\mathbf{w}) \tag{4.13}$$

where \underline{w} is the frequency (radians/unit time). Substituting, we have

$$\int_{-\infty}^{\infty} iwt_{h} \exp(iwt)dZ_{f}(w) + \int_{-\infty}^{\infty} \exp(iwt)dZ_{f}(w) = 1/a \int_{-\infty}^{\infty} \exp(iwt)dZ_{r}(w)$$

and then

$$dZ_{r}(w) = dZ_{r}(w)/(a + iawt_{h})$$

Since the random process Z(w) has orthogonal increments (Lumley and Panofsky, 1964, p.16)

$$E (dZ_f(w_1)dZ_f^*(w_2)) = 0$$
 for $w_1 \neq w_2$
= $S_{ff}(w)dw$ for $w_1 = w_2 = w$

and

$$E (dZ_{r}(w_{1}) dZ_{r}^{*}(w_{2})) = 0 \text{ for } w_{1} \neq w_{2}$$

$$= S_{rr}(w)dw \text{ for } w_{1} = w_{2} = w_{2}$$

where S_{ff} , S_{rr} are the spectral density functions or spectra of \underline{f} and \underline{r} respectively and $dZ^*(w)$ is the complex conjugate of dZ(w).

Since

$$E(dZ_{f}(w)dZ_{f}^{*}(w)) = E(dZ_{r}(w)dZ_{r}^{*}(w)/((a+iaS)(a-iaS)))$$
(4.14)

using the previous orthogonal properties, we find

$$S_{ff}(w) = S_{rr}(w)/(a^2 + w^2 S^2)$$
 (4.15)

Equation 4.15 gives the relationship between the spectrum of the input and the output of the system.

The spectrum is the Fourier transform of the autocovariance function and shows how the variance of a stochastic
process is distributed with frequency. Therefore, the expression for the variance of the <u>f</u> process is

$$\sigma_{f}^{2} = K_{f}(0) = \int_{-\infty}^{\infty} S_{ff}(w) dw \qquad (4.16)$$

using equation 4.7, the input spectrum is

$$S_{rr}(w) = 1/2 \pi \int_{-\infty}^{\infty} \exp(-iw \xi) K_{rr}(w) d\xi = T \sigma_r^2 / (1+J^2w^2) \pi$$
(4.17)

Using (4.17), (4.15) and (4.16),

$$\sigma_{\mathbf{f}}^2 = T \sigma_{\mathbf{r}}^2 / \pi \int_{-\infty}^{\infty} dw/(1 + J^2 w^2) (a^2 + Sw^2)$$

and performing the integration, we obtain

$$\sigma_{\rm f}^2 = \sigma_{\rm r}^2 J/a(S + Ja) \tag{4.18}$$

Equation 4.18 gives the stationary expression for the variance of the head, and was used to check values obtained from equation 4.6.

The Cross Correlation Coefficient of the Head and Pumping

An analysis similar to the previous one was carried out to find the cross correlation coefficient of the water level in the aquifer, \underline{h} , and the pumping discharge \mathbb{Q}_p .

An expression relating the head \underline{h} and specific pumping discharge $q_{\underline{p}}$ is

$$t_h dh/dt + h = -q_p/a$$
 (4.19)

Representing \underline{h} and $q_{\underline{p}}$ in complex form, we obtain

$$h(t) = \int_{-\infty}^{\infty} \exp(iwt) dZ_h(w)$$
 (4.20)

$$q_{p}(t) = \int_{-\infty}^{\infty} \exp(iwt) dZ_{q_{p}}(w)$$
 (4.21)

After substituting (4.20) and (4.21) into (4.19), we get

$$dz_h(w) = - dz_{q_p}(w)/(a + iws)$$

The cross-spectral density function of q_p and h, $S_{q_ph}(w)$ can be expressed (Lumley and Panofsky, 1964, p.21) as

$$E \left(dZ_{q_p}(w) dZ_h^*(w)\right) = S_{q_ph}(w) dw$$

Therefore

$$S_{q_ph}(w) = -S_{q_p q_p} (a + iwS)/(a^2 + w^2 S^2)$$
 (4.22)

If the random fluctuation of q_p about its mean is assumed stationary and is a first-order autoregressive process, then

$$K_{q_p} = \exp(-|\tau|/J) \sigma_{q_p}^2$$
 (4.23)

and

$$S_{q_ph}(w) = -(a+iw)T \sigma_{q_p}^2/(a^2+w^2S) (1 + J^2 w^2)\pi (4.24)$$

since

$$K_{q_p h}(o) = 1/2 \pi \int_{-\infty}^{\infty} S_{q_p h}(w) dw$$

then

$$K_{q_p h}(o) = -J \sigma_{q_p}^2 / (Ja + S)$$
 (4.25)

Let

$$\int_{q_{p}}^{q_{p}} h(o) = K_{q_{p}} h(o) / \sigma_{q_{p}} \sigma_{h}$$
 (4.26)

and by analogy with (4.18) we have

Now, substituting (4.27) and (4.25) into (4.26) produces

$$f_{Q_{p} h}(0) = - (aJ/(aJ + S))^{\frac{1}{2}}$$
 (4.28)

where P_{Q_p} h(o) is the cross correlation coefficient of the pumping and the head in the aquifer.

4.4 Randomness in the Subsurface Outflow Constant

Our system represents a natural phenomenon governed by chance. We do not know what the demand for water will be next year or how much rain will fall. Furthermore, we do

not know how much water will be pumped nor what the water level in the aquifer will be next year. The output uncertainty will depend on the uncertainty present in the system and on the randomness and persistence of the inputs.

Much work remains to be done in the theory of stochastic differential equations. Equations (of the mixed type) with both a random forcing function and random coefficients, are difficult to solve. A conditional probability approach will be followed to obtain an expression of the uncertainty of the head as a function of a random input and of the subsurface outflow constant <u>a</u> in equation 4.1.

We will start our analysis by presenting an expression for the variance of a random variable \underline{Y} which depends on another random variable \underline{X} (Parzen, 1962, p.55).

$$Var(Y) = E(Var(Y | X)) + Var(E(Y | X))$$
 (4.29)

The subsurface outflow constant \underline{a} , will be considered a random variable, leaving the storage coefficient \underline{S} , as a deterministic quantity. Equation 4.1 can be transformed to

$$S dh/dt + ah = Y_A(t) + aH(t)$$
 (4.30)

where $y(t) = Y_A(t) + a H(t)$

From the linearity of equation 4.30 and from (2.47), we obtain

$$h(t) = h_o \exp(-at/S) + 1/S \int_o^t (Y_A(\tau) + aH(\tau)) \exp(-a(t-\tau)/S) d\tau$$

Taking the expected value of h(t) given a we get

$$E(h(t)|a) = h_{o} \exp(-at/S) + 1/S \int_{o}^{t} a_{H}(T) \exp(-a(t-T)/S) dT + 1/S \int_{A}^{t} \mu_{Y_{A}}(T) \exp(-a(t-T)/S) dT$$
(4.31)

Now, making an analogy with equation 4.29, in which h(t) is a random variable that depends on another random variable, the subsurface outflow constant \underline{a} , we have

$$Var(h(t)) = E(Var(h(t) \mid a)) + Var(E(h(t) \mid a)) \quad (4.32)$$

In order to obtain the second part of the right hand side of equation 4.32 we use

$$Var (g(a)) = E((g(a) - E(g(a))^2)$$

for any function g(a).

Expanding g(a) in a Taylor series about E(a) and assuming a first order analysis (Cornell, 1972, p.1245), (i.e. neglecting terms beyond the first order)

$$g(a) \cong g(a) \Big]_{E(a)} + g'(a) \Big]_{E(a)} (a - E(a))$$
 (4.33)

Squaring equation 4.33 and taking the expected value

(Papoulis, 1965, p.152)

$$\mathbb{E}((g(a) - g(\mathbb{E}(a)))^2) \cong (g'(a))_{\mathbb{E}(a)}^2)^2 \sigma_a^2$$
 (4.34)

with g(a) = E(h(t) | a)

$$\operatorname{Var} (\mathbb{E}(h(t) \mid a)) \cong (\partial \mathbb{E}(h(t) \mid a) / \partial a)_{\mathbb{E}(a)})^{2} \sigma_{a}^{2}$$
(4.35)

The first term of the right hand side of (4.32) can be obtained by taking the expected value of (4.6). Hence

$$E(Var(h(t) | a)) = 1/S^2 \int_0^t E(K_y(u,v,a,)exp(-a(t-u)/S))$$

$$exp(-a(t-v)/S))dudv (4.36)$$

Expanding $K_y(u,v,a)$ about E(a) and assuming a first order analysis and then taking the expected value, we obtain

$$\mathbb{E}(\mathbb{K}_{y}(u,v,a)) \cong \mathbb{K}_{y}(u,v,\mathbb{E}(a))$$

Therefore

$$Var(h(t)) \approx 1/S^2 \int_0^t \int_0^t K_y(u,v,E(a)) \exp(-E(a)(t-u)/S)$$

.
$$\exp(-E(a)(t-v)/S \, dudv + (\delta(E(h(t)|a)]_{E(a)})/\delta a)^2 \, \sigma_a^2$$
(4.37)

The above expression shows the variance of the water levels

due to the uncertainty in the input $\,\underline{y}\,$ and in the subsurface outflow constant $\,\underline{a}\,$.

CHAPTER 5 STOCHASTIC REPRESENTATION OF THE MANAGEMENT MODEL

5.1 Introduction

No general procedure has yet been developed to solve the general stochastic programming problem in which some of the parameters are random. There are two bounds to the solution of a stochastic programming problem (Hadley, 1964, p.180); the lower bound can be obtained by determining the optimal value of the objective function for every possible set of parameters assuming that the random variables are known a priori, and then taking the expected value over all values of the random variables. The upper bound is obtained by replacing all the random parameters by their expected values and therefore, the variables found form a feasible but not necessarily optimal solution.

A solution of a stochastic programming problem could be obtained assuming that each model parameter can take on any one of a finite number of known values and all constraints hold for all possible combinations. However, the number of constraints becomes prohibitive if the number of possibilities is reasonably large. Also, the joint density function of the parameters must be known in this procedure.

The approach which will be followed in this work is a trade-off with respect to the solution that occurs between the two bounds. Expected values of the variables will be used in the objective function and the constraints will be

of the chance constraints type or constraints that hold for most of the possible combinations but not for all. General operations research books discuss this type of constraint (e.g., Hillier, and Lieberman, 1972, p.536).

A stochastic management model will be developed to represent the management of a stream-aquifer system where economic and physical variables are governed by chance.

Uncertainties for the demand of water and future availability of groundwater and surface water facilities will be considered. A stochastic management model aids in obtaining optimal operational policies and in designing water facilities.

The objective function is a function of the uncertainty in the aquifer water levels and of the cross correlation between pumping and head. It represents the discounted expected value of cost. Chance constraints (Charnes, et.al., 1958) are used to include probabilities of satisfaction of constraints. A nonstationary demand is easily reproduced by these constraints. The linear decision rule is used to define the decision variables and helps to transform the chance constraints into deterministic constraints. Finally, the computational part of the iterative procedure, used to solve the nonlinear programming problem, is discussed.

5.2 Decision Variables

The policy, control or decision variables, those deterministic variables calculated out of the optimization Process, are defined as in the deterministic case (see,

section 3.3) and they are:

The surface water decision variable

$$\mathcal{J}_{S_i} = Q_{SD_i} / D_{i-1}$$

The groundwater decision variable

$$\gamma_{p_i} = Q_{p_i} / ASh_{i-1}$$

The dam operation decision variable

$$\mathcal{T}_{B_i} = S'_{i-1} - Q_{ou_i}$$

The variables appearing in the decision variables definitions are random.

One advantage of the linear decision rule in defining the decision variables is that when the random events materialize in the form of preceding events (D_{i-1}, h_{i-1} and S_{i-1}) they become known and are used in connection with the decision variables to make decisions (Q_{SD_i}, Q_{P_i}, and Q_{ou_i}) at the present. Therefore a random problem is transformed into one which deals with deterministic quantities. This feature is useful in scheduling problems; the decision policy is dynamic in the sense that current decisions depend on the previous condition of the system.

5.3 Objective Function

Due to the random nature of the variables, the objective function becomes a random variable; however, since it is meaningless to minimize a random variable, a deterministic quantity is needed. The expected value was selected because of its simplicity.

If we take the expected value of equation 3.1 (ensemble average), the objective function will represent the discounted expected value of cost.

Minimize
$$E(W) = \sum_{i=1}^{n} \mu_{C_{S}} \mu_{Q_{SD_{i}}} / (1 + r/N_{S})^{i}$$

$$+ \sum_{i=1}^{n} \mu_{C_{P}} (Z \mu_{Q_{P_{i}}} - E(Q_{P_{i}} h_{i})) / (1 + r/N_{S})^{i}$$

$$+ \sum_{i=1}^{n} \mu_{C_{P}} \Psi(Q_{P_{i}}^{2}) / (1 + r/N_{S})^{i}$$

$$+ \sum_{i=1}^{n} \mu_{C_{P}} \Psi(Q_{P_{i}}^{2}) / (1 + r/N_{S})^{i}$$
(5.1)

where the well water level, \underline{h}' , is represented by $h \not \in DC$ and the drawdown correction, DC, is given by (2.49)

$$DC = S_W - \overline{S} = \psi Q_D$$

Considering Q_p and \underline{h} to be correlated, we have

$$E \left(Q_{P_{i}} h_{i}\right) = \mu_{Q_{P_{i}}} \mu_{h_{i}} + \rho_{Q_{P_{i}}} \sigma_{Q_{P_{i}}} \sigma_{h_{i}}$$

$$(5.2)$$

also

$$\mathbb{E} (Q_{P_{i}}^{2}) = M^{2}_{Q_{P_{i}}} + \sigma^{2}_{Q_{P_{i}}}$$
 (5.3)

where $f_{\rm Qph}$ is the cross correlation coefficient of pumping and aquifer head, $f_{\rm Qp}$ is the standard deviation of pumping and $f_{\rm h}$ is the standard deviation of aquifer head. Substituting (5.2), (5.3) and the first two decision variables into (5.1), we get

Minimize

$$E(W) = \sum_{i=1}^{n} (1/(1 + r/N_{S})^{i}) \mu_{C_{S}} \mu_{D_{i-1}} \gamma_{S_{i}} + \mu_{C_{P}}^{AS} (Z \mu_{h_{i-1}}) - \mu_{h_{i-1}} \mu_{h_{i}} + \mu_{DC_{i}} \mu_{h_{i-1}}) \gamma_{P_{i}} + \mu_{C_{P}} (-\rho_{Q_{P}} \sigma_{Q_{P_{i}}} \sigma_{h_{i}} + \gamma \sigma_{Q_{P_{i}}}^{2}))$$

$$(5.4)$$

From equation 4.27, for a stationary process,

$$\sigma_{\rm h} = \sigma_{\rm q_p}$$

where $\underline{\mathbf{C}}$ is a constant which depends on aquifer properties. Above equation can be transformed into

$$\mathbf{\sigma}_{Q_{p}} = c_{1}\mathbf{\sigma}_{h} \tag{5.5}$$

where the constant $C_1=C/A$, since $q_p=Q_p/A$ and $\sigma_{q_p}=\sigma_{Q_p}/A$. Substituting (5.5) into (5.4) we obtain

Minimize

$$E(W) = \sum_{i=1}^{n} (1/(1 + r/N_S)^i) \mu_{C_S} \mu_{D_{i-1}} \gamma_{S_i} + \mu_{C_P} AS(Z) \mu_{h_{i-1}}$$

$$-\mu_{h_{i-1}} \mu_{h_i} + \mu_{DC_i} \mu_{h_{i-1}} \gamma_{P_i} + \mu_{C_P} (-C_1 \rho_{Q_P} h^+ C_1^2 \gamma) \sigma_{h_i}^2$$
(5.6)

where, the first term represents the cost of surface water diversion, the second term is that portion of the pumping cost which does not depend on the head variance, and the last term is that part of the pumping cost that depends on the head variance.

5.4 Chance Constraints

Chance constraints are not absolute but are satisfied up to specified probability levels. They were introduced by Charnes and Cooper (1959) as an approach to linear programming under uncertainty. As used in this work they include: (1) probabilities that imply degree of constraint satisfaction; (2) uncertainties of water facilities; and (3) nonstationary of the demand.

The constraint on the demand of water will be taken as an example of the procedure for representing a system restriction, by a chance constraint.

We are interested in the satisfaction of the demand constraint (see equation 3.2) under the probabilistic condition

$$P \left(D_{i} - \left(Q_{SD_{i}} + Q_{P_{i}}\right) \leq 0\right) \geq \lambda^{*}_{1}$$
 (5.7)

where λ^*_1 is a level of probability chosen to satisfy the probabilistic statement. Since the demand of water \underline{D} , the amount of water diverted from the stream Q_{SD} , and the aquifer pumping Q_P are random variables, (5.7) is a difficult statement to convert to certainty inequalities that can be used in the linear programming. In place of (5.7) we state

$$P(D_{i} \leq \mu_{Q_{SD_{i}}} + \mu_{Q_{P_{i}}}) \geq \lambda_{1}$$
 (5.8)

For various values of λ_1 we give lower bounds on P (D_i - (Q_{SD_i} + Q_{P_i}) \geq 0) in Appendix G; these calculations indicate that the probability level λ_1^* in (5.7) is slightly smaller than the value λ_1 . It is shown how λ_1^* can be estimated from a given value of λ_1 .

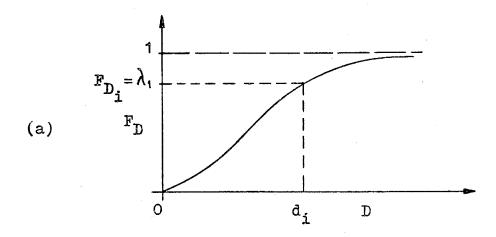
Therefore, the cumulative distribution of the demand $F_{D_{\dot{\mathbf{1}}}}$ (d) at a time $\underline{\mathbf{i}}$ (see, Figure 5.1) is defined as

$$F_{D_{i}}(d) = P (D_{i} \leq d)$$
 (5.9)

where \underline{d} is a variable. To insure that (5.9) is satisfied

$$\mathbf{d} \geq \mathbf{d}_{\mathbf{i}} (\lambda_{\mathbf{1}}) \tag{5.10}$$

where $d_i(\lambda_1)$ is the solution for x_1 of the equation $F_{D_i}(x_1) = \lambda_1$. Hence, from (5.8) and introducing the decision variables (see Section 5.2), we obtain



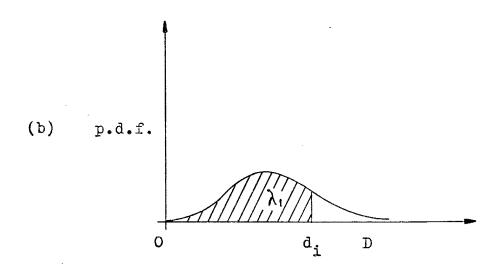


Fig. 5.1 (a) Cumulative probability distribution of the demand for a given level of probability λ , and (b) Probability density function of the demand for a given level of probability

$$F_{D_{\mathbf{i}}}(\mu_{D_{\mathbf{i}-1}} \chi_{S_{\mathbf{i}}} + AS \mu_{h_{\mathbf{i}-1}} \chi_{P_{\mathbf{i}}}) \ge \lambda_{1}$$
 (5.11)

This inequality may be called a chance representation of the demand. Equation (5.11) is equivalent to

$$\mu_{D_{i-1}} \gamma_{S_i} + AS \mu_{h_{i-1}} \gamma_{P_i} \geq d_i (\lambda_1)$$
 (5.12)

where $\mathbf{d_i}(\lambda_1)$ can be connected with μ_D and σ_D , to produce

$$\mu_{\mathbf{D_{i-1}}} \gamma_{\mathbf{S_i}} + \mathbf{AS} \mu_{\mathbf{h_{i-1}}} \gamma_{\mathbf{P_i}} \geq \mu_{\mathbf{D_i}} + \mathbf{x} \sigma_{\mathbf{D_i}}$$
 (5.13)

where \underline{x} depends on λ_1 and the type of probability density function of the demand which can be skewed.

Equation 5.13 is a deterministic representation of the chance constraint and can be used with a mathematical programming technique. A nonstationary demand can easily be represented by this constraint and if (5.12) is used instead of (5.13) a skew probability density function of the demand can easily be considered.

According to equation 5.13, the probability that the water demand in a given time period \underline{i} be smaller than or equal to the average sum of flows Q_{SD} and Q_{p} must be greater than or equal to a probability level λ_1 .

Another type of constraint states that the available pumping capacity at a time period <u>i</u> must be greater than or equal to the average amount of water pumped from the

aquifer with a given probability level λ_2 . In other words, there is always an uncertainty present in the available pumping capacity at a given time, due to maintenance and operational problems which shut down several of the available wells. Therefore, there is no way to know precisely how much water we shall be able to pump at a future time. The chance constraint for pumping facilities is

$$AS \mu_{h_{i-1}} \gamma_{P_{i}} \leq \mu_{Q_{P_{i}}} + x \sigma_{Q_{P_{i}}}$$
 (5.14)

where $\sigma_{\mathbb{Q}_{P}^{'}}$ represents the standard deviation of the pumping capacity and $\mu_{\mathbb{Q}_{P}^{'}}$ the expected amount of water that can be extracted from the aquifer at time period \underline{i} .

Equation 5.14, as well as the other constraints, can be obtained following a procedure similar to that used for the demand-of-water constraint.

The surface water diversion constraint states that the available surface water capacity at time period \underline{i} must be greater than or equal to the average amount of water diverted from the stream at the same time with a probability level λ_3 . The constraint can be written as

$$\mu_{\mathcal{D}_{i-1}} \gamma_{\mathcal{S}_i} \leq \mu_{\mathcal{Q}_{SD}} + x \sigma_{\mathcal{Q}_{SD}}$$
 (5.15)

where $\sigma_{
m QSD}$ is the standard deviation of the surface water capacity and $\mu_{
m QSD}$, the expected amount of water that

the surface water facilities can convey at a given time i.

Finally, the stream requirements constraint states that the average flow left in the stream, after all uses and interactions between the stream and the aquifer, at time period <u>i</u>, must be greater than or equal to the downstream flow required at the same time.

$$\mathbb{P} \left(\mathbb{Q}_{\mathtt{ST}_{\underline{\mathtt{i}}}} \geq \mu_{\mathbb{Q}_{\mathtt{SD}_{\underline{\mathtt{i}}}}} + \mu_{\mathbb{Q}_{\mathtt{S}_{\underline{\mathtt{i}}}}} + \mu_{\mathtt{K1}_{\underline{\mathtt{i}}}} \right) \geq \lambda_{4}$$

or

$$1 - \mathbb{F}_{Q_{ST_{i}}} (\mu_{Q_{SD_{i}}} + \mu_{Q_{S_{i}}} + \mu_{K1_{i}}) \ge \lambda_{4}$$
 (5.16)

where the variables were defined in Section 3.3 in a deterministic form. The certainty equivalent of equation 5.16 is

$$\mu_{D_{i-1}} \chi_{S_{i}} + Aa(\mu_{H_{i}} - \mu_{h_{i}}) + \mu_{K1_{i}} \leq d_{i} (1 - \lambda_{4})$$

where $\text{d}_{\text{i}}(\text{1}-\lambda_4)$ represents the 100.(1 $-\lambda_4)$ percentile of the streamflow Q_{ST} .

5.5 Iterative Procedure

An iterative procedure similar to that described in Chapter 3 is used to solve the stochastic management problem.

Figure 5.2 shows a flow chart depicting the iterative procedure. The variable names are given in previous sections

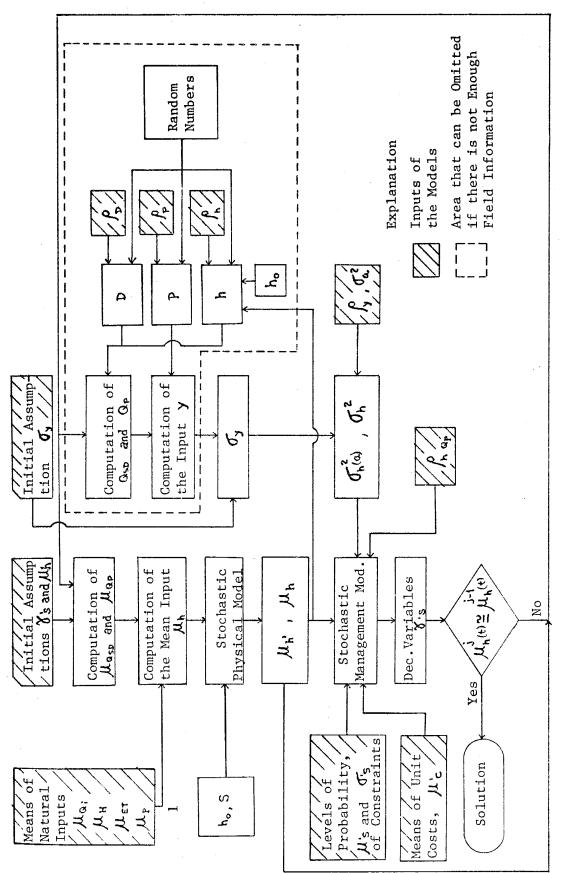


Fig. 5.2 Iterative procedure of a stochastic management problem.

or in the list of symbols. Shaded blocks show the inputs to the system and the area delimited by dashed lines represents the generation of the random input Y_i . This can be omitted if not enough field information is available. In this case, $\sigma_{\rm v}^{\rm 2}$ should be assumed. Assumpthe variance of the input tions implied throughout the computation of the variance of the input are: (1) the components of the general input, Y_i , are statistically independent; (2) first order autoregressive processes are used to simulate demand of water, D_i , precipitation, P_i and the aquifer head, h_i ; (3) a normal cumulative distribution function is used to generate random numbers; (4) the variance of y is assumed constant and is estimated by $\sigma_{\overline{y}}^2 = \sum_{i=1}^{n} (y_i - \overline{y})^2/(n-1)$; (5) precipitation is the only natural input with important randomness. Certainly most of the above assumptions could easily be relaxed; they were chosen to keep the simulation of data simpler and closer to the real case.

In summary, we have presented the stochastic management model in its simplest form. Depending on a specific problem, more terms may be added to the objective function, as well as constraints. The iterative procedure and basic concepts and equations will remain the same giving generality to the work presented.

CHAPTER 6 RESULTS AND APPLICATIONS

6.1 Introduction

To examine the reliability of the models developed herein, a comparative test was done based on a suitable case study obtained from the literature related to the subject. Furthermore, to demonstrate the viability and the versatility of these models they were applied to an actual stream-aquifer system, located in northwestern Mexico.

6.2 Comparative Study

Two features of the models were examined through comparative study: the presence of uncertainties or randomness in the stream-aquifer system and the distribution of variables in space and time. Based on a survey of related literature, a study by Maddock (1974) was chosen for the comparative work because it uniquely met the above requirements.

Maddock developed operating rules for the conjunctive use of surface water and groundwater when the demand and the natural supply (streamflow) are stochastic. He used a set of "technological functions" to condense information supplied by a distributed aquifer model and to get a link between the physical model and the stochastic management model. Also, when his water demand was represented by a Markov process (first-order autoregressive process) a demand

persistence was introduced into the management model through the product of pumping and drawdown.

It was our purpose to simulate the reference problem as closely as possible. Nevertheless, a few discrepancies remain. For instance, the main source of randomness in Maddock's case was the demand, while for the model proposed here it is the mean water level in the aquifer which involves the randomness. Also in the present model, decision variables are defined differently. In Maddock's work the decision variables are defined as ratios of flow to demand at a specific time <u>i</u>, while here the decision variables are defined as ratios of flow occurring at time <u>i</u> to the demand of water occurring at time i-1, or to the volume of water stored in the aquifer at time i-1. This definition is the result of the use of a linear decision rule which allows more dynamic decision variables.

The proposed management model is given by the following equations which should be compared to the development in Chapter 5 (Sections 5.2, 5.3 and 5.4). Objective function;

$$E(W) = \sum_{i=1}^{n} \frac{1}{(1 + r/N_S)^{i}} \mu_{C_S} \mu_{D_{i-1}} \chi_{S_i} + \alpha_1 \mu_{C_u} \mu_{D_{i-1}} \chi_{u_i} + \mu_{C_u} \mu_{D_{i-1}} \chi_{u_i} + \mu_{C_u} \mu_{D_{i-1}} \chi_{u_i} + \mu_{C_u} \mu_{D_{i-1}} \chi_{u_i} + \mu_{C_u} \mu_{D_{i-1}} \chi_{D_u} + \mu_{D_u} \mu_{D_{i-1}} \chi_{D_u} + \mu_{D_u} \mu_{D_{i-1}} \chi_{D_u} + \mu_{D_u} \mu_{D_u} + \mu_{D_u} \mu_{D_$$

Constraints;

(1) Demand of water,

$$\mu_{D_{i-1}} \chi_{S_i} + AS \mu_{h_{i-1}} \chi_{P_i} \geq \mu_{D} + x \sigma_{D}$$
(6.2)

(2) Stream Requirements,

$$\mu_{D_{i-1}} \gamma_{S_i} - \alpha_1 \mu_{D_{i-1}} \gamma_{i} \leq \mu_{Q_{ST_i}} - aA \mu_{H} + aA \mu_{h_{i-1}}$$
 (6.3)

(3) Water left after the demand is satisfied,

$$\mathcal{U}_{\mathbf{u_i}} + \mathcal{U}_{\mathbf{R_i}} = 1$$
 (6.4)

Decision variables;

(1) Surface water diversion,

$$\gamma_{S_{i}} = Q_{SD_{i}} / D_{i-1}$$
 (6.5)

(2) Water returned to the stream,

(3) Pumping,

$$\gamma_{P_{i}} = Q_{P_{i}} / ASh_{i-1}$$
 (6.7)

(4) Artificial recharge,

where the parameters are

 $\mathbf{Q}_{\mathrm{SD}_{\mathbf{i}}}$ amount of water diverted from the stream at time $\underline{\mathbf{i}}$;

 $Q_{u_{\dot{1}}}$ amount of water returned to the stream at time \underline{i} ; $Q_{P_{\dot{1}}}$ amount of water pumped out of the aquifer at time \underline{i} ; \underline{i} ;

 $\mathbf{Q}_{\mathbf{R_i}}$ amount of water recharged to the aquifer at time $\underline{\mathbf{i}}$.

The rest of the variables are defined in the List of Symbols. All the decision variables, except that for pumping, are in a form equivalent to that used by Maddock. Since the pumping decision variable is defined differently, the structure of the objective function is such that the variance of the head appears rather than that of the demand.

Table 6.1 summarizes the important conceptual differences between the two models. An idea of the simplicity of our physical model is demonstrated by the number of aquifer parameters needed.

$$T = 0.031 \text{ ft}^2/\text{s}$$

S = 0.01

L = 4900 ft

A = 8173 acres

 $\beta = 3$

TABLE 6.1 Significant Differences Between the Compared Models.

	Distributed Parameter Model (Maddock, 1974)	Lumped Parameter Model (Present Investigation)
	The location of wells must be specified	The location of wells is not specified and the
Physica1	and the aquifer properties defined in	aquifer properties are average values. The
Model	detail. The pumping scheduling is	pumping scheduling is obtained for the entire
	obtained for every well.	region.
	This model computes the drawdown at	Since this model does not compute the drawdowns
	nodal points representing wells.	at the well locations, a drawdown correction is
		added in order to achieve correct pumping costs.
	A standard quadratic programming package	An iterative procedure was developed to take
	requiring 190 k bytes of core was used.	advantage of the structure of the physical model
		and a simple linear programming package is used.
		A phase overlay computer software technique helps
Management		to reduce program storage to 144 k bytes of core.
Model		A solution requiring two iterations is solved in
		about 12 minutes on an IBM 360 model 44 system.
	An average demand constraint is applied	A chance demand constraint is applied to the
	to the problem.	problem.
	"Static" decision variables.	Dynamic decision variables which use the linear
		decision rule.
*		

The properties of the homogeneous aquifer, transmissivity and storage coefficient, and a map of the study area were provided by Maddock (personal communication, 1975). The characteristic length <u>L</u> of the system (Section 2.3) was estimated from the aquifer area and the length of the main stream channel. The location of the wells was unknown. Appendix H gives the information required by the models and the variable names. A response time the of one month was obtained for this system by using (2.47).

The operating rules formulated by Maddock for a coefficient of variation of 0.457 and a mean demand of water of 131 acre-ft per season are shown in Table 6.2 along with our results for the same situation. A remarkable likeness is to be noted in these results, which substantiates the competence of our stochastic management model in general and the iterative procedure in particular.

By referring to the deterministic case, we obtain the sensitivity of the discounted expected cost to changes in the demand variance. This sensitivity is expressed by Maddock as a percent error in the discounted expected cost in relation to the deterministic world assumption $P'(\sigma_D^2, 0)$, versus σ_D^2 . An expression that defines $P'(\sigma_D^2, 0)$ is

$$P'(\sigma_D^2, 0) = (E(W(\sigma_D^2, 0)) - E(W(0,0))).100/E(W(0,0))$$
(6.9)

where E(W(0,0)) is the discounted expected cost when the true value of the demand is known (deterministic case).

TABLE 6.2 Comparison of Operating Rules of Maddock's and Proposed Models.

	Ďecision Variables									Expected	
	Pumping			Stream Diversion		Return to the Stream		Spreading		Interaction Withdrawal from Stream (acre-ft)	
Sea- son	V (1,n)	X*(2,n)	y,	λ^* (n)	71 5	}** 5(n)	71	V * (3,n)	ð' _R	f(n)	Qs
1 2 3 4 5 6	0.511 0.519 0.466 0.514 0.516 0.519	0.489 0.481 0.534 0.486 0.484 0.481	1.0 1.0 1.0 1.0	0.0 0.0 0.0 0.0	0.0	0.0		1.0 1.0 1.0 1.0 1.0	1.0 1.0 1.0 1.0	84 89 89 93 93 94	57 62 62 62 62 62
1 2 3 4 5 6	0.523 0.527 0.447 0.516 0.517 0.520	0.477 0.473 0.553 0.484 0.483 0.480	1.0 1.0 1.0 1.0	0.0	0.0	0.0 0.0 0.036 0.0 0.0	0.0	1.0 1.0 0.964 1.0 1.0	1.0 1.0 1.0 1.0	95 95 93 96 96 96	62 62 62 62 62 62
1 2 3 4 5 6	0.525 0.529 0.449 0.489 0.515 0.517	0.475 0.471 0.551 0.511 0.485 0.483	1.0	0.0 0.0 0.0 0.0	0.0	0.0 0.0 0.054 0.0 0.0	0.0 0.0 0.0 0.0	1.0 1.0 0.946 1.0 1.0	1.0 1.0 1.0 1.0 1.0	97 97 95 96 98 98	62 62 62 62 62 62
1 2 3 4 5 6	0.522 0.526 0.446 0.466 0.504 0.499	0.478 0.474 0.554 0.534 0.496 0.501	1.0 1.0 1.0 1.0 1.0	0.0 0.0 0.0 0.0 0.0	0.0	0.0 0.0 0.063 0.0 0.0	0.0	1.0 1.0 0.937 1.0 1.0	1.0 1.0 1.0 1.0 1.0	98 98 96 96 98 98	62 62 62 62 62 62

^{*} Maddock's Solution
Present Investigation

(k) = (1,n) + (2,n)

(k) = Fraction of the demand

Fraction of the demand supplied by the κ th well during the $\ n$ th time period

This expression for sensitivity was also utilized in the present investigation as a basis for comparison. The results of this analysis are expressed in graphical form in Figure 6.1. Maddock's result represents the point given in the text of Maddock (1974, p.9); Maddock (personal communication, 1975) has stated that his Figure 2 is incorrect. His results are only a special case of a more general stochastic representation used in the presented management model. In Maddock's problem, the expected value of the demand of water is satisfied according to any given level of probability λ , as shown in Figure 6.1 by using a chance constraint representation (Section 5.4). In addition, a non-stationary demand could easily be represented by this type of constraint (see equation 6.2).

Up to this point apparently no discrepancies exist between the management decision resulting from the two approaches. The aquifer in our case shows a decline of the mean water level which is responsible for the stream aquifer flow. However, a water balance calculation from Maddock's Table 5 implies that the mean water level of the aquifer underwent a recovery of 8.6 ft at the end of the design period instead of declining. The explanation of this phenomenon was found in the distributed nature of Maddock's model, which was able to simulate the local cone of depression of a pumping well and to induce local stream to aquifer flow even though the mean water level in the aquifer was above the stream level.

EXPLANATION

Maddock (1974) expected value constraint (equivalent to $\lambda = 0.5$)

× Present study

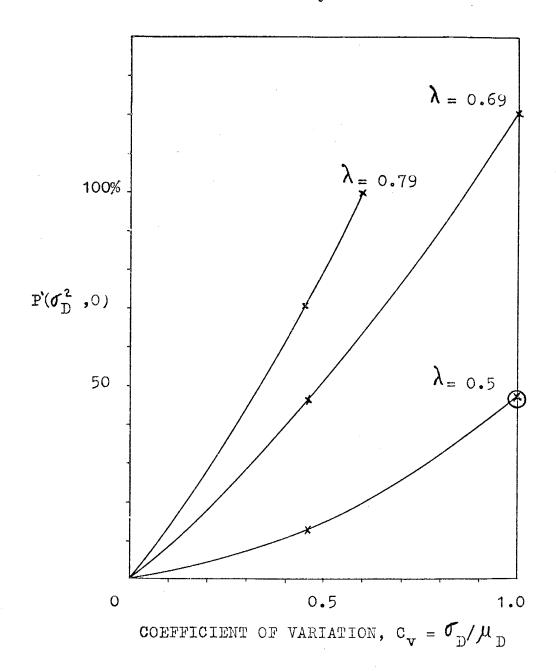


Fig. 6.1 Graph of P(σ_D^2 , 0) versus c_v , as a function of probability level λ .

Since the cone of depression due to pumping of only two wells was the dominant effect on aquifer flow it was difficult for our lumped model to manage problems of the local flow type, even though a correction for the effect of drawdown at the wells themselves was included. As a consequence, the values of the objective function differ in magnitude. For a coefficient of variation of 0.458 and $\lambda = 0.5$, Maddock's objective function was \$3606, while in our case it was \$3976.

The advantage of our models in terms of computational effort and simple structure is illustrated by the fact that only 24 quantities, appear in the pumping term of the objective function compared to 600 cf Maddock. For instance if we had 20 pumping wells, (instead of 2, as in the present case), Maddock's objective function would show 6000 different products of decision variables; while only 24 quantities would still appear in our case.

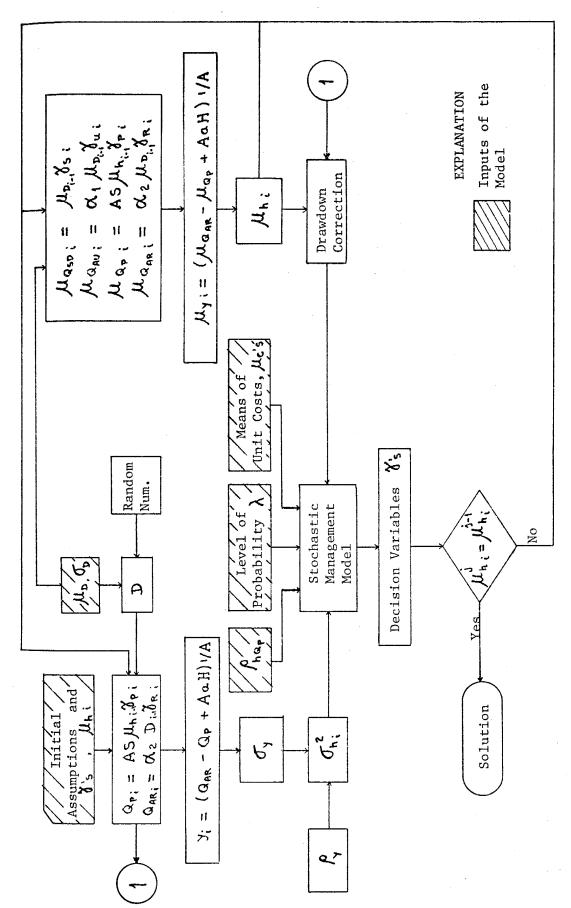
A management model such as Maddock's is very cumbersome and almost impossible to solve when the number of pumping wells is large. This is due to the large number of terms in the objective function, which is not only a consequence of the distributed representation of the problem but also of the structure of the physical model. To compute drawdown in Maddock's management model all past pumping must be included in the objective function.

A discrete representation of the convolution integral is part of our lumped parameter model solution and is used

to compute all past pumping outside of the management model condensing the past information into the current aquifer head. Hence, when the physical model and the management model are brought together in the objective function many complications are avoided and an iterative procedure arises as a natural procedure for solving the nonlinear optimization problem. The iterative procedure used to solve Maddock's problem is depicted in Figure 6.2 and a listing of the computer program is supplied in Appendix I. The inputs of the models are: initial assumptions of the decision variables and the mean aquifer water levels; and the model parameters. Normally distributed random numbers were used to simulate random demand needed in the artificial recharge computation. As a computational simplification, mean water levels instead of random water levels were used in the pumping computation. To compute the variance of the system input, $\sigma_{
m v}^{\,\,2}$, a time average was used and stationarity was assumed. The computation of the variance of the aquifer head was obtained from (4.6) and the mean water levels from (4.2). The drawdown correction was computed using (2.49).

Summary of Model Testing

The simple physical model was developed for regional studies where the effect of many wells produces a quasi-mean water level change. The resulting operating rules compare satisfactorily with Maddock's results. However under the local flow situation herein tested, in which the pumping



Flow chart of the iterative procedure used to solve Maddock s problem. Fig. 6.2

effect of two wells produced cones of depression dominating the flow picture, the lumped model indicates a slightly higher value of the objective function.

The stochastic management model, with the use of a linear decision rule to define the decision variables, makes the problem more dynamic since every future decision for the system depends on a known present situation. Furthermore the use of a chance constraint representation of the demand shows that situations such as Maddock's dealing with average accomplishments (50% level of probability) are only special cases of a more general problem, in which any desired level of probability can be considered. Demands of water represented as nonstationary process, can easily be managed by a chance constraint, as used in the present work.

6.3 Application

Introduction

The objective of this part of the study was to illustrate the application of the present management scheme to a complex and realistic field problem. A system able to develop conjunctive use of surface water and groundwater and a central management agency were used to test the reliability and adaptability of the models to specific situations. A basin in northwestern Mexico was chosen as the study case. Inasmuch as not enough detailed field information was available to represent the area accurately, the results obtained from our models should not be thought

was important but not the most important criterion. The practical objectives of the investigation were: to formulate an optimal operational schedule for the system; and to determine the size of a projected dam for control of the stream. We especially considered uncertainties present in the natural inputs, in future demands of water, in availability of surface and groundwater facilities, and in the stream-aquifer subsurface outflow constant.

Description of the Area

The study area is crossed by the Rio Sinaloa which flows into the Gulf of Baja California. Two well fields exist, one on each side of the river. They serve mainly agriculture. The boundaries of the system are shown in Figure 6.3. Additional information on the area can be found in Appendix J.

Water Balance

To obtain the subsurface outflow constant a water balance of the studied area was carried out for the period between September of 1969 to September of 1970, this portion of the problem can be defined as the calibration part. The following equation represents the water balance of the aquifer

$$S dV/dt = Q_i + N_r + Q_{ret} + Q_C + Q_S - Q_P - ET$$
 (6.10)

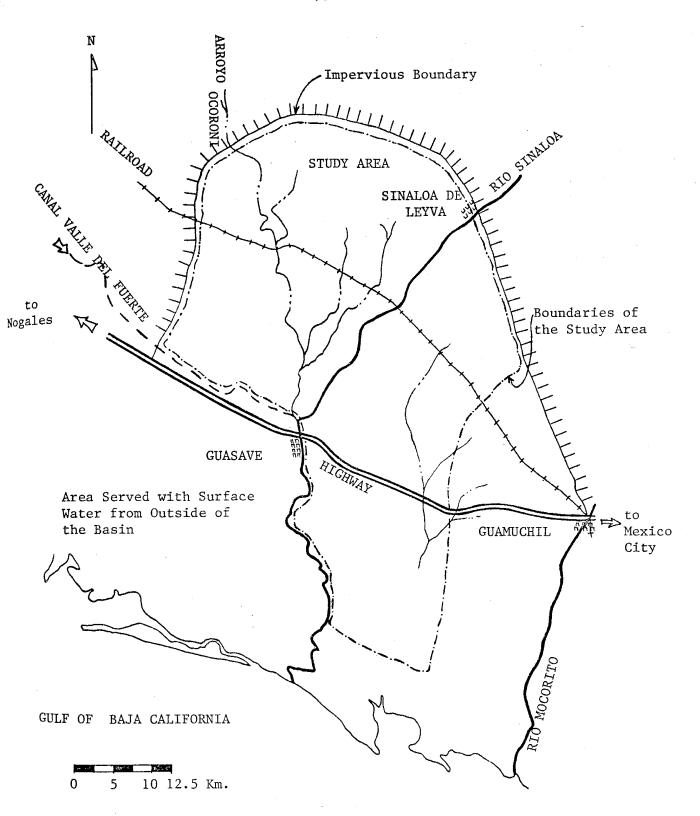


Fig. 6.3 Map of the Rio Sinaloa study area.

where

$$N_r = \alpha_1 P'$$

$$Q_{ret} = \alpha_4 \alpha_2 (Q_P + \beta_1 P + Q_{SD})$$

$$Q_S = Aa(H - h)$$

$$Q_{C} = \alpha_{3} Q_{SD}$$

The variables are defined in Figure 6.4.

To visualize better the magnitude of the variables equation 6.10 may be expressed in terms of water depths; this is done by dividing by the aquifer area \underline{A} .

$$S dh/dt = \epsilon - q_p + a(H - h)$$
 (6.11)

in which

$$\epsilon = q_1 + \alpha_1 p' + \alpha_4 \alpha_2 (q_p + \beta_1 p + q_{SD}) + q_{SD} - q_{ET}$$
(6.12)

Information about the variables involved in (6.11) and (6.12) is presented next.

- a) Irrigated Land. Irrigated land of 460 Km² and an aquifer of 1744 Km² were included in the aquifer water balance.
- b) Water demand. An average consumptive use of one

EXPLANATION

Q_{SD} : Surface water applied to

the field

: Conveyance loss

 \mathfrak{d}_{RS} : Surface drainage

CU : Consumptive use

Evapotranspiration

: Precipitation

: Recharge from precipitation Subsurface inflow

Vret: Irrigation return flow : Pumping

: Stream-aquifer flow

AQUIFER SURFACE LAND AND SOIL Z o[‡] Q, ď o Sp

Fig. 6.4 Rio Sinaloa water cycle.

meter was estimated. This estimate is based on the consumptive use of the main crops and the seasonal irrigation cycles. Hence 1.7 meters of applied water was assumed reasonable.

Demand =
$$460 \times 10^6 \times 1.7 = 782 \times 10^6 \text{ m}^3/\text{yr}$$

$$q_D = 782/1744 = 0.448 \text{ m/yr}$$
 (6.13)

where \mathbf{q}_{D} is the water depth required by the demand and computed for the total area of the aquifer (as opposed to the irrigated area only).

c) Subsurface Inflow. It is mainly due to the Arroyo Ocoroni (Figure 6.3) and was estimated from water table haps.

$$Q_i = 25 \times 10^6 \text{ m}^3/\text{yr}$$

and

$$q_i = 25/1744 = 0.0143 \text{ m/yr}$$
 (6.14)

where \mathbf{q}_{i} is the depth of surface inflow, over the total aquifer area.

d) Pumping. Figures for pumping can be seen in Appendix J.

$$Q_p = 200 \times 10^6 \text{ m}^3/\text{yr}$$

and

$$q_p = 200/1744 = 0.115 \text{ m/yr}$$
 (6.15)

where q_{p} is the depth of pumped water over the total aquifer area.

e) Precipitation. An average annual precipitation of 0.45 meters was estimated for the basin; 67 percent of this precipitation falling over the irrigated land was assumed to contribute to the demand. Then

$$p = 0.45 \times 460/1744 = 0.118 \text{ m/yr}$$

and

$$\beta_1$$
 p = 0.67 x 0.118 = 0.0793 m/yr (6.16)

where p is the depth of precipitation, referred to the aquifer area.

f) Diverted Surface Water. Since no precise information existed about surface water diverted from the stream, this quantity was obtained as follows

$$q_p + q_{SD} + \beta_1 p = q_D$$

where q_{SD} is the depth of diverted surface water, over the total aquifer area. Therefore,

$$q_{SD} = q_D - q_P - \beta_1 p$$

Substituting (6.13), (6.15) and (6.16) into above equation produces

$$q_{SD} = 0.2527 \text{ m/yr}$$
 (6.17)

g) Irrigation Return Flow. A coefficient of infiltration of water applied to the irrigated land was computed as:

$$\alpha_2 = \frac{\text{water applied-consumptive use}}{\text{water applied}}$$

or

$$\alpha_2 = (1.7 - 1.0)/1.7 = 0.411$$

Then the depth of water infiltrated due to irrigation is

$$\alpha_2$$
 $q_D = 0.185 \text{ m/yr}$

Since some of the water infiltrated returns to any available surface drainage (such as the stream) it

was assumed that 55 percent of the amount of water infiltrated returned to the surface drainage system (\mathbf{C}_4) and therefore,

$$\alpha_4 \alpha_2 q_D = 0.45 \times 0.185 = 0.0829 \text{ m/yr}$$
 (6.18)

h) Infiltration from Precipitation. Here, the flow of water infiltrated into the non-irrigated area is calculated assuming a coefficient of infiltration, α_1 , of 5 percent. The depth of precipitation falling on non irrigated land is

$$p' = (1744-460) \times 0.45/1744 = 0.332 \text{ m/yr}$$

and the depth of infiltrated water is

$$p' = 0.0166 \text{ m/yr}$$
 (6.19)

i) Conveyance Losses. A coefficient of infiltration α_3 , of 10 percent, due to the conveyance losses of canals was included in the losses as follows

$$\alpha_{3} q_{SD} = 0.0253 \text{ m/yr}$$
 (6.20)

j) Evapotranspiration. This term includes losses from evapotranspiration due to phreatophytes (mainly cottonwoods along the Arroyo Ocoroni and Rio Sinaloa, see Figure 6.3). An area 130 Km long and 250 m wide was assumed to be affected by the phreatophytes. Based on an approximation of the volume density and the water consumption of cottonwoods (Robinson, 1958, p.61), a consumptive use of 1.55 meters was estimated. Therefore,

$$q_{ET} = (130 \times 0.25 \times 1.55)/1744 = 0.0289 \text{ m/yr}$$
(6.21)

where, $q_{\overline{ET}}$ is the depth of phreatophyte consumption referred to the aquifer area.

Making use of equation 6.12 and the previous terms, we obtain

$$E = 0.1102 \text{ m/yr}$$
 (6.22)

The mean water level change between September 1969 and September 1970, & h was

$$\Delta h = -0.311 \text{ m}$$
 (6.23)

A mean water level for the entire aquifer of 19.969 meters above sea level was calculated from water table maps of the studied area.

Two points should be kept in mind when computing the mean stream stage; first, downstream of the town of Guasave

(Figure 6.3), the area to the west of the river is not considered in the analysis; second, some subsurface outflow discharges to the sea. Therefore, in the computation of the mean stream stage, the length of the stream above Guasave was included twice; the length of coast was considered and at datum level. The average stream stage elevation was then 20.6 meters.

With the values of the system variables and the water balance of (6.11) the subsurface outflow constant was computed as follows

$$-0.311 \times 10^{-2} = 0.110 - 0.116 + 0.63a$$
 (6.24)

and

$$a = 4.29 \times 10^{-3} \text{ 1/yr}$$
 (6.25)

The response time (see equation 2.54) can be obtained as

$$t_h = 10^{-2} / (4.29 \times 10^{-3}) = 2.33 \text{ years}$$
 (6.26)

A characteristic length of the aquifer can be computed once the subsurface outflow constant is known (see Section 2.3). In this case, the characteristic length is 21 km. This can easily be measured from a map of the area and is strikingly the same as that obtained using the aquifer

water balance equation. This example shows how simple it is to obtain the subsurface outflow constant and to represent the system by our physical model, provided we have a clear picture of the field situation. A water balance will always be recommended as a powerful and simple tool in checking the behavior or characteristics of the physical model.

Management of the System

Plans have been made for construction of a reservoir on the Rio Sinaloa in order to control and have better use of the river. However, for best use of available water resources in the area, the conjunctive use of groundwater and surface water appears to be an advantageous alternative, and should be considered.

An aquifer, an underground reservoir built by nature and able to store, transmit and supply water, is already available. It is naturally connected to the stream, and hydraulic head differences dominate the stream-aquifer interaction. About 600 wells, approximately 120 with depth greater than 50 meters, presently extract water from the aquifer. In drought periods, the aquifer can be a reliable source of water.

Both subsystems, stream and aquifer would be operated by a central agency, charged with satisfying an estimated water demand in the "best" economic way, and with absorbing the initial costs of the irrigation and pumping facilities. No changes in the unit operational cost of the facilities,

due to operation of the system, will be considered.

Optimal decisions concerning size of the dam and its operation, diversion, and operational policies for pumping will be determined. The inputs and characteristics of the system such as the subsurface outflow constant and the availability of pumping facilities are the uncertain quantities.

In a deterministic treatment, the minimization of the discounted operational cost of the system (see, e.g., equation 3.1), including the fixed cost of the dam, is represented by an objective function such as:

$$W = \sum_{i=1}^{n} 1/(1 + r/N_S)^{i} (C_{S_{i}} D_{i-1} \gamma_{S_{i}} + C_{R_{1}} \gamma_{R_{1}} + C_{R_{1}} \gamma_{R_{1}} + C_{R_{1}} \gamma_{R_{1}}$$

$$+ C_{P_{i}} Q_{P_{i}} (Z - h_{i} + DC_{i}))$$
(6.27)

See section 3.3 and the List of Symbols for description of the variables. The decision variables are:

ratio of water diverted from the stream at time

i, to water demand at time i-1;

Size of the dam in 10⁶ m³;

ratio of water pumped out of the aquifer at time

i to amount of water stored in the aquifer at time

i time i-1.

If the demand of water and inputs of the systems are random a stochastic representation of the objective function

is the discounted expected value of cost. Following an analysis similar to that presented in Section 5.3 we obtain

Minimize
$$_{n}$$

 $E(W) = \sum_{i=1}^{\infty} (1/(1 + r/N_{S})^{i})(\mathcal{M}_{C_{S}}\mathcal{M}_{D_{i-1}})^{2} + \mathcal{M}_{C_{R}} \mathcal{N}_{R_{1}}$
 $+ \mathcal{M}_{C_{P}} AS(Z\mathcal{M}_{h_{i-1}} - \mathcal{M}_{h_{i-1}}\mathcal{M}_{h_{i}} + \mathcal{M}_{DC_{i}}\mathcal{M}_{h_{i-1}}) \mathcal{N}_{P_{i}}$
 $+ \mathcal{M}_{C_{P}} (-c_{1} f_{Q_{P}h} + c_{1}^{2} \gamma) f_{h_{i}}^{2})$ (6.28)

The constraints of the problem are given next (see Section 5.4 for development of some of the constraints).

1) The demand constraint states that the water demand in a given period \underline{i} must be smaller than or equal to the sum of the expected amount of water diverted from the stream and that pumped out of the aquifer, with a level of probability λ_4 .

$$\mu_{D_{i-1}} \gamma_{S_i} + AS \mu_{h_{i-1}} \gamma_{P_i} \ge \mu_{D_i} + x_1 \sigma_{D_i}$$
 (6.29)

2) The pumping capacity constraint says that the available pumping facilities at a time $\,\underline{i}\,$, must be greater than or equal to the expected amount of water pumped out of the aquifer, with a given probability $\,\lambda_{\,2}\,$.

AS
$$\mu_{h_{i-1}} v_{P_i} \leq \mu_{Q'_P} + x_2 \sigma_{Q'_P}$$
 (6.30)

3) The diversion facilities constraint establishes that the surface water capacity at a time \underline{i} must be greater than or equal to the expected amount of water diverted from the stream, with a given level of probability λ_3 .

$$\mu_{D_{i-1}} \chi_{S_i} \leq \mu_{Q_{SD}^{i-1}} \chi_{SD}$$
 (6.31)

4) The dam freeboard constraint says that the freeboard at time $\,\underline{\mathtt{i}}\,$ must exceed $\,\mathtt{f}_{\mathtt{i}}\,$ with probability $\,\lambda_{\,4}\,$.

$$\mathbf{\tilde{\gamma}}_{R_1} - \mathbf{\tilde{\gamma}}_{B_i} \geq r_i (\lambda_4) + f_i$$
 (6.32)

where $r_i(\lambda_4)$ is the 100. λ_4 percentile of the streamflow Q_{ST} and f_i is the considered freeboard volume.

To obtain equation 6.32, a new decision variable \mathcal{X}_{B_i} (see Section 3.3) is introduced through a linear decision rule (Revelle et.al., 1969) which is

$$Q_{ou_{i}} = S_{i-1}' - \gamma_{B_{i}}'$$
 (6.33)

is expressed in terms of the reservoir storage during the previous time period $S_{i-1}^{'}$. The continuity equation for the reservoir is

$$S_{i}^{t} = S_{i-1}^{t} - Q_{ou_{i}} + Q_{ST_{i}}$$
 (6.34)

Substituting (6.33) into (6.34) produces

$$\mathbf{S_i'} = \mathbf{N}_{\mathbf{B_i}} + \mathbf{Q}_{\mathbf{ST_i}} \tag{6.35}$$

and similarly

$$S_{i-1}^{i} = \chi_{B_{i-1}} + Q_{ST_{i-1}}$$
 (6.36)

Introducing (6.36) into (6.33), we obtain

$$Q_{ou_{i}} = \chi_{B_{i-1}} - \chi_{B_{i}} + Q_{ST_{i-1}}$$
 (6.37)

which gives us an expression of the release from the dam $\mathbf{Q}_{ou} \text{ at time } \underline{\mathbf{i}} \text{ , based on the stream flow } \mathbf{Q}_{ST} \text{ at time i-1.}$

In a deterministic representation of the freeboard constraint

$$\gamma_{R_1} - s_i \ge f_i \tag{6.38}$$

Substituting equation 6.35 into 6.38, we have

$$\mathbf{\tilde{I}}_{R_1} - \mathbf{\tilde{I}}_{B_i} - f_i \ge Q_{ST_i} \tag{6.39}$$

If the streamflow is random, then equation 6.39 can be written in terms of a probability statement, as follows:

$$P(Q_{ST_{\underline{i}}} \leq \gamma_{R_{\underline{i}}} - \gamma_{R_{\underline{i}}} - f_{\underline{i}}) \geq \lambda_{4}$$
 (6.40)

For mathematical programming it is better to represent it

as a certainty equivalent (equation 6.32).

5) The stream requirement constraint, states that the streamflow downstream of the studied region must be greater than or equal to a given senior right K $_1$ with a probability λ_5 .

$$w_0 \mathcal{N}_{R_1} - \mathcal{N}_{B_1} - \mu_{D_1} \mathcal{N}_{S_1} \ge aA(\mu_H - \mu_{h_1}) + K1_1$$
 (6.41)

is an equation for time i = 1, and

$$\chi_{B_{i-1}} - \chi_{B_{i}} - \mu_{D_{i-1}} \chi_{S_{i}} \ge aA(\mu_{H} - \mu_{h_{i}}) - r_{i-1}(1-\lambda_{5}) + K1_{i}$$
(6.42)

is a constraint for time i \geq 2 where $w_0 \bigvee_{R_1}$ is the initial storage of the reservoir.

6) The dam storage constraint is defined as the storage at the dam which must be greater than a minimum storage with a probability λ_6 .

$$w_{\rm m} \gamma_{\rm R_1} - \gamma_{\rm B_i} \leq r_{\rm i} (1 - \lambda_6) \tag{6.43}$$

where $w_m \gamma_{R_1}$ is the minimum storage that the dam must have and $r_1(1-\lambda_6)$ is the 100.(1- λ_6) percentile of the stream-flow.

The deterministic constraint can be written as

$$s_i' \geq s_{min}'$$

Then, making use of equation 6.35, we obtain

$$Q_{ST_{i}} \ge w_{m} \gamma_{R_{1}} - \gamma_{B_{i}}$$
(6.44)

where $S_{\min}^{i} = w_{m} \gamma_{R_{1}}^{i}$. Now, if $Q_{ST_{i}}^{i}$ is random, we have

$$P(Q_{ST_{i}} \geq w_{m} \gamma_{R_{1}} - \gamma_{B_{i}}) \geq \lambda_{6}$$

or

$$1 - F_{Q_{ST_{i}}} (w_{m} \gamma_{R_{1}} - \gamma_{B_{i}}) \ge \lambda_{6}$$
 (6.45)

in which F_{QST_i} is the cumulative distribution of the streamflow. Equation 6.45 in its certainty representation becomes equation 6.43.

At this point, it is convenient to mention that the levels of probability λ 's are selected by the designer according to available information and future estimations about the system operating policy.

A well drawdown correction DC was included in the objective function to simulate the difference between the average water level in the aquifer and the average water level at the pumping wells. Equation 2.49, previously developed, was applied to obtain the above correction. Well losses were not included in the analysis.

A mean influence area of the wells of 1.45 km² was obtained from a map showing the location of the wells in

the studied area. This value is based on an average distance between wells, the irrigated land area and the number of wells significantly deep (depth greater than 25 meters).

The well drawdown correction based on (2.49) is

$$\mathbf{s}_{\mathbf{w}} - \overline{\mathbf{s}} = (Q / 2\pi T)(p_{\mathbf{D}} - \overline{p}_{\mathbf{D}}) \tag{6.46}$$

where Q is an average instantaneous pumping, obtained by assuming that two thirds of the number of pumping wells, WN, were pumping half of the year; it is related to the annual pumping of the area $\, Q_p \,$, as follows.

$$Q_p = 2/3 \times 1/2 \times WN \times Q_w \times 31.54$$
 (6.47)

Statistics

A gamma distribution was selected to represent the streamflow because of its non-symmetry (Fiering, 1971, p.35). The gamma cumulative distribution (Mood et.al., 1963, p.128) or incomplete gamma function is given by

$$F(x) = \int_{0}^{x} t^{\alpha} \exp(-t/\beta) dt/\alpha! \beta^{\alpha+1}$$
 (6.48)

which can be transformed to

$$P(a, x') = F(x) = 1/\Gamma(a) \int_{0}^{\beta x} t_1^{a-1} \exp(-t_1) dt_1$$
 (6.49)

where, Γ (a) = α !, α = a-1 and $x = \beta x'$

Equation 6.49 can be related to the chi-square distribution if <u>a</u> is an integer (Abramowitz, et.al., 1964, p.941) as follows,

$$P(a, x') = \chi(a, x') / \Gamma(a) = P(\chi^2/\gamma)$$
 (6.50)

in which, V = 2a and $\chi^2 = 2x'$ (chi-square distribution), and

$$\Gamma$$
 (a, x')/ Γ (a) = Q (χ^2/γ) (6.51)

where

$$1 - P(\chi^2/\gamma) = Q(\chi^2/\gamma)$$
 (6.52)

A table of $Q(\chi^2/\gamma)$ can be found in Abramowitz (1964, p. 978). Two parameters \underline{a} and $\underline{\beta}$ define the shape of the gamma distribution and are related to the statistics of the streamflow as follows:

$$\mu = \beta a$$

$$\sigma^2 = \beta^2 a^2$$

The assumed values of μ and σ were 1334 x 10⁶ m³/yr and 544 x 10⁶ m³/yr, respectively. Therefore,

$$a = 6$$

$$\beta = 222.5$$

$$V = 12$$

For a value of probability of F(x) = 0.75 we obtain $\chi^2 = 14.85$ from the tables of χ^2 . Since

$$\chi^2 = 2x/\beta$$

then

$$x = r(0.75) = 1650 \times 10^6 \text{ m}^3/\text{yr}$$

where r(0.75) is the 75 th percentile of the streamflow. Repeating the procedure for F(x) = 0.25, we have

$$x = r(0.25) = 940 \times 10^6 \text{ m}^3/\text{yr}$$

where r(0.25) is the 25 $\frac{th}{}$ percentile of the streamflow.

The cross correlation function of pumping and the head of the aquifer for zero lag(computed by equation 4.28) was -0.74.

Parameters Needed by the Models

The amount of information required by the models under a stochastic formulation increases substantially compared to a deterministic formulation. The values of the parameters

required for the Rio Sinaloa problem are given in Table 6.3.

A flow chart depicting the iterative procedure for solving the Rio Sinaloa management problem under random conditions is shown in Figure 6.5. The listing of the program is given in Appendix I.

Results

Figure 6.6 summarizes certain final results obtained from the application of the proposed models to the study area. These results are: the optimal operation of the system, the optimal size of the dam χ_{R_1} and the expected value of the operational cost of the system (which includes the cost of the dam). Dam, surface water diversion facilities and pumping facilities are those items optimally operated. Also shown in Figure 6.6 are: the expected water level in the aquifer, the stream-aquifer flow and the 75 $\frac{th}{th}$ percentile of the demand.

Examination of the results shows that pumping was always at its maximum capacity throughout the entire horizon, since pumping was cheaper than diversion of water from the stream. Therefore, the amount of surface water was enough to satisfy the demand unfulfilled by pumping, and at the same time absorbed any trend or random fluctuation included in the demand.

An average well drawdown correction of about 7.29 m was found by using equation 2.49.

Because of the increasing water demand and the particular

TABLE 6.3 Parameter Values for the Rio Sinaloa Problem.

N	Design horizon	20 years
N_S	Number of seasons per year	1
A	Aquifer area	1744 Km ²
T	Transmissivity	$0.02 \text{ m}^2/\text{sec}$
S	Storage coefficient	0.01
ß	Dimensionless constant, used to	
•	compute the subsurface outflow	
	constant	3.0
ľ	Characteristic length	21 Km.
Z	Ground surface level	350 m.
H	Mean stream water level	338.63 m.
h _o	Initial water level	338 m.
WN	Number of wells	314
${\tt r}_{\tt w}$	Average well radius	0.254 m.
Aw	Average influence area of a well	1.45 Km ²
K1 _i	Downstream quota	0.0
F1 _i	Dam freeboard	$200 \times 10^6 \text{ m}^3$
\mathbf{w}_{m}	Minimum dam storage fraction	0.4
Wo	Initial dam storage fraction	0,6
0 ₁	Fraction of precipitation that	
	actually reaches the water table	0.1845
d 2	Fraction of water applied that	
	infiltrates	0.411
α_4	Fraction of water infiltrated that	
	actually recharges the aquifer	0.45

TABLE 6.3 (Continued)

β_1	Fraction of precipitation that	
	helps to satisfy the demand	0.422
ET	Expected value of evapotranspi-	
	ration	$50.4 \times 10^6 \text{ m}^3/\text{yr}$
P	Expected value of precipitation	785 x 10 ⁶ m ³ /yr
$\mathtt{Q}_{\mathbf{i}}$	Expected value of subsurface	
	inflow	$25 \times 10^6 \text{ m}^3/\text{yr}$
/ y	Autocorrelation function of the	
	inputs for lag 1	0.7
$f_{\mathtt{Q_ph}}$	Cross correlation function of	
	pumping and head for lag 0	-0.74
	Probability level to satisfy	
	the constraints	0.75
r (0.75)	75 percentile of the streamflow	1650 x 10 ⁶ m ³ /yr
r(0.25)	25 percentile of the streamflow	940 x 10 ⁶ m ³ /yr
$\mu_{\mathtt{Q}_{\mathtt{P}_{\mathtt{i}}}}$	Expected value of capacity of	
Pi	the pumping facilities	$470 \times 10^6 \text{ m}^3/\text{yr}$
M _{Q'SD}	Expected value of capacity of	
"SD _i	the surface water facilities	1500 x 10 ⁶ m ³ /yr
$\sigma_{\scriptscriptstyle \mathrm{D}_{\mathtt{i}}}$	Standard deviation of the demand	$200 \times 10^6 \text{ m}^3/\text{yr}$
σ _{Q_D}	Standard deviation of the	
ri.	pumping facilities	$70 \times 10^6 \text{ m}^3/\text{yr}$
$\sigma_{\dot{Q}_{gn}}$	Standard deviation of the	
Q _{SD_i}	surface water facilities	300 x 10 ⁶ m ³ /yr
$\sigma_{\rm a}$	Standard deviation of the	. •
	subsurface outflow constant	0.25 a

TABLE 6.3 (Continued)

o y	Sta	andar	d devia	tion (of the in	put	$8.07 \times 10^{-3} \text{ m/yr}$
r	Non	inal	rate of	finte	erest		5%
μ_{c_s}	Exp	ecte	d stream	n dive	ersion co	sts	\$6000/10 ⁶ m ³
$\mu_{c_{D}}$	Exp	ecte	d dam w	nit co	ost		\$24444/1 0 ⁶ m ³
μ _{c_R} μ _{c_P}	Exp	ecte	d pumpi	ng cos	sts		\$63.8/10 ⁶ m ⁴
μ_{D_i}	Exp	ected	l water	demar	nd in 10^6	m 3	
4.							
i	$\mu_{\scriptscriptstyle \mathrm{D_i}}$	i	$\mu_{\scriptscriptstyle \mathbb{D}_{\mathbf{i}}}$	i	$\mu_{\scriptscriptstyle \mathrm{D_i}}$	i	$\mu_{_{\mathrm{D_{i}}}}$
i 1	Д _Д 800	i 6	Д _Д	i 11	加 _{D₁}	i 16	从 _{D_i} 1050
	•			i 11 12	ル _{D_i} 1050 1050		
1	800	6	1000		-	16	1050
1 2	800 850	6 7	1000	12	1050	16 17	1050 1050

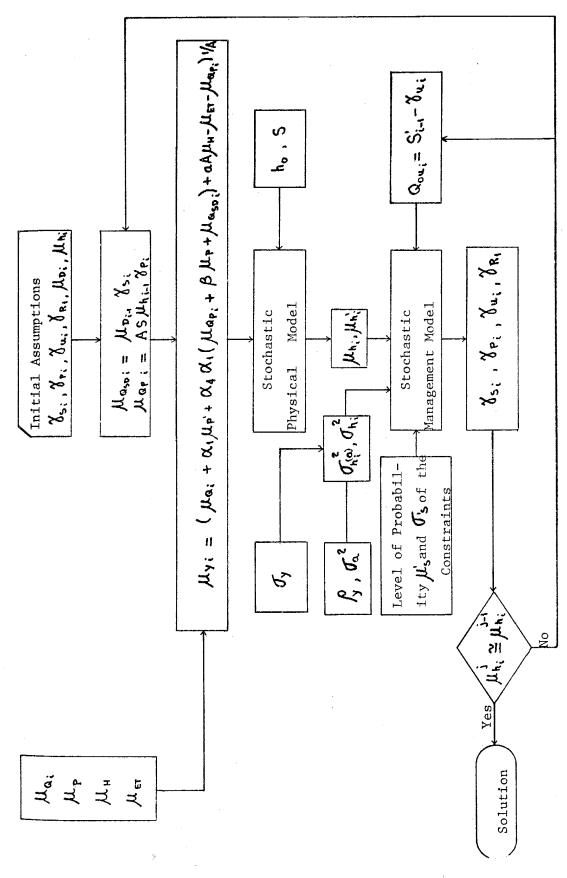


Fig. 6.5 Iterative procedure used to solve the Rio Sinaloa management problem.

Objective function OF = \$113,224,000 Reservoir volume $7_{R_1} = 1915 \times 10^6 \text{ m}^3$ Std. dev. of subsurface outflow constant Probability level $7_{R_1} = 0.25 \text{ a}$ $7_{R_2} = 0.75$

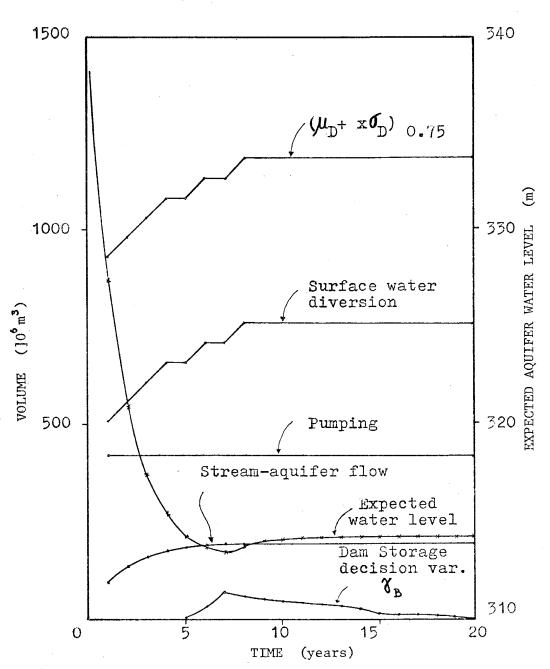


Fig. 6.6 Operational scheduling and aquifer behavior for probability level λ = 0.75 .

combination of physical aquifer properties, the aquifer behaved such that the expected water levels experience a fast drop in the first five years of operation of the system. After this large initial decline of the water table, an equilibrium is rapidly reached because irrigation return flow and stream-aquifer flow increase. The amount of increase depends on the demand and on the stream-aquifer head difference.

The results of several alternatives are summarized in Table 6.4. Note that alternative <u>B</u> shows a 19% increase of the objective function relative to the deterministic case (alternative A), when the coefficient of variation of the demand is approximately 0.2 (see Table 6.3). This increase is comparable to that found in the Maddock problem under similar conditions (see Figure 6.1).

A graph of the variability of the water level \underline{h} in the aquifer is presented in Figure 6.7. Shown is the result when the subsurface outflow constant \underline{a} is a deterministic quantity ($\sigma_a = 0$) and the randomness is due to the inputs to the system. Figure 6.7 also shows the variability of \underline{h} when \underline{a} is treated as a random variable with a standard deviation of 0.25 \overline{a} . A sum of both variance $\sigma_h^2(\overline{a})$ and $\sigma_h^2(a)$ produces the total variance of the system. From Figure 6.7 it is seen that both cases behave in a similar manner, increasing up to a steady state value. However, $\sigma_h(a)$ has higher values than $\sigma_h(\overline{a})$ and takes almost twice the time to show its total effect. This implies that an uncertainty in \underline{a} due to inadequate field information and

TABLE 6.4 Summary of the Results Obtained from Several Alternatives for the Rio Sinaloa.

		ALTERN	ALTERNATIVES	
	A	В	ט	D
~	deterministic	0.75	0.75	0.75
ر "		0.0	0.25a	æ
$\mu_{c_s}(\$/10^{m_3})$	0009	0009	0009	0009
$\mu_{c_{p}}(\$/10^{6}m^{3})$	63.8	63.8	63.8	63.8
OF(\$)	95,054,000	112,993,000	113,224,000	116,703,000
$a_{R_1(10^6 \text{ m}^3)}$	1534	1915	1915	1915
		ALTERNATIVES	TIVES	
	H	<u> </u>	ტ	Н
γ	0.75	6.0	6.0	0.75
Qa	0.25a	0.25a	0.25a	0.25a
$\mu_{c_{S}}$ (\$/10 m)	3000	0009	3000	3000
$\lambda c_{\rm p} (\$/10^6 \text{m}^3)$	63.8	63.8	63.8	0.06
OF(\$)	87,090,000	1,325,252,000	1,292,978,000	118,942,000
8 _{R(10⁶m³)}	1915	51,054	51,054	1915

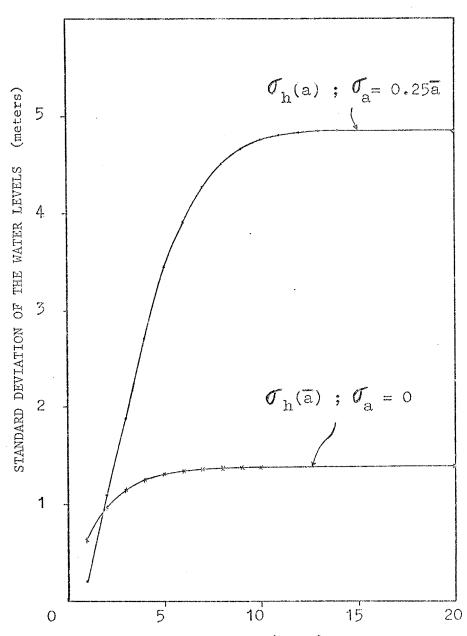


Fig. 6.7 Variability of aquifer water levels; $\sigma_h(a)$ represents uncertainty when the subsurface outflow constant is deterministic, the mean $(a = 4.29 \times 10^{-3} \text{ yr}^4)$; $\sigma_h(a)$ represents uncertainty when the subsurface outflow constant is considered a random variable with $\sigma_a = 0.25a$.

the random behavior of the system properties such as the aquifer transmissivity, increases considerably the uncertainty associated with water levels.

Sensitivity Analysis

In order to see the effect of randomness on the operation of the system, the deterministic case was run and its solution is presented as Figure 6.8. We note that both cases, deterministic and random, behave in a very similar manner; but the system under fully known conditions is cheaper to operate and the size of the dam is almost 25% smaller than in the situation where uncertainties dominate the picture.

The effect on the objective function caused by uncertainty in the subsurface outflow constant is shown in Figure 6.9. However, it should be noted that this behavior depends on the parameters of the stream-aquifer system through the coefficient part of the variance term in (6.28). In this case the effect on the objective function which is caused by uncertainty in the subsurface outflow constant is small (Figure 6.9).

The nonlinear objective function (quadratic in pumping) was solved by the proposed iterative procedure (see, Section 3.3), in which a standard linear programming package using a simplex algorithm (Kuester and Mize, 1973, p.10) was used. If reasonable initial conjectures of the value of the variables were supplied to the models, only two or three

Objective function Reservoir volume OF = \$95,054,000 $% \chi_{R_1} = 1534 \times 10^6 \text{ m}^3$

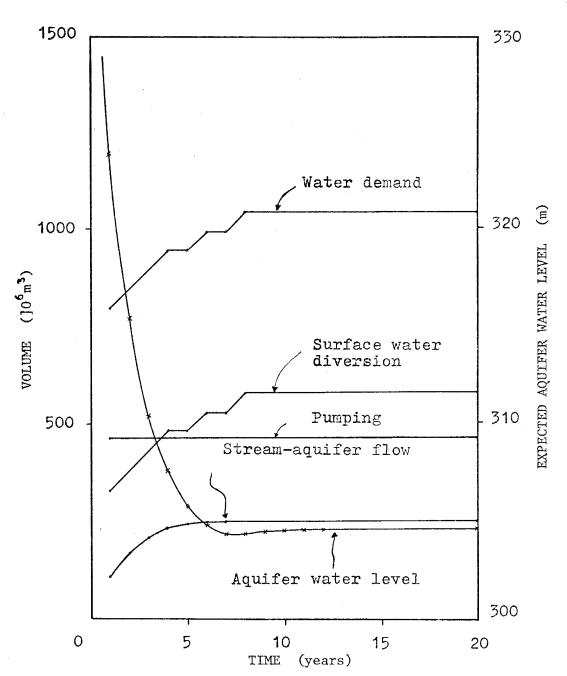
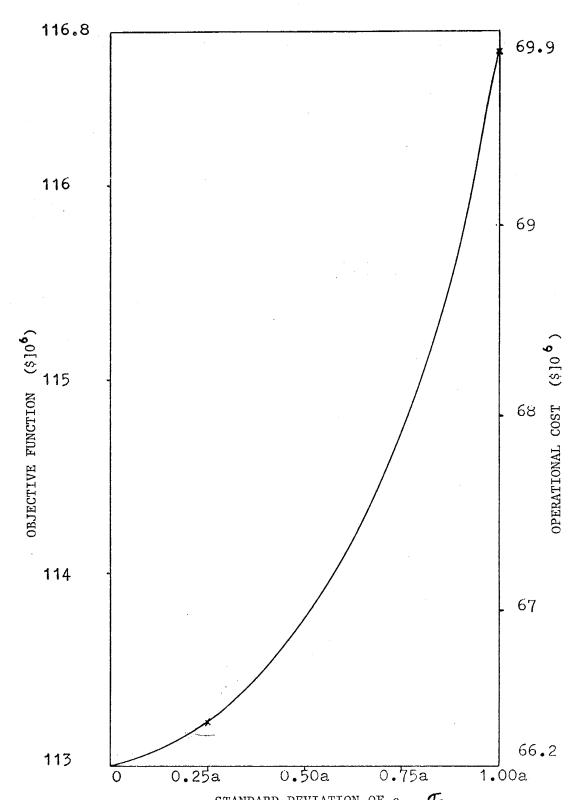


Fig. 6.8 Operational scheduling and aquifer behavior of the deterministic case.



STANDARD DEVIATION OF \underline{a} , σ_a Fig. 6.9 Variation of the objective function value and operational cost of the system as a function of uncertainty in the subsurface outflow constant \underline{a} for a level of probability λ = 0.75 .

iterations in an IEM 360 model 44 were required to solve the Rio Sinaloa management problem. Less than 150 k bytes of main memory were utilized.

Convergence problems were found when the cost of diverting water from the stream $Q_{\rm SD}$, and of pumping from the aquifer $Q_{\rm p}$ were approximately equal. The above problems are illustrated in Figure 6.10 and 6.11; Figure 6.10 shows the results of two iterations (subindices 1 and 2); Figure 6.11 presents the average of iterations 1 and 2 (subindex 3) as the initial assumption of the next iteration (subindex 4). Even though both objective functions are almost identical in Figure 6.11, the policies appear very different. No procedure was found to solve this convergence problem. The application of any of the two schedulings found by the models (Figure 6.11) would of course solve the management problem, since their cost is the same. The actual selection of a operational scheme would depend on factors other than those economic factors introduced in this management model.

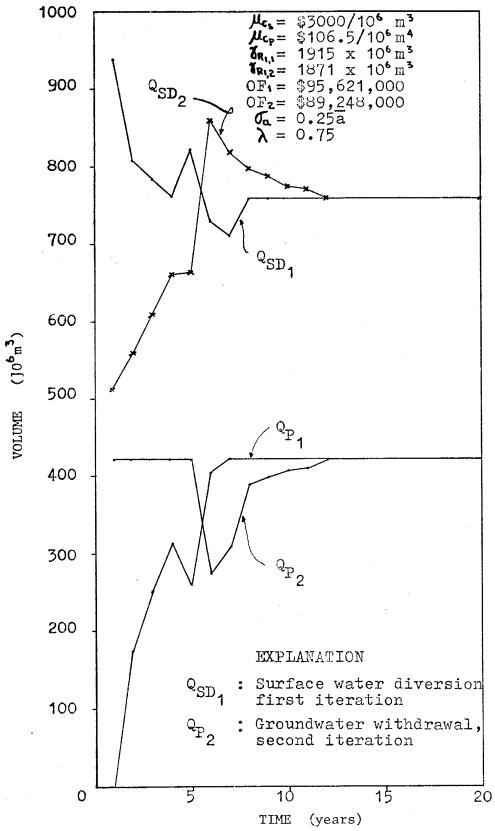


Fig. 6.10 Representation of the convergence problem when cost of surface water diversion and pumping are nearly the same.

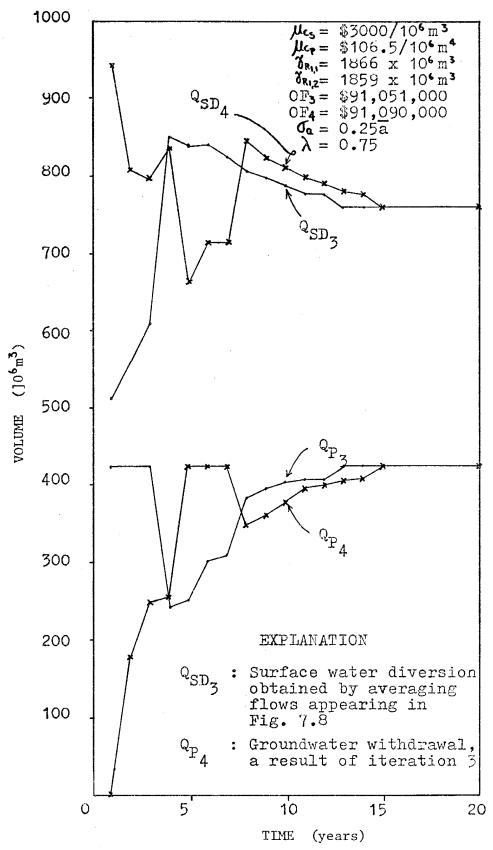


Fig. 6.11 Effect of averaging on convergence.

CHAPTER 7 SUMMARY AND CONCLUSIONS

Summary

A development of simple models to represent a streamaquifer system and its optimal operation under situations involving uncertainties was the main concern of the study. Only physical and economic variables were considered in this work.

A lumped parameter model composed of an aquifer water balance and a linear stream-aquifer flow relationship is proposed for modeling the system. This model is not offered as a substitute for distributed models but as a simple reliable and economical alternative suitable for initial evaluation of systems with only limited field data. The stream-aquifer flow is governed by the subsurface outflow constant and a head difference between stream and aquifer. The subsurface outflow constant was found to be dependent on the average transmissivity of the aquifer, a characteristic length of the aquifer and a dimensionless constant. The effect of system properties and input characteristics on the value of the dimensionless constant was studied.

The solution of the physical or lumped parameter model is given by a convolution integral which accounts for past inputs to the system. Since the lumped model provides an average water level \underline{h} , an improvement was made by introducing a correction which allows the physical model

to compute the head at the pumping wells. An important concept included in the analysis is the response time of the stream-aquifer system $\,t_h$; it is a measure of the time required for the system to respond to inputs, and is related to the subsurface outflow constant and an average storage coefficient of the aquifer.

A management model was developed which minimizes the discounted operational costs of a stream-aquifer system. It is linked to the physical model by the average head of the aquifer. A simplification of the objective function was obtained by computing the average head of the aquifer outside of the management model, not including any past input to the system in the objective function. Taking advantage of this link between the models, an iterative procedure was developed for solving the quadratic optimization problem with a standard linear programming package. Linear decision rule were used to define the decision variables. By making present decisions based on previous information the operation of the system was made more dynamic.

A further step in the analysis was made by considering random natural inputs and a random demand. A stochastic differential equation with a random forcing function represented the physical model. The ensemble average, the variance, and the autocovariance of the aquifer head were computed. Using a conditional probability approach, the variance of the random subsurface outflow constant was included in the problem; a variance of the head as a

function of the variance of the inputs and of the subsurface outflow constant is computed. It was found that the pumping cost depends on the interaction between the head and pumping. Hence, spectral analysis was used to find a cross correlation coefficient between these quantities. The minimization of the discounted expected value of cost is the representation of the objective function in a stochastic system. Chance constraints which allow for satisfaction of the constraints with a given probability level were used in the stochastic management model. Nonstationary demands of water are easily represented by these types of constraints.

To examine the reliability of the proposed models a comparative test was made with a study by Maddock (1974), which includes a distributed aquifer model coupled with a stochastic management model. From the comparison, similar operating rules were found and a sensitivity analysis showed that Maddock's results were a particular case of a more general problem treated by our stochastic management model. The increase in the objective function with increasing variance of the demand was in agreement with that found by Maddock. However, some differences in the objective functions were found because of the local effect on the water table of only two pumping wells. The iterative procedure as well as the link between the physical and management model proved to work satisfactorily. An advantage of our models is the small number of terms in the objective function produced by computing the mean water level of the aquifer outside of

the management model.

The proposed model was applied to a basin in northwestern Mexico. The adaptability to a different situation was tested and a sensitivity analysis performed. Optimal decisions about the size and operation of a projected dam were made. The operational scheduling of water diverted from the stream and water pumped out of the aquifer were obtained to satisfy a random demand. Since the groundwater costs less than surface water, all random fluctuations in the demand of water were absorbed by the surface water. The variance of the random levels in the aquifer including a random or a deterministic subsurface outflow constant, showed similar patterns; it increased up to a steady state value. The variance of the water levels was larger when affected by a random subsurface outflow constant. Comparison of a deterministic and a stochastic case showed that for a deterministic case operational costs are less and a smaller dam is required. The study of the sensitivity of the objective function to uncertainties in the subsurface outflow constant showed that they had little effect on the discounted expected value of cost. Convergence problems in the iterative procedure were found only when the surface water cost and pumping cost were similar. In this case two different policies produced almost identical discounted cost. Otherwise, with reasonable initial assumptions, only two or three iterations where required to converge to a reasonably accurate solution.

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Conclusions

The following conclusions were obtained

- 1. In regional studies the physical model developed in this work is very simple and reliable in its usage; it is capable of accounting for local drawdown at the wells, stream-aquifer interaction, and can easily be coupled to a management model.
- 2. The subsurface outflow constant is a very useful concept in modeling a stream-aquifer system. It groups parameters such as the transmissivity of the aquifer, a characteristic length of the system, and a dimensionless constant which depends on several system properties and input characteristics.
- 3. A simple link was made between a physical and a management model allowing us to develop an iterative procedure for solving a nonlinear optimization problem with a standard linear programming package.
- 4. In the stochastic management model dynamics were introduced with the use of linear decision rules to define decision variables and more generality was obtained with the use of chance constraints.
 A nonstationary water demand was easily represented by using chance constraints.
- 5. Good agreement was obtained between the results of the proposed model and a previous study by Maddock

- (1974) based on a distributed aquifer model and quadratic programming. The operating rules and the sensitivity to demand uncertainty were practically the same. The value of the objective function obtained from the lumped parameter model was slightly larger; the difference is thought to be related to the interaction between the stream and the local cones of depression of the two wells.
- 6. The versatility of the developed model was demonstrated by applying it in the Rio Sinaloa study area in northwestern Mexico. This was a regional study involving over 400 km² of land irrigated by hundreds of wells and by diversion from a stream. The optimal operational scheduling of conjunctive use of surface water and groundwater and the optimal size of a surface reservoir were obtained under random conditions.
- 7. The effect of uncertainty on the management of a stream-aquifer system is an important factor to be considered; under random conditions the size of the surface reservoir is larger and the cost of operation is greater than under a deterministic situation. The choice of the level of probability in the chance constraints is an important managerial decision because the expected value of the discounted cost is significantly affected by the level of probability. Uncertainty of the water demand

produced a larger increase in the operational cost than uncertainty in aquifer parameters. However, the effect of uncertainty on the aquifer water levels was found to be dependent on the system properties and input randomness.

Recommendations

- 1. Work remains to be done on the determination of the subsurface outflow constant when the aquifer is asymmetric with respect to the stream.
- 2. Different types of boundaries and shapes of well influence areas need to be used and analysed.
- 3. In managerial studies of conjunctive use of groundwater and surface water more emphasis should be
 given to the statistics of the economic variables
 than the statistics of the properties of the streamaquifer system.
- 4. More study related to the convergence problem of the iterative procedure is needed.
- 5. Another approach to include a random subsurface outflow constant in the physical model, can be used: it consists of solving a stochastic differential equation with a random coefficient and a random forcing function.

APPENDIX A Computation of the Subsurface
Outflow Constant for the Unsteady Case

The equation governing the flow is

$$\alpha^2 \delta^2 h / \delta x^2 + \epsilon = \delta h / \delta t$$
 (A.1)

where $\alpha^2 = T/S$ is the hydraulic diffusivity of the aquifer, and

$$\epsilon = \epsilon_0 ; t < 0$$

$$\epsilon = 0 ; t > 0$$

The initial and boundary conditions are

t
$$\langle 0 \rangle$$
; $h - H = (2I - x) \epsilon_0 x/2T$ (A.2)

$$x = 0$$
 ; $h - H = 0$ (A.3)

$$x = L$$
 ; $\partial(h - H)/\partial x = 0$ (A.4)

The method of separation of variables is used to solve (A.1) satisfying the initial and boundary conditions. The variable h - H is used throughout the analysis.

Let

$$h - H = X(x)T(t) \tag{A.5}$$

Substituting the above expression into (A.1) produces

$$\alpha^2 x''/x = T'/T$$

Now, let

$$\alpha^2 x''/x = -p^2 \tag{A.6}$$

and

$$T'/T = p^2 \tag{A.7}$$

Solving (A.6) and (A.7) and substituting into (A.5) we have

$$h - H = \exp(-p^2 t)$$
 (A cos px/ α + B sin px/ α) (A.8)

where \underline{A} and \underline{B} are constants of integration, which are obtained by using (A.3) and (A.4). Now (A.8) may be transformed into

$$h - H = B \exp((-m \pi \alpha/2L)^2 t) \sin(m \pi x/2L)$$
 (A.9)

In order to satisfy the initial condition (A.2)

$$h - H = \sum_{m=1,3,5,...}^{\infty} A_m \exp((-m\pi\alpha/2L)^2 t) \sin(m\pi x/2L) (A.10)$$

where

$$A_{m} = 1/L \int_{0}^{2L} f(x) \sin(m\pi x/L) dx$$

If

$$f(x) = (2L - x) \in_{0} x/2$$

then

$$A_{m} = (1 - \cos m \pi) 8 \in L/T m^{3} \pi^{3}$$
 (A.11)

Equations A.10 and A.11 are the solutions of (A.1) satisfying the initial and boundary condition.

The average head in the aquifer can be obtained by

$$\overline{h} = 1/2L \int_{0}^{2L} h \, dx \qquad (A.12)$$

Substituting (A.10) into (A.12) we get

$$\overline{h} - H = \sum_{m=1}^{\infty} A_m \exp((-m \pi/2L)^2 Tt/S) (1-\cos m \pi)/m$$
(A.13)

since

$$q = T/L (3 \overline{h}/3 x) |_{x = 0}$$
 (A.14)

we can find that

$$q = \sum_{m=1}^{\infty} A_m \exp((-m \pi/2L)^2 Tt/S) (Tm \pi/2L^2)$$
 (A.15)

Both Venetis (1969) and Kraijenhoft Van de Leur (1958) show that the terms in the series in (A.13) for m > 1 become very small relative to the first harmonic when time increases. Retaining only the m = 1 term

$$q = A_1 \exp(-\pi^2 Tt/4S) (T\pi/2L^2)$$
 (A.16)

and

$$\bar{h} - H = (A_1 2/\pi) \exp(-\pi^2 Tt/4S)$$
 (A.17)

Since

$$q = a (\overline{h} - H) \tag{A.18}$$

then

$$a = T \pi^2 / 4L^2 \tag{A.19}$$

which is the subsurface outflow constant for the unsteady case, with an initial condition equal to the steady state head solution.

APPENDIX B Computation of the Subsurface
Outflow Constant for a Clogged Stream

The differential equation that governs the flow under steady flow conditions is

$$T d^2h/dx^2 = 0 (B.1)$$

with boundary conditions

$$x = 0$$
 ; $dh/dx = 0$

$$x = L$$
 ; $h = h_0$

The solution of the boundary problem is

$$h = (L^2 - x^2) \in /2T + h_0$$
 (B.2)

Since the flow is steady and the average water level is located at 2/3 of the maximum water level difference, because the shape of the water table is parabolic,

$$q = a (\overline{h} - h_0)$$
 (B.3)

where $a = 3T/L^2$. Analogous to (B.3), we find an expression for the flow passing through the semipermeable layer (see Fig. 2.8)

$$q = a_c (\overline{h} - H)$$
 (B.4)

where a_c is the subsurface outflow constant which includes the clogging effect. Therefore

$$a_c = q (\overline{h} - h_0 + \Delta h)^{-1}$$
 (B.5)

where, $\Delta h = h_0 - H$. Applying Darcy's law at x = L

- T dh/dx =
$$K_s$$
 (h_o + H) Δ h/2d = ϵ L (B.6)

If

$$(h_0 + H)/2 \cong H$$

and if the flow is steady, we obtain

$$\Delta h \cong qLd/HK_s$$
 (B.7)

Substituting (B.3) and (B.7) into (B.5), produces

$$a_c = 3T/L^2(1 + 3Td/HK_sL)$$
 (B.8)

or

$$a_c = a/(1 + 3Td/HK_sL)$$
 (B.9)

A further simplification gives

$$a_c = a/(1 + 3B^2/HL)$$
 (B.10)

where \underline{B} is the leakage factor (Davis and De Wiest, 1967, p.225).

APPENDIX C Details on the Computation of the Subsurface Outflow Constant for Converging Flow

The equation governing the flow under steady conditions and as shown in Figure 2.6 is

$$1/r (d(Tr dh/dr)/dr) = -\epsilon$$
 (C.1)

where T is a constant. The boundaries conditions are

$$r = R_2$$
 , $dh/dr = 0$

and

$$r = R_0$$
, $h = H$

The solution of (C.1) is

$$T(h - H) = (R_0^2 - r^2)\epsilon/4 + (ln (r/R_0))\epsilon R_2^2/2$$
 (C.2)

The mean water level in the aquifer is

$$\overline{h} - H = 1/(R_2^2 - R_0^2) \pi \int_{R_0}^{R_2} (h - H) 2 \pi r dr$$
 (C.3)

Let

$$dr^2 = 2r dr (C.4)$$

and

$$r \ln(r/R_0)dr = 1/4 \ln(r/R_0)^2 dr^2$$
 (C.5)

Making use of (C.4) and (C.5) and substituting (C.2) into (C.3), we obtain

$$T (\overline{h} - H) = \epsilon (R_0^2/4 - (R_2^2 + R_0^2)/8 + R_2^4 \ln(R_2^2/R_0^2)/4 (R_2^2 - R_0^2) - R^2/4)$$
(C.6)

If $\delta = R_0/R_2 << 1$, we obtain

$$(\overline{h} - H) = ((1 + 2 \delta)(-\ln \delta)/2 - 3(1+2 \delta)/8) \in L^2/T$$
(C.7)

Since

$$q = \epsilon = a(\overline{h} - H) \tag{C.8}$$

substitute (C.7) into (C.8), to get

$$a = (1/(1 + 2 \delta)) ((-\ln \delta)/2 - 3/8))T/L^2$$
 (C.9)

APPENDIX D Effect of Different Aquifer
Properties in Individual Segments of
a Stream-Aquifer System

Let us start by trying to compute a subsurface outflow constant of an aquifer divided into two parts by a stream.

The equations governing the flow at each aquifer cell (see Section 2.2) are:

$$S_1 dh_1/dt + a_1h_1 = y_1$$
 (D.1)

and

$$S_2 dh_2 / dt + a_2 h_2 = y_2$$
 (D.2)

Multiplying both sides of (D.1) and (D.2) by the aquifer cell areas $\,{\rm A}_1$ and $\,{\rm A}_2$, respectively and rearranging the equations, we obtain

$$A_1(dh_1/dt + h_1/t_{h_1}) = y_1A_1/S_1$$
 (D.3)

and

$$A_2(dh_2/dt + h_2/t_{h_2}) = y_2A_2/S_2$$
 (D.4)

where the response time of cell 1 is $t_{h_1} = S_1/a_1$ and the response time of cell 2 is $t_{h_2} = S_2/a_2$. Adding (D.3) and

(D.4) and dividing by $A = A_1 + A_2$,

$$d/dt (A_1h_1 + A_2h_2)/A + (A_1h_1/t_{h_1} + A_2h_2/t_{h_2})/A$$

$$= (y_1A_1/S_1 + y_2A_2/S_2)/A$$
 (D.5)

An equation for the entire aquifer might be

$$d \overline{h}/dt + \overline{h}/t_h = \overline{y}$$
 (D.6)

where the overbars mean weighted averages with respect to the areas. However, (D.6) is not be found unless $t_{h_1} = t_{h_2} = t_h \quad \text{and} \quad S_1 = S_2 \;, \quad \text{i.e.,} \quad a_1 = a_2 \;. \text{ This last case might represent an aquifer symmetric to the stream or a combination of the transmissivity <math>\underline{T}$ and characteristic length \underline{L} , such that the $\underline{T}/\underline{L}^2$ ratio were the same (see equation 2.15). Therefore in order to represent the streamaquifer system by only one subsurface outflow constant \underline{a} , the response times of each cell must be equal as well the storage coefficient \underline{S} . The reason for this restriction is the nonlinear relationship between the aquifer head and the response time. If the parameter \underline{a} and \underline{S} are significantly different it may be necessary to use more than one cell to represent the physical model.

APPENDIX E Proof that the Use of Average
Heads in the Outflow Equation is Valid

To demonstrate that the use of average heads is correct in the outflow equation, we shall show that the average of any departure from the mean head in the aquifer and in the aquifer outlet is zero.

Let us consider an aquifer consisting of a sector of a circle bounded externally by a stream, as shown in Figure E.1 and with uniform recharge $\underline{\epsilon}$. For simplicity, steady flow is assumed. The equation of continuity in polar coordinates (Davis and De Wiest, 1966, p.245) is

$$(T/r) \delta (r \delta h / \delta r) / \delta r + (T/r^2) \delta^2 h / \delta^2 \theta = -\epsilon$$
(E.1)

Since equation E.1 is a non homogeneous partial differential equation,

$$h = h_p + h_1 (r, \theta)$$
 (E.2)

where h_{p} is the particular integral and solution of

$$\nabla^2 h_p = -\epsilon \tag{E.3}$$

and h₁ is the complementary function and solution of

$$\nabla^2 h_1 = 0 \tag{E.4}$$

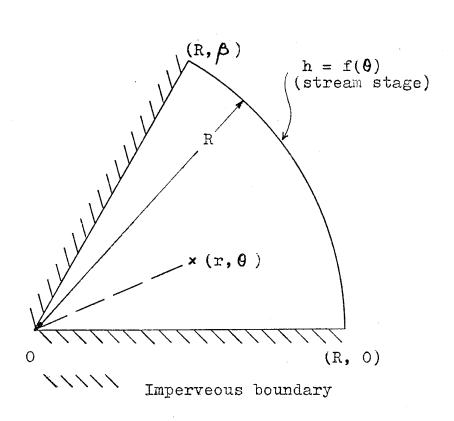


Fig. E.1 Boundaries of the aquifer.

Next the solution of (E.3) will be found. The boundary conditions are:

$$h = h_1 = f(\theta)$$
; $r = R$ (E.5)

$$h_{p} = 0$$
 ; $r = R$ (E.6)

and

$$dh_{p}/dr = 0$$
 ; $r = 0$ (E.7)

Thus h_p refers to the average outlet head and $f({\it g})$ is the departure from the average outlet head.

Integrating (E.3) twice and using (E.6) and (E.7) we find the solution of (E.3) which is

$$h_{p} = (R^{2} - r^{2}) \epsilon / 4T \qquad (E.8)$$

The solution of (E.4) will be found by using the method of separation of variables. With the boundary conditions

$$r = 0$$
; h_1 is finite

$$\theta = 0$$
 ; $\partial h_1/\partial \theta = 0$

$$\theta = \beta$$
 ; $\partial h_1/\partial \theta = 0$

we find that

$$h_1 = a_0/2 + \sum_{m=1}^{\infty} a_m \cos(m\pi\theta/\beta) r^{m\pi/\beta}$$
 (E.9)

Equation E.9 satisfies (E.5) if

$$f(\theta) = a_0/2 + \sum_{m=1}^{\infty} a_m \cos(m \pi \theta/\beta)$$
 (E.10)

Since the above equation is a Fourier series,

$$a_0 = 2/\beta \int_0^\beta f(\theta) d\theta = 0$$
 (E.11)

because $\overline{f}(0) = 0$, and

$$a_{m} = (2/\beta R^{m\pi/\beta}) \int_{0}^{\beta} f(\theta) \cos m \pi \theta/\beta d\theta \qquad (E.12)$$

Therefore

$$h_1 = \sum_{m=1}^{\infty} a_m \cos (m \pi \theta / \beta) r^{m \pi / \beta}$$
 (E.13)

is the solution of (E.4) with the proper boundary conditions. The outflow equation is

$$\epsilon = a(\overline{h} - \overline{H})$$

Let

$$\overline{h} = 1/A \int_{0}^{R} \int_{0}^{\beta} h(r, \theta) r dr d\theta$$
 (E.14)

or

$$\overline{h} = 1/A \int \int h_p r dr d\theta + 1/A \int \int h_1 r dr d\theta$$
 (E.15)

where $A = \beta R^2/2$. Then

$$\overline{h}_{p} = \epsilon / 4TR^{2} \int_{0}^{R} (R^{2} - r^{2}) dr^{2} = \epsilon R^{2} / 8T$$
 (E.16)

and

$$\overline{h}_1 = 1/A \int_0^R \int_0^\beta a_m r^{m \pi/\beta} \cos(m \pi \theta/\beta) r dr d\theta$$

But

$$\int_{\alpha}^{\beta} \cos(m \pi \theta / \beta) d\theta = 0$$

Then

$$\overline{h}_1 = 0$$

This shows that the use of average heads in the outflow equation is correct for any head distribution at the outlet. Since the average of the aquifer head perturbation produced by the departure at the boundary head from its average is zero, it follows that the average boundary head can be used in the outflow expression for \underline{H} .

APPENDIX F Analytical Solution of the Lumped Model

Let us transform equation 2.4 which represents the lumped model to

$$dh/dt + ah/S = y/S$$
 (F.1)

Solving the homogeneous equation, we find

$$h = h(t_0) \exp(-a(t - t_0)/S)$$
 (F.2)

which represents a decay curve from an initial condition $h(t_0)$. From (F.2) we have

$$h(t_0) = h \exp(a(t - t_0)/S)$$

Differentiating with respect to time,

$$d/dt (h exp(a(t-t_0)/S)) = 0 (F.3)$$

or

$$(dh/dt + ah/S) \exp(a(t - t_0)/S) = 0$$

where exp(at/S) is the integration factor. Multiplying both sides of (F.1) by the integration factor and making

use of (F.3), we obtain

$$d/dt (h \exp(at/S)) = y \exp(at/S)/S$$
 (F.4)

Integrating the above equation produces

$$h(t) = h(t_o) \exp(-a(t - t_o)/S)$$

$$+ 1/S \int_{t_o}^{t} y(\tau) \exp(-a(t - \tau)/S) d\tau \qquad (F.5)$$

Then if

$$t_0 = 0$$
 , $h = h_0$

we get

$$h(t) = h_0 \exp(-at/S) + 1/S \int_0^t y(\tau) \exp(-a(t-\tau)/S) d\tau$$
(F.6)

The above integral is called a convolution integral.

A somewhat different and perhaps more illustrative procedure for finding the solution of (2.4) or (F.1) is given next.

Let us represent the rate of recharge \underline{y} , as a Dirac delta function or impulse function (see Figure F.1) defined as

$$\delta(t - t_0) = \begin{cases} \infty & \text{when } t = t_0 \\ 0 & \text{when } t \neq t_0 \end{cases}$$

and

$$\int_{-\infty}^{\infty} (t - t_0) dt = 1$$

Using the above definition, y(t) is given by

$$y(t) = \int_{-\infty}^{\infty} (t - \tau) y(\tau) d\tau$$

Let us represent (F.1) by

$$S dh/dt + ah = y (F.7)$$

For a unit input in (F.7),

$$S dh/dt + ah = \delta (t - t_0)$$

At $t \neq t_0$

$$S dh/dt + ah = 0$$

whose solution is

$$h = c \exp(-at/S)$$
 (F.8)

When
$$t \cong t_o$$

$$\int_{t_0-\Delta/2}^{t_0+\Delta/2} (S dh/dt + ah - \delta(t - t_0)) dt = 0$$

where \(\Delta \) is a small time increment. Integrating gives

$$S(h(t_0^+) - h(t_0^-)) + a \int_{t_0^-}^{t_0^+} h(t) dt - 1 = 0$$

and if $\Delta \rightarrow 0$

$$h(t_0^+) = 1/S \tag{F.9}$$

Substituting (F.9) into (F.8), we get

$$h = (1/S) \exp(-a/S(t - t_0)) = \mu (t - t_0)$$
 (F.10)

a function called unit response or weighting function; $\mu(t-t_0)$ is the output of the system to a delta function input (Dooge, 1973, p.21).

If y(t) changes arbitrarily as shown in Figure F.2, we can follow the next analysis,

$$\Delta T_k = t_k - t_{k-1}$$

where τ_k is a point between t_k and t_{k-1} .

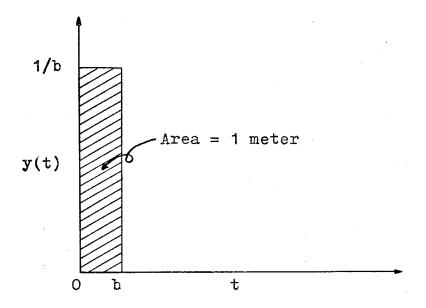


Fig. F.1 Dirac delta function representation of natural recharge \underline{y} .

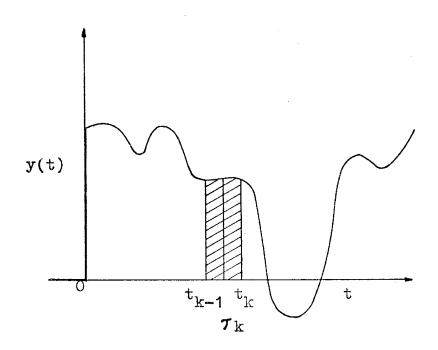


Fig. F.2 Representation of the natural recharge y

$$(y(T_k)\Delta T_k)\delta(t-t_k)$$

represents the shaded area in Figure F.2. The natural recharge is represented by

$$y(t) \cong \sum_{k=1}^{n} y(T_k) \delta(t - t_k) \Delta T_k$$

Since the response of the system to δ (t - au_k) is μ (t - au_k), we have

$$h(t) = 1/S \sum_{k=1}^{n} y(\tau_k) \mu(t - \tau_k)$$
 (F.11)

Substituting (F.10) into (F.11) and taking the limit when ΔT tends to zero, we obtain

$$h(t) = 1/S \int_{0}^{t} y(\tau) \exp(-a(t - \tau)/S) d\tau$$
 (F.12)

the convolution integral for a lumped model, which represents a time-invariant system.

Observe that the initial condition effect (see equation F.2) is

$$h_o(t) = h_o \exp(-at/S)$$
 (F.13)

Inasmuch as the system is linear, the superposition principle can be applied and equations F.12 and F.13 can be added together to produce the total output of the

system,

$$h(t) = h_o \exp(-at/S) + 1/S \int_0^t y(\tau) \exp(-a(t-\tau)/S) d\tau$$
(F.14)

APPENDIX G Discussion on the Probability Level of
Constraints Involving Random Quantities and
Constraints Related to the Expected Values

Consider the deterministic representation of the demand chance constraint to be

$$\mu_{D_i} + x \sigma_D \leq \mu_{Q_{SD_i}} + \mu_{Q_{P_i}} = \mu_{Q_{T_i}}$$
 (G.1)

where \underline{x} corresponds to a probability level of λ_1 . To get a lower bound for

$$P (D_i - Q_{T_i} \leq 0) \geq \lambda^*_1$$
 (G.2)

where λ_{1}^{*} is the actual probability associated with the constraint stated in terms of random quantities, assume that:

(1) $D_{i} - Q_{T_{i}}$ and D_{i} are normal random variables; (2) the correlation between Q_{T} and D is positive. Hence, $D_{i} - Q_{T_{i}}$ has mean $\mu_{D_{i}} - \mu_{Q_{T_{i}}}$ and variance

$$\sigma_{\mathrm{D}}^{2} + \sigma_{\mathrm{Q}_{\mathrm{T}}}^{2} - 2 \operatorname{P} \sigma_{\mathrm{D}} \sigma_{\mathrm{Q}_{\mathrm{T}}}, \text{ where}$$

$$\sigma_{\mathrm{D}}^{2} + \sigma_{\mathrm{Q}_{\mathrm{T}}}^{2} - 2 \operatorname{P} \sigma_{\mathrm{D}} \sigma_{\mathrm{Q}_{\mathrm{T}}} \leq \sigma_{\mathrm{D}}^{2} + \sigma_{\mathrm{Q}_{\mathrm{T}}}^{2} \tag{G.3}$$

if $\stackrel{\sim}{\sim}$ 0.

$$P(D_{i} - Q_{T_{i}} \leq 0) = P((D_{i} - Q_{T_{i}} - \mu_{D_{i}} - \mu_{Q_{T_{i}}})) / \sigma_{D - Q_{T}}$$

$$\leq (\mu_{Q_{T_{i}}} - \mu_{D_{i}}) / \sigma_{D - Q_{T}}) \qquad (G.4)$$

Now, if we satisfy (G.1), then

$$\mu_{Q_{T_i}} - \mu_{D_i} \ge x \sigma_{D} \tag{G.5}$$

and

$$P(X \leq a) \geq P(X \leq b)$$
 (G.6)

if a > b. Therefore, by using (G.4) and (G.5) in (G.6), we get

$$\begin{split} & \mathbb{P}((\mathbb{D}_{\mathbf{i}} - \mathbb{Q}_{\mathbb{T}_{\mathbf{i}}} - \boldsymbol{\mu}_{\mathbb{D}_{\mathbf{i}}} - \boldsymbol{\mu}_{\mathbb{Q}_{\mathbb{T}_{\mathbf{i}}}}))/\boldsymbol{\sigma}_{\mathbb{D} - \mathbb{Q}_{\mathbb{T}}} \leq \boldsymbol{\mu}_{\mathbb{D}_{\mathbf{i}}} - \boldsymbol{\mu}_{\mathbb{Q}_{\mathbb{T}_{\mathbf{i}}}})/\boldsymbol{\sigma}_{\mathbb{D} - \mathbb{Q}_{\mathbb{T}}}) \\ & \leq \mathbb{P}((\mathbb{D}_{\mathbf{i}} - \mathbb{Q}_{\mathbb{T}_{\mathbf{i}}} - \boldsymbol{\mu}_{\mathbb{D}_{\mathbf{i}}} - \boldsymbol{\mu}_{\mathbb{Q}_{\mathbb{T}_{\mathbf{i}}}}))/\boldsymbol{\sigma}_{\mathbb{D} - \mathbb{Q}_{\mathbb{T}}} \leq \times \boldsymbol{\sigma}_{\mathbb{D}}/\boldsymbol{\sigma}_{\mathbb{D} - \mathbb{Q}_{\mathbb{T}}}) \end{split}$$

or

$$P(D_{i} - Q_{T_{i}} \leq 0) \geq P((D_{i} - Q_{T_{i}} - \mu_{D_{i}} - \mu_{Q_{T_{i}}})) / \sigma_{D-Q_{T}}$$

$$\leq x \sigma_{D} / \sigma_{D-Q_{T}}) \qquad (G.7)$$

If
$$\sigma_D^2 = \sigma_{Q_m}^2$$
 and $f = 0$, we have

$$\sigma_{\rm D} / \sigma_{\rm D-Q_{\rm p}} = 1/\sqrt{2} = 0.707$$

where (G.7) is transformed into

$$P(D_i - Q_{T_i} \le 0) \ge P(N(0,1) \le 0.707 x)$$
 (G.8)

where N(0,1) is a normal random number with mean zero and variance one. Using (G.8) we can easily find the actual probability level, λ^*_1 .

For
$$\lambda_1 = 0.95$$
, then $P(D_i - Q_{T_i} \le 0) \ge 0.877 = \lambda_1^*$

and

$$\lambda_1 = 0.7$$
, then $P(D_i - Q_{T_i} \leq 0) \geq 0.644 = \lambda_1^*$

As we can note the difference between the probability levels is not very large; the above procedure can be used to estimate the actual probability level λ_1^* which is implicit in an assumed value of λ_1 .

APPENDIX H Input Data Used in the Comparative Study

N	Design horizon	4 years
N _S	Number of seasons per year	6
A	Aquifer area	8172.635 acres
T	Transmissivity	0.031 ft ² /S
S	Storage coefficient	0.01
ß	Dimensionless constant	3.0
L	Characteristic length	4900 ft
Z	Ground surface level	20 ft
H	Mean stream water level	20 ft
h _o	Initial water level	20 ft
$_{ m HL}$	Average initial lift	26.25 ft
$\mathbf{r}_{\mathbf{w}}$	Average well radius	1 ft
$\mathbb{A}_{\mathbf{W}}$	Average influence area of a well	$1.78 \times 10^8 \text{ ft}^2$
α_1	Fraction of developed water for	
	return to stream	0.8
α_2	Fraction of developed water for	
	spreading	0.5
$\mathcal{P}_{\mathbf{y}}$	Autocorrelation coefficient of	
. •	the inputs	0.7
$\mathcal{P}_{Q_{\mathbf{p}}\mathbf{h}}$	Cross correlation coefficient of	
P	pumping and head (from eq. 4.28)	-0.92
$\mu_{_{ m D}}$	Expected water demands per season	131 ac ft
o D	Standard deviation of water	•
-	demands per season	60 ac ft

r	Nominal rate of intere	est	5%
μ _{cs}	Expected stream divers	sion costs	\$3.4/acft
μ_{c}	Expected operating cos	st of	
£'	pumping		\$0.024/acft ²
$\mu_{c_{-}}$	Expected return to str	eam costs	\$0.105/acft
μ _{c_u} μ _{c_R}	Expected recharging co	osts	\$0.085/acft
$\mu_{_{\mathrm{Q}_{\mathrm{ST}}}}$	Expected available str	reamflow	
. 51	Season	$oldsymbol{\mathcal{U}}_{ ext{QST}}$ ac-ft/se	eason
	1, 7, 13, 19	193	
	2, 8, 14, 20	115	
	3, 9, 15, 21	. 89	
	4,10, 16, 22	. 96	
	5,11, 17, 23	165	

6,12, 18, 24

APPENDIX I Listing of the Computer Program

The Fortran IV program used in this work is composed of: (1) a control program which controls the number of iterations either by a mean square error test of the aquifer heads or a maximum number of iterations; (2) a Main 1 program which prepares data for linear programming; (3) a linear programming program (see, Kuester and Mize, 1973, p.10).

A phase overlay computer software technique in which Main 1 and Linear Programming share main computer core is used. This listing is for the particular case of Maddock's problem consisting of inputs, program listing, and outputs of the first iteration.

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 //SYSOO3 ACCESS SCRICH
IABBI SYSOO3 SCRICH
// EXEC COPY
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YSO03 423
YSYSO03 4C25S SCRIGH
YSYSO03 ACCESS SOSOPF
/SYSO03 ACCESS SOSOPF
/LABEL 80
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DO18
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SYSOO3 423
//PROG EXEC FURTRAN
                                                                                                                                                                                     COMMON/SIS/VS(50), vu(50), vv(50), vx(50), CRP
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                             0002
                             0003
                                                                                                                                                                                        COMMON/SIS/VS(50), vU(50)
COMMON/SUS/HI[50], H2[50]
UAIA
J=0
MA=3
N=24
NU=2
NI=10
NZ=8
KI=72
KZ=KI+1
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                               0005
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0014
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                GO TOP
  0007
  TUTAL MEMORY REQUIREMENTS 000A6C BYTES
COMPILER HIGHEST SEVERITY CODE WAS O
               //MAINI EXEC FORTRAN
                                                                 00:00:32
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  0002
  6000
  0004
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0010
0011
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DIMENSION VALUEZ(300)
DIMENSION CCHZ(50), QM(50), CS(50)
LUGICAL*1 SYMMISOU)
LUGICAL*1 SYMMISOU)
LUGICAL*1 SYMMI(300)
LUGICAL*1 SYMMI(300)
LUGICAL*1 LUGICAL*1/MENUS/*-*/
LUGICAL*1 LUGICAL*1, LUGICAL*1
LUGICAL EQ, NE, GI, GE, LT, LE
DATA
M=24
0012
0013
0014
0015
0016
0017
0018
                                                      C
0021
0022
0023
                                                                                  N=24
H1=10
N2=8
                                                              NZ=8

K1=72

K2=K1+1

K3=N1+N

LA=2

KFAE (LA,204) (AA(1),1=1,13)

204 FURMAT (IX,13A4)

RFAE (LA,205) (EB(1),1=1,2)

205 FURMAT (2A4)
0024
0025
0026
0027
 0028
0029
0030
0031
                                                             READ (LA,203) (EB(I),I=1,2)
FÜRMAI (2A4)
READ (LA,205) (CC(I),I=1,2),READ (LA,205) (LD(I),I=1,2),DDI)
READ (LA,205) (LD(I),I=1,2),DDI)
READ (LA,201) (IEC(I),I=1,I),FEI)
READ (LA,201) (IEC(I),I=1,I),FEI)
READ (LA,201) (LD(I),RNI(I),RN2(I),I=1,K2)
READ (LA,201) (CLMNI(I),CLMM2(I),RNM1(I),RNM2(I),I=1,K3)
READ (LA,201) (CLMNI(I),RM2(I),I=1,K1)
READ (LA,201) (AMI(I),RM2(I),I=1,K1)
READ (LA,201) (AMI(I),RM2(I),I=1,K1)
READ (LA,001) (C(K),K=1,N2)
DATA
AHI=1.73E3
CC QH=-0.92
HU=20.0
MD=131.0
R=0.05
R=1.0
0033
0033
0033
0035
0035
0033
0033
0041
0044
0044
 0045
0046
0047
0048
0049
                                                                                  RW=1.0
S=.01
SDD=60.0
SS=6.
T=0.031
  C050
0051
0052
                                                          0360
                                                       С
  0062
0063
   0064
 0066
CC67
0068
   0071
                                                        c
  0072
0073
0074
0074
0076
0077
0078
0079
0060
                                                        C
   0081
                                                        Ç
  0082
0083
0084
                                                        C.
   UU85
0086
0087
   8800
  0089
0089
0090
0091
0092
0093
0094
                                                                         ### CONTINUE

IF (0+(I)) 101.4.4

1 ### (1) - 04(I)

BO(I) - 05(I)

BO(I) - 05(I)

IF (E)(ESA(KA+I), *&*I) GO TO 3

SYMMIKA+I) = MMERK
GO TO 5

SYMMIKA+I) = MCTOS
GO TO 5

SYMMIKA+I) = COCCH(I, KA+I)

WATH CEFT AFTER CONSULTIVE USE CONSTRAINTS

DECISION VAR COCCH MAINING

DECISION VAR COCCH MAINING

FIRST 3 TEFM, ARE VOICE.
   0096
0097
0098
6099
6100
0101
0103
                                                                   101
                                                         c
   U106
                                                                                    FIPST 3 TERM, ARE VS(1)
SECOND 3 TERMS ARE VU[1)
FHIPD 2 TERMS ARE VP[1]
FOURTH 2 TERMS APE VR(1)
IF IT IS A MAX.CHANGE SIGN OF U.F. COEFFS.
```

```
DO 199 1=[,N

VALUE (1.4 (1-1.4 1) ==C1X(1)

VALUE (N1 (1-1.4 2) = B1(1)

VALUE (N1 (1-1.4 2) = B(1)

VALUE (N1 (1-1.4 2) ==C1(1)

VALUE (N1 (1-1.4 2) ==C1(1)

VALUE (N1 (1-1.4 2) ==C1(1)

VALUE (N1 (1-1.4 2) ==C3X(1)

VAL
0107
0108
0109
0110
01112
01113
01114
01115
01117
01119
01121
0122
0122
                                                                                                                                                                                            Ç
                                                                                                                                                                                                                                        DO 203 [=1,N

VALUEL([1]=83[1]

VALUEL([N+[]=84[1])

VALUEL([N+[]=84[1])

VALUEL([N+[]=84[1])

203 CONTINUE

SIREAN-AUNIFER INTERACTION

DO 2 <=1,N

QSA(K)=AL*AR*(WH(K)-H(K))

2 CONTINUE

MRITE (6,10)

10 FORMAT (1H ,10X,73(1H-))

MRITE (6,11) (A1,VARY)

11 FORMAT (1H ,12X,*'1',5X,*'QSD([]*,4X,*'QAU([]*,4X,*'OP([]*,9X,*'QAR([]*

1,6X,*'([]*,3X,*'Al=*,Ei3.6,2X,*'VARY=*,Ei3.6,2X,*'INITIAL GUESSES*)

WRITE (6,10)

WRITE (6,10)

WRITE (6,12) (J,QSD(J),QAU(J),QP(J),QAE(J),Y(J),J=[,N)

12 FORMAT (1H ,10X,13,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,1X,F10.3,
     0124
0125
0126
0127
                                                                                                                                                                                            c <sup>203</sup>
          ŎĨŽĖ
       0129
0130
0131
0132
          0133
0134
0135
                                                                                                                                                                                                                                   0138
       0139
J140
0141
0142
J143
       0144
0145
0146
0147
0148
0149
0150
       0151
0152
0153
0154
                                                                                                                                                                                                    C.
       0155
0156
0157
0158
0159
0160
0161
               0162
0163
0164
0165
            0184
               0186
0187
0183
                                                                                                                                                                                                                                             #RITE (6.39) (I,QSA(I),CCH2(I),RN(I),D[I),I=1,N)

39 FURMAT (IH ,IIX,I3,0X,EI3.5,6X,EI3.6,0X,EI3.6,0X,EI3.6)

RRITE (6,IO)
REWIND 2
LB=3

60 FORMAT (IX,I3A4)
WPITE (E0,61) (BU(I),I=1,2)
61 FORMAT (IX,I3A4)
WRITE (E3,62) (S/MSI(I),RGE(I),RN2(I),I=1,K2)
62 FORMAT (IX,A1,A4,A1)
WRITE (E3,62) (CU(I),I=1,2)
WRITE (E3,63) (CU(I),I=1,2)
PRINT (E3,63) (CUMP(I),CUMP(I),RNMI(I),RNM2(I),SYMB(I),
IVALUE (II,I-1,N)

63 FORMAT (IX,A4,A1,IX,A4,A1,FIL.4)
WRITE (E3,60) (RMI(I),RM2(I),VALUEI(I),I=1,K1)

64 FORMAT (IX,A4,A1,IX,A4,A1,I+II.4)
WRITE (E3,64) (RMI(I),RM2(I),VALUEI(I),I=1,K1)
WRITE (E3,44,A1,IX,I+I,4)
WRITE (E3,44,A1,IX,I+I,4)
WRITE (E3,204) (EE(II),I=1,I),EEI)
RETURN
END
                  0189
               0190
0191
0192
0193
0193
0193
0193
0193
                  0200
                    0201
                    0203
                    0205
0205
0206
```

```
INPUTY EXEC FORTRAN
```

```
00:00:53
```

```
0001
                                                                                                       SUBRUUTINE INPUTY (N.AR.AL)
                                                                        INPUT TO THE PHYSICAL MODEL
                                                                                                     VRIJ=STIREM STAGE
VRIJ=RT KECHARGE DEC VAR
WRIJ=RT KECHARGE
VRIJ=RT KECHARGE
VRIJE
VRIJ
             0002
            0003
0004
0005
0006
0007
             0008
0009
0011
0011
0013
0014
0015
0017
0018
0019
0022
0022
              0025
0026
0027
0028
0029
0030
0031
0032
              0034
0035
0036
0036
0037
0038
0039
                                                                          C
               0041
0042
0043
               0044
               TOTAL MEMORY REQUIREMENTS GOOTEC BYTES
COMPILER HIGHEST SEVERITY CODE WAS 0
                                                                                                                                                                                                                                                                                                                                                                                                                     00:01:00
//MEANH EXEC FURTRAN
                                                                                                        SUBRUUTINE MEANH (H.SH.N.AR.AL)
              0001
                                                                                                        AVERAGE MEAD DE TOP PHYSICAL MODEL
                                                                                                    Ç
              0002
               0003
                                                                                              DIMERSICA H(50), SH(50)
DATA
HU=23.0
S=.01
A=A1/S
9 X1=1.-EXP(X)
F18S1 H(A0) VALUE
4 H(1)=H(9EXP(X)+X1*Y(1)/A1
1F (H(1).0F.20.0) H(1)=20.
5 M(1)=H(1)*H(1)
SUGCESSIVE VALUES OF HEAD
6 DI 1 1-2.H
H(1)=H(1-1)*(X)*X1*Y(1)/A1
1F (H(1).LE.U.0) H(1)=0.0
                                                                          C
               0004
0005
0006
               0007
               8008
               0010
                                                                           Ĺ
               0011
0012
0013
0013
0015
                                                                                                         H(1)=H(1)+E:0.0) H(1)=0.0
IF (H(1)+E:0.0) H(1)=0.0
IF (H(1)-5t.20.0) H(1)=20.0
SH(1)=H(1)*H(1)
CONTINUÉ
RETURN
```

```
0018
                    END
```

0034

TOTAL MEMORY REQUIREMENTS 00035C BYTES CUMPILER HIGHEST SEVERITY CODE WAS 0 //VARH EXEC FURTRAN

```
00:01:04
```

PLUT0037

```
SUBROUTINE VARH (VAR.SD, VARY, N.AR, Al)
     0031
                                                     0002
      0003
      0004
     U-J

W=ABS(A-B)

CHECKING EXPONENT SIZE (EXP.LE.100)

Z=2.xe-A-B

Z1=100, $5/A1

IF (2.5e-Z1) Z=Z1

6 VAKJ=VARJ+VARY1*(CC**W)*EXP(-A1*Z/S)

3 CONTINUE

VAKK=VARK+VARJ

2 CONTINUE

VAK(1)=VARK

SD(1)=SURT(VAR(1))

1 CONTINUE

RETURN

END
                                       ζ
       0029
0030
0031
0033
0033
0035
0035
0037
0038
        TOTAL MEMORY REQUIREMENTS 000540 BYTES
COMPILER HIGHEST SEVERITY CODE WAS 0
                                                                                                                                                                                                                      00:01:10
//LP EXEC FORTRAN
                                                     SUBROUTINE LP
INTEGER RN41,RNM2,CLNM1,CINM2,RLNK,NEG,PUS,SYMB,CDID,RU,M4,F1,EU,
148N111001,184C11001,NAN1(1001,ANX(1001)
REAL X-M2,FP,CUMAE,X,VALU,FP11001,RC(1001),B(160,160),P1(160),
1NAP(1601,AP(1160),F1V-17,LST
C.ME-NYSIS/X,ST001,VUTSO1,VP1001,VR(50),CRP
INTEGER VSINUX,VUTNOX,VP1NOX,VR1NDX
INTEGER VSINUX,VUTNOX,VP1NOX,VR1NDX
INTEGER VSINUX,VUTNOX,VP1NOX,VR1NDX
LUGICAL*1 GUMCHR
LUGICAL*1 TITLE (40)
        0001
        0003
        0004
0005
0006
0007
0008
                                                                                                                                                                                                                                      PL010005
PL010005
PL010007
                                                        SET ALPHAMERIC CODES IN RO. MA, FI. EU. POS, NEG. BLNK FUR COMPARING WITH LP CARD CODES
                                                        KU=-640270212
        0009
                                                       RU=+640270272

#A=-725532608

F1=+959533384

E1=+975314592

POS=1346384032

REG=1614823488

BUNK=1077952576
        0019
0010
0012
0013
0014
                                       C INPUT PROS
                                                                                                                                                                                                                                       PE010012
PE010015
PE010014
                                                         INPUT PRUGRAM
        0016
0017
0018
0019
0020
0021
0022
0023
0024
0025
                                                       CONTINUE

M=0

N=1

ISM = 0

NHOWS = 0

NUE = 0
                                                                                                                                                                                                                                      PL010017
PL013010
PL013019
PL013021
PL013022
PL013022
PL013024
PL013025
PL013026
                                                         CLEAR MATRIX TO ZEKO
                                                                                                                                                                                                                                        PLUTUUZA
                                           00 12 1=1,160

00 12 J=1,160

12 811,JJ = 3,0

8EAD PROBLEM TIFLE

READ (2,400) TITLE

WAITE(6,8151)

WAITE(6,801) TITLE

WAITE(6,801)

8151 FORMATTIME)
        0027
0028
0029
                                                                                                                                                                                                                                       PLOTO332
        0030
0031
0032
0033
```

```
READ FIRST CARD. - SHOULD BE ROWLD

READ [2,2] CDID

FORMAT (A2)

IF (CDID-RO)13,680,3

RRITE[6,3333]

RRITE[6,3333]

ROWLD CARD MISSING *//)

C

READ AND STORE RUWID CARDS

FOR DOILDING GUMMY READ

FUR DOILCTIVE

GENERALE
0035
6036
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      PLOTOGS9
PLUT JO40
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     . PL010042
 0037
0038
0039
0040
0041
0042
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      PLOTO045
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      PEUTO04/
PEUTO043
PEUTO049
PEUTO050
                                                                                                                                        READ AND STORE RUWID CARDS
INCLUDING GUMMY READ
FUR JUDICTIVE WUM NAME
GENERATE PUS AND NEG SLACKS AS REQUIRED
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       PLUT0054
                                                                                  680 READ (2,681) DUMCHR
681 FORMAT (A1)

101 READ (2,102) CDID, LGE, RNM1, RNM2
HTE ( b,102 ) LDID, LGE, RNM1, RNM2
102 FREMAT(A2,9X,A1,1X,A4,A1)

504 CONTINUE
GD TO 104

103 M=M41
NRUMS = NRUWS+1
IF (LGE-POS)105,106,105
105 IF (LGE-POS)105,106,105
106 IB, L(M) = RNM1
IBN2(M) = RNM2
NLE = NLE+1
BP(M) = J.0
GD TO 101

108 ID, L(M) = RNM1
IBN2(M) = RNM2
NGE = NGE+1
BP(M) = -1.0
E(M,N) = -1.0
401 N9N1(N) = RNM1
NANA(N) = RNM2
NBP(N) = 0.0
N = N+1
UTO 101
101 IBN2(M) = RNM1
101 IBN2(M) = RNM1
NANA(N) = RNM1
NBP(M) = -2.0
READ AND STORE FIRST MAIKIX ELFMEN
                                                                                        680 READ (2,681) DUMCHR 681 FURMAT (A1)
  0043
0044
 0045
0046
0047
0048
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      PLUTUUGO PUUGO PLUTUUGO PUUGO PLUTUUGO PUUGO 
     0061
0062
0063
0064
0065
     0066
0067
0068
0069
0070
0071
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        PLUTOUS 3
PLUTOUS 5
PLUTOUS 7
PLUTOUS 7
PLUTOUS 8
PLUTOUS 8
                                                                                     READ AND STORE FIRST MATRIX ELEMENT

104 READ (2,195) CDID, CLNM1, CLNM2, RAM1, NAM2, SYM3, VALUE
WRITE ( 0,195) CDID, CLNM1, CLNM2, RAM1, RAM2, SYM3, VALUE
195 FORMAT (A2,50,44,A1,10,44,A1,41,41,41,41)
109 IF (NANTIN) CLNM1) III, 600, III
600 IF (NANZ) CLNM2) III, 600, III
601 CUNTINUE
112 PD 113 I=1, M
14 (IMAL(I)-RAM1) II3, 602, II3
602 IF (IMAL(I)-RAM2) II3, 603, II3
113 CUNTINUE
HAI IE (6,8113)
8113 FORMAT (//* INCORRECT INGREDIENT CARD *//)
8114 IF (SYM3-NEG) II0, II5, II6
115 PO II II7
116 PO II II7
117 PO II II7
118 PO AND STORE MATRIX STEMPATS
                                                                                                                      READ AND STORE FIRST MATRIX ELEMENT
      0075
0076
0077
0078
0079
0080
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      PE013093
PE010094
PE010095
PE013096
PE013093
       0080
0081
0082
0083
0084
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    PEUT3098
PEUT3099
PEUT3100
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  PLOTOTOS
PLOTOTOS
PLOTOTOS
PLOTOTOS
PLOTOTOS
PLOTOTOS
PLOTOTOS
PLOTOTOS
PLOTOTOS
         0086
        0088
         0092
         0093
                                                                                                                                  READ AND STORE MATRIX ELEMENTS
                                                                                                 117 READ (2.195) COID, CENMI, CENMI, RNMI, RNMI, SYMB, VALUE
                                                                                               6094
         0095
0096
0097
0098
0099
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              PLUTOLLA
PLUTOLLA
PLUTOLLA
PLUTOLLA
PLUTOLLA
PLUTOLLA
           0105
0101
0100
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                PEGTOLZO
PEGTOLZE
PEGTOLZO
PEGTOLZO
           0103
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                PLUTUIZA
PLUTUIZA
PLUTUIZA
PLUTUIZA
PLUTUIZA
PLUTUIZA
PLUTUIZA
PLUTUIZA
            Olai.
                                                                                                                              READ AND STORE RHS ELEMENTS
                                                                                         0108
0109
0110
0111
0112
0113
```

```
PLUT0153
                                                             BLANK OUT ARTIFICIAL NAMES
                                                                                                                                                                                                                                                                              PLOTOLOS
PLOTOLOS
PLOTOLOS
PLOTOLOS
PLOTOLOS
PLOTOLOS
PLOTOLOS
                                                DO 10 I=1.M

I+(HPII)+1.0)19.11.10

11 INNI(I) = 8LNK

IUNZII) = 8LNK

GU TO 10

19 RP(I) = -1.0

IBNI(I) = 8LNK

IBNZII) = 8LNK

IBNZII) = 8LNK

10 CONTINUE
0129
0130
0131
0132
0133
0134
0135
0136
                                                           ACCUMULATE COUNT OF INFEASIBILITIES
                                                           0= 7 NINF
M, I=1 CCC6 CU
C138
                                          IF(BP(I))6001.6000.6000
6331 NINF = 4INF+1
6600 CONTINUE
                                                                                                                                                                                                                                                                                PLUTUL64
PLUTUL73
0140
0141
0142
                                                              GENERATE INDICATORS FOR MINIMIZATION OF INFEASIBILITY
                                          DJ 6101 J=1,N

AP[[J] = J.0

DO 6101 I=1,M

IF(8P(I)) = 10,2,6101,6101

6102 API(J) = XPI(J)-B(I,J)

6101 LUNTINUE

DU 6002 I=1,M

6002 BP(I) = J.0

IPHASE = 1
0143
0144
0145
0146
0147
0148
0149
0150
                                      HAIN ROUTINE

9201 WRITE (619202)
9202 FORMAT (10 TERATION VAR IN
054325 CUNTINUE
C CALCULATE CONTE
                                                                                                                                                                          VAR OUT
                                                                                                                                                                                                                                QBJ FN',/)
                                               00 194 J=1.N
PI(J) = -N8P(J)
D() 194 [=1.4
194 PI(J) = PI(J) + BP(I)*B(I,J)
                                                              SELECT BEST NUNBASIS VECTOR
                                            9101 LST = -.0000001

KCOL = J

GO TO (751,552), IPHASE

751 IF(NIMF)54321,54321,552

552 CONTINUE

00 9102 J=1,N
 0160
0161
0162
0163
0164
                                                                IGNURE ARTIFICIAL VARIABLES
                                                              [F(NEN1(J)-BENK+NDN2(J)-BENK1651,9102,651
  01667
0168
0169
0171
0172
0173
0175
0177
0178
                                             651 CONTINUE
GO TO (0003-6004), IPHASE
6003 (FIXPI(3)-EST)6005-6006-6006
                                            6003 IF(x)[(3)-L$T]6005,6006,6006

6005 KCL=J

LST = XPI(J)

GU fO YIJZ

6004 CONTINUE

IF(PI(J)-L$T]9103,9102,9102

9103 KCUL = J

L$I = PI(J)

6006 CONTINUE

9102 CONTINUE

9102 CONTINUE

IF (KCUL)54321,54321,9104
                                          C
                                         C DETERMINE KEYROW

9104 KROW = 0
CJOAR = LST
LST = 1.0F20
DD 9107 I=1.M
TF (B(1.KCOH))9105.9105.9106

9100 MAILO = 301(178(1.KCOH)
9107 LST = RAITO
KROW=1
9105 COMMINUE
TEKROWSH
1912 ARTHE (0.9113) NOMITECOH).NAM2 (KCOH)
9113 FORMATI ' VARIABLE ', A4, A1, ' UNBCUNDED ')
GO 10 54323
    0180
0181
0182
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0184
0185
0186
                                                                  TRANSFURM
                                              TRANSFURM

DIVIDE BY PIVOT
PIVOT = B(KRCW, KCOL)
PO 91JJ J=1,N

9108 E(KPOH, J) = A(KPOH, J)/PIVOT
RQ(KK(M) = KO(KKCH)/PIVOT
DI) 91J/ [= 1, M

IF (I-KRUH)91[0,9109,9110

9110 AJ(1) = 20(1) - EQ(KROH)*B(I, KCOL)
DU 910/ J=1,N

FF (J-KCOL)7111,9109,9111

9111 E(I,J) = B(I,J) - B(KKOH,J)*B(I, KCOL)

9109 (UNITAGE
DU 930) I=1,M

9300 B(I, KC,L) = -B(I, KC, DL)/PIVOT
B(KKOH, KCOL) = 1.0/PIVOT
B(KKOH, KCOL) = 1.0/PIVOT
    0195
0196
0197
0198
0199
0200
0201
0202
      0204
0205
0206
                                                                    INTERCHANGE BASIS AND NUMBASIS VARIABLES
                                                               RNM1 = N3N1(KCUL)
RNM2 = NBN2(KCUL)
NBN1(KCUL) = IBN1(KKUW)
NBN2(KCUL) = IBN2(KKUW)
IBN1(KKUW) = KNM1
                                                                                                                                                                                                                                                                                    PLUI0264
                                                                                                                                                                                                                                                                                      PL-110208
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PLUT0269
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0221
                                                                  IRNZ[RRU#] = RNM2

LST = RBP(KCUL)

NBP(KCUL) = BP(KRUH)

BP(KRU#) = LST

IT = IT + 1

IF (NBM)(KCUL) = BLNK + NBNZ(KCUL) - BLNK + 0 201,6 200,6 201

NINE = NINE - 1
                                          200 VINE = NI
6201 CUNTINUE
C COM-
                                                                       COMPUTE UBJECTIVE FUNCTION
0223
                                                                    FN = 0.0
                                               FN = 0.0

9301 [=1, M]

9301 FN = FN + 0P(1) *RQ(1)
GO TD (737)7.7001), IPHASE

7000 SAVE = P[(KCDL)
DO 7003 J=1, N
PI(J) = PI(J) - SAVE*3(KROW, J)
XPI(J) = XPI(J) - CJBAK*3(KROW, J)

7003 CONTINUE
XPI(KCUL) = -SAVE/PIVOT
XPI(KCUL) = -CJBAR*/PIVOT
CONTINUE
DO 19302 J=1, N
0224
0226
0227
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0229
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0231
                                       0233
0234
0235
 0236
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0238
0239
 0240
0241
0242
0243
0244
0245
                                                  WRITE(5,9120) 17,10N1(KROW),18N2(KROW),NBN1(KCOL),NBN2(KCOL),FN
9120 FORMAT(1),TX,A4,A1,GX,A4,A1,GX,F13,G)
GU TU 9101
                                              C GU TU 9101

C 54321 CONTINUE

IF (IPHASE-1)8000,8000,54322

8000 IPHASE = 2

IF (NIN-1800),8003,8004

8004 MRI FE (6,3005)

8005 FORMAT(') SULUTION INFEASIBLE',/)

GU TU 54322

8003 CONTINUE

9302 FORMAT(') SULUTION FEASIBLE ',/)

GU TO 54325

54322 CONTINUE
 0249
0250
0251
0252
                                                                                                                                                                                                                                                                                                                             PLOTO313
PLOTO319
PLOTO320
                                                                                                                                                                                                                                                                                                                            PLOT0322
PLOT0323
PLOT0324
PLOT0325
PLOT0326
PLOT0327
                                                                         OUTPUT ROUTINE
                                                      WRITE(6,301) IT.FN
301 FORMAT(11, TIERATION*.15,* OBJ FN *.F15.3/)
WRITE (6,21) CEP
21 FORMAT (3X,*RANDUM PUMPING TERM*,3X,F10.3)
ZZ=1M+URP
WRITE to,22] ZZ
22 FORMAT (3X,*TOTAL OBJ FN*,6X,F10.3)
WRITE (6,302)
3G2 FORMAT (3X,*BASIS VAR*,1/X,*AMOUNT*,6X,*UNIT PROFIT*,6X,*UNIT OBJ FN*,6X,F10.3)
1.GX,*MIGH*,/)
DH 3933 I=1,M
 0261
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                                                                                                                                                                                                                                                                                                                             PEGT0324
   0263
0263
                                                                                                                                                                                                                                                                                                                             PLUIDI31
                                                                                                                                                                                                                                                                                                                             PENTO352
PENTO353
PENTO334
PENTO355
    0270
                                                                      CUST RANGING
                                               C VALUE = 1.0E20

LSY = 1.0E20

B) 12300 J=1a

IF (AMMI (JI-BLNK+NBN2(J)-BLNK)12305,12300,12305

12305 CPMITINUM

IF (IIII)/3(I,J)

IF (X-LST)12303,12300,12300

12302 X=PI(J)/3(I,J)

IF (X-LST)12303,12300,12300

12304 X=-PI(J)/3(I,J)

IF (X-VALUE)12304,12300,12300

12304 X=-PI(J)/3(I,J)

IF (X-VALUE)12304,12300,12300

12304 CONTINUME

LSI = BP(I) - LSI

VALUE = BP(I) + VALUE

3035 HKITC(G,303)18NI(I),18N2(I),RQII),BP(I),LSI,VALUE

304 FIDEMAI('X,A4,A1,/X,FI0.0,3X,FII.6,3X,FII.6)

MGIIC(G,305)

305 FORMAI('I VARIABLE REDUCED COST'//)

DI 309 J=1,N

IF (NOSI(J)-BLNK+NBN2(J)-BLNK)511,309,311

311 #KITC(G,310)DRNI(J),RBN2(J),PI(J)

309 CONTINUE

C SURT DECISION VARS AND EDRA AGE ADDANCE
   0211
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                                                                        VALUE = 1.0E20
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                                                                         SURT DECISION VARS AND FORM NEW ARRAYS
                                                 NP=NO.JF PERIODS
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PLUTU364
                                                                                                                RETURN TO READ NEXT PROBLEM
                                                                                                          RETURN
END
               TOTAL MEMORY REQUIREMENTS 010704 BYTES
COMPILER HIGHEST SEVERITY CODE WAS O
                                                                                                                                                                                                                                                                                                                                                                                                                            00:01:33
//INDX EXEC FURTRAN
                                                                                                         FUNCTION INDX (PARTI, PARTZ)
INTEGER PARTI, PARTZ, NAME(2), CVB
LOGICAL+1 INDNAM (B), EJ
LOGICAL+1 INDNAM (B), EJ
LOGICAL+1 INDNAM (B), EJ
LOGICAL+1 INDNAM (B), EJ
LOGICAL+1 INDNAM (B), ED
LOGICAL INDNAM (B
              0001
0002
0003
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                                                                              C
                 6009
                                                                              c
                 0010
0011
0012
                 TOTAL MEMORY REQUIREMENTS 030254 BYTES
COMPILER HIGHEST SEVERITY CODE MAS 0
COMPILER HIGHEST SEVERITY

// EXEC LNKEDT
LIST PHASE COMPH.ROOT
LIST AUTOLINK LOAD
LIST AUTOLINK 19COMJ
LIST AUTOLINK SQRT
LIST AUTOLINK SQRT
LIST AUTOLINK SQRT
LIST AUTOLINK FIGGSM
LIST INCLUDE MAINT.L
LIST INCLUDE MARH.L
LIST AUTOLINK EQ
LIST AUTOLINK FRAPR
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PHASE MAINI,*
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         76/029
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		•				ENTRY	USEKOPT	006588
76/029	PHASE	TRANSFER ADDR.	LUCORE	HICORE	BLOCK NO.	GSECT ENTRY ENTRY ENTRY ENTRY ENTRY ESU TYPE	EDAFIDES BUFURGH RCBURGH FIDCSH FIDCDH FIAd VARB LABEL	00F290 00E384 00E388 00E290 00E3F8 00E406 LUADED
			-			. ENTRY	VDIOCS#	60E98C
						CSECT ENTRY	#SAT I NU	00E420 00E420
	HAINL	B AA30U	BAASOU	0139AF	28	CSECT ENTRY	MAINIE MAINI	CALICO COEIAS
		•				CSECT ENTRY	IMPUTYE IMPUTY	012500 012500
						CS ECT ENTRY	MEANHS MEANH	012060 012060
						CS ECT ENTRY	VARHE VARH	013000
						CSECT # ENTRY # ENTRY # ENTRY # ENTRY # ENTRY	EQ GE GT LT NE	013-00 013-028 013-018 013-20 013-10 013-08
						CSECT ENTRY * ENTRY	BUASLUG ALUG ALUGIO	013558 013574 013660
						CSECT	EGAFRXPR FRAPR#	013768 013770
				•	•	CSECT	BUASEXP EXP	01.360 01.3864
	LP	OOEAA 8	OUEAA8	028660	57	C SEC T ENTRY	LPE LP	OOLAAB
				•		CSECT ENTRY	SXUNI XUX	028280 028280
						CS ECT .	CLC	028408
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				3 PHASES US	ED 216 8LNC	KS CSECT	C∨8	028508

LINKAGE EDITOR HIGHEST SEVERITY WAS 0

//SYSUUZ ACCESS SCRICH //SYSUUZ ACCESS SCRICH IABBI SYSOUZ SCRICH 190 SYSRES IABBI SYSOUZ SCRICH 190 SYSRES // EXEC CUMPH

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1	0.0	0.0	1،0،102	4.00	0.37355			
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ز	0.0	0.0	127.443	61.1.10	3.39395			
4	0.0	0.0	121.473	50.500	U. 37355			
5	0.0	0.0	121.493	11.563	0.39395			
6	0.0	0.0	127.493	90. 100	0.39395			
7	0.0	0.0	127.493	91.960	0.39395			
8	0.0	0.0	121.493	33.100	0.39395			
9	0.0	0.0	127.493	52.363	0.39395			
10	0.0	0.0	127.493	13.000	0.39395			
ii	0.0	0.0	127.493	70.703	0.39395			
11	0.0	0.0	121.493	109.900	0.39395			
13	0.0	0.0	121.443	42.400	0.39395			
14	0.0	0.0	127.493	51.400	0.39395			
15	ŭ.ŭ	ŭ.ŏ	127.493	61.600	3.39595			
16	0.0	0.0	127.493	45.500	0.39395			
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55	ŏ.ŏ	ő.ŏ	127.493	109.900	5.39395			
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20 21 22 23 24	ŏ.ŏ	0.0	127.493	93.100	0.39395			
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<u>.</u> I	HEAD MEAN	DRAM. CURR.	HEAD VAR.	PUMPING RANGOM	CRP= -472.673
1	19.653	23.394	0.130161f JU	0.1776811 02	•
Ž	19.620	22.032	0.1569731. 00	0.2125112 02	
3	19.619	22.516	0.1597561 30	0.21.091E 02	
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5	19.619	22.010	U. 16004/1. 00	りゃとほしゅうし ひと	
ģ	19.619	22.516	0.16 00000 00	U.ZJYOUIE C2	
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Ĕ	19.619	44.516	defeorable on	0.2061511 02	
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1345 115 119 11222234	19.619 19.619 19.619 19.619 19.619 19.619 19.619 19.619	22.516 22.516 22.516 22.516 22.516 22.516 22.516 22.516 22.516	9	160050E 00 160050E 00 160050E 00 160050E 00 160050E 00 160050E 00 160050E 00 160050E 00 160050E 00 160050E 00	0.19/173E 02 C.19/13dE 02 0.19/517E 02 0.19/517E 02 0.19/315E 02 0.13/754E 02 0.13/754E 02 0.18/0601E 02 0.18/060E 02 0.18/060E 02 0.18/060E 02 0.18/060E 02
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<u>-</u>		CONSTRAINTS 2=82	 3=03		
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		STREAM CONSTRAINT	<u> </u>		
	1=05	2=86	3=84		
123456789012345678901234	131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00 131.00	+104.80 -104.80 -104.30 -104.80	136.06 52.63 33.51 102.50 137.50 137.50 137.50 137.50 102.50 102.50 102.50 133.50 133.50 133.50 133.50 133.50 133.50		
		46160 6 10 1000			
	WATER LEFT	2=1.		3=1.	

1	QSA(1)	CC112(1)	PH(1)	0(1)
12345678901123456789012	0.56/36/8E U2 U.62/31/94E U2 U.62/4/97/E U2 U.62/4/97/E U2 U.62/4/97/E U2 U.62/4/97/E 02 U.62/4/97/E 02 U.62/4/97/E 02 U.62/4/97/E U2	0.70000E 00 0.49000E 00 0.49000E 00 0.240100E 00 0.240100E 00 0.164070E 00 0.17649E 01 0.576480E-01 0.40536E-01 0.40536E-01 0.197735E-01 0.197735E-01 0.197735E-02 0.342329E-02 0.323231E-02 0.12842E-02 0.12842E-02 0.7777923E-03 0.58547E-03	-0.235300E 01	0.800000E 01 0.107600E 03 0.107600E 03 0.107600E 03 0.143400E 03 0.453400E 03 0.413400E 03 0.113200E 03
23 24	0.624957E 02 0.624957E 02	0.273666E-03 0.191581E-03	-0.1553366 31 - 0.920030E 00	0.184200E 03

MADDUCK PRUBLEM

VSI PROFT- 441.7158
VSI DDI 131.0300
VSI DRI 131.0300
VSI DRI 131.0300
VUI PROFI- 10.7131
VUI DRI 104.3000
VUI CUI 1.0000
VVI CUI 1.0000
VVI PROFI- 1933.1011
VVI PROFI- 5.5215

MA

AKT	CUL	1.0000
755	007	438.7084
V 55	DH2	131.3000
VUZ	PRÜFT-	10.3223
ÝŬŽ	DKZ -	104.8300
VU2	CUZ	1.0000
VP2	PROFT-	1867.6575
VPZ	002	1606.1414
VK Z	PROFIT	2.4/27
งั่วรั	PRIET-	01.000
všš	มมัง	131.6303
ŸŠ3	DK3	131.0000
VŨ3	PRUFT-	10.7334
VU 3	D K3 −	104.8300
VU3	CUS	1.0000
VP 3	PRUP I-	1844.8347
VD 3	PROFT-	5-4104
VR 3	cu3	1.0000
VS4	PROF T~	430.0577
VŠ4	004	131.0000
VS4	DR4	131.0300
VU4	PROFT-	10.6447
VU%	DK 4	104.8330
VP2	PRINET-	1826 5056
VP4	Dije	1603.4148
VR4	PROFT-	5.3857
VR4	CU4	1.0000
V 5 5	PROFT-	427.2969
A 2 5	ນທຸລ	131.0000
A 2 3	リドラ りゅつモチー	121.55000
VIIS	025 -	104 3398
งันร์	čūš	1.0000
VP5	PROFT-	1814.3735
VP5	כסט	1603.4036
VR5	PROFT-	5.3412
VR 5	CU5	1.0000
V26	PROFT-	423.7555
A 2 D	006	131.0000
W116	PAGE 1-	131.0300
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APPENDIX J Basic Information on Rio Sinaloa Study Area

Population of the valley in

which the study area is

Area of the irrigated land:

Area of the aquifer:

Main aquifer:

located:

Irrigation cycles and average

consumptive use:

Main crops:

Climate:

Rainy season:

Average precipitation:

Monthly mean temperature:

Annual mean evaporation:

Topography of the study area:

150.000 inhabitants

460 Km²

1744 Km²

Quaternary alluvium

Spring (46.8 cm), summer

(77.7 cm) and winter (48 cm)

Cotton, wheat, bastard saffron,

sorghum, corn, soybean and

cantaloupe.

Semiarid

July to October and sometimes

is extended to January

450 mm.

29°C maximum and 17°C minimum

About 2300 mm

The area to the west of the

river slopes to the southwest

and descend from 45 m above

sea level to 20 m above sea

level. The area to the east of

the river slopes to the south-

Pumping figures:

west and descends from 65 m above sea level to sea level. East side of the river, 300 wells extracting 149x10⁶m³/yr (in 1971); west side of the river 240 wells extracting 50 x 10⁶ m³/yr

Well depth distribution:

About 68 wells with a depth greater than 50 m are located at the east side of the river; about 22 wells with a depth greater than 50 m are located at the west side of the river

Average aquifer transmissivity:

 $0.02 \text{ m}^2/\text{s}$

Average aquifer storage

coefficient:

0.01

201

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